

#### (An Autonomous Institution)

Managed by I.I.E.T Society, Approved by AICTE, New Delhi,
Affiliated to Anna University, Chennai,
Accredited by NAAC with 'A' grade and NBA for programs applied,
Recognized by UGC with 2(f) & 12(B) status















# M.E. EMBEDDED SYSTEM TECHNOLOGIES CURRICULUM AND SYLLABUS REGULATIONS 2024 CHOICE BASED CREDIT SYSTEM

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(An Autonomous Institution, Affiliated to Anna University, Chennai)

**Prof. K. R. Sundararajan**, a well-known educationalist, established the Indian Institute of Engineering Technology (I.I.E.T) society in the year 1947 in Chennai. The total area of 14 acres was purchased with enormous hardship and was donated to the IIET Society for the cause of education. The society's main objective is to provide quality education and it has been ensured since 1951.

#### The HET Society has the following to its credit:-

- An uninterrupted and continuous education since 1951 in its premises
- All Colleges run by the institution are ranked among the top 5 top 10 programs in Tamil Nadu
- 350 KW Solar Power Plant Generating upto 70% of its electricity needs
- Significant portion of the students are first generation learners
- Campus holds approximately 7000 plus students from the ages of 4 to 35 plus.
- Large Green Campus in the heart of the city of Chennai, Tamil Nadu
- In existence since 1947 Completed 75 years
- Targeting to be Carbon Neutral from the end of the year 2025

#### The society currently has the following institutions:-

- Meenakshi Sundararajan Engineering College(MSEC) established in 2001 & affiliated to Anna University offering engineering programs with about 2000 plus students.
- Meenakshi Sundararajan School of Management(MSSM) established in 2000 & affiliated to University of Madras offering MBA programs with about 100 plus students.
- The NEST School (TNS)- established in 2022 offering IB (International Baccalaureate) & CAIE (Cambridge) boards.

All of the institutions have earned an enviable name and are rated as one among Top 10 colleges in the Tamil Nadu state in their respective programs. Efforts are on to make the campus carbon neutral in 2 years (end of 2025) by using our community of staff and students.

Meenakshi Sundararajan Engineering College (MSEC) was established by the IIET Society in 2001. MSEC is defined by two keywords "Industry Ready" & "Vibrancy". Creating a new generation of self- actualized learners is our raison d'etre. If children are our future, then education is the key to their future. When education is shaped around them, and not the other way around, we are laying the foundation for a future/world where creativity, diversity and caring, independent-thinkers thrive. Our curricula thrive on continuous learning while interacting with and incorporating real-world situations and challenges.

#### MSEC's Hallmark of Quality

- Affiliated to Anna University, Chennai
- Approved by AICTE, New Delhi
- Accredited by NBA for programs in:
  - Civil Engineering
  - Computer Science and Engineering
  - Electronics and Communication Engineering
  - Mechanical Engineering
  - Electrical and Electronics Engineering
  - Information Technology
- Accredited by NAAC with a prestigious "A" grade
- Declared under Section 2(f) and 12(B) of the UGC Act
- Conferred with Autonomous status for 10 years (2024-25 to 2033-34) by the University Grants Commission (UGC) on February 1, 2024
- Meenakshi Sundararajan Innovation and Incubation Centre (MSIIC)
- Meenakshi Sundararajan Career Development Cell (MSCDC)
- MSEC Research Centre (MSEC RC)
- Center of Excellence Industry Tie Up in Specialized Labs
- Industry MOU's 200 Plus

#### Vision of the Institute

To impart state-of-the-art technical education, including sterling values and shining character, producing engineers who contribute to nation building thereby achieving our ultimate objective of sustained development of an unparalleled society, nation and world at large.

#### Mission of the Institute

Meenakshi Sundararajan Engineering college, Chennai constantly strives to be a Centre of Excellence with the singular aim of producing students of outstanding academic excellence and sterling character to benefit the society, our nation and the world at large.

To achieve this, the college ensures

- Continuous upgradation of its teaching faculty to ensure a high standard of quality education and to meet the ever-changing needs of the society
- Constant interaction with its stakeholders
- Linkage with other educational institutions and industries at the national and international level for mutual benefit
- Provision of research facilities and infrastructure in line with global trends
- Adequate opportunities and exposure to the students through suitable programs, to mould their character and to develop their personality with an emphasis on professional ethics and moral values.

#### We offer following courses:

S.No	Course	Intake						
	Undergraduate courses in B.E / B. Tech							
01	B.E Civil Engineering	60						
02	B.E Computer Science and Engineering	120						
03	03 B.E Electronics and Communication Engineering							
04	04 B.E Electrical & Electronics Engineering							
05	05 B.E Mechanical Engineering							
06	B. Tech Information Technology	120						
07	B. Tech Artificial Intelligence & Data Sciences	120						
	Postgraduate courses in M.E / M. Tech							
08	M.E. Construction Engineering and Management	18						
09								
10	M.E. Embedded System Technologies	18						
11								

#### **DEPARTMENT OF HUMANITIES AND SCIENCE**

The H&S Department stands out for its commitment to providing a well-rounded academic experience for first-year students. Covering key subjects like Physics, Chemistry, Mathematics, English, and Tamil. The department boasts a high pass percentage in semester exams, a testament to the hard work and dedication of the faculty. This year, the department enhanced offerings with industry and alumni talks, foreign language courses, engaging games, and specialized coaching for AEP and ICS. Additionally, the department introduced an industry-oriented and department-specific syllabus to better prepare students for future challenges and opportunities

#### DEPARTMENT OF CIVIL ENGINEERING

The Civil Engineering Department at our college, established in 2002, is a beacon of academic excellence and research innovation. Offering both undergraduate program and postgraduate program in M.E. Construction Engineering and Management, the department is committed to integrating advanced technologies and sustainable practices into its curriculum. The department boasts state-of-the-art laboratories and strong industry collaborations. Graduates of the department have made significant contributions to civil engineering, both nationally and internationally, and continue to shape the future of the discipline through unwavering commitment to excellence.

#### DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING

The Department of Computer Science and Engineering was established in 2001. It has its mission to inculcate innovative thinking and analytical abilities in addition to imparting quality education in the theory and application of Computer Science and Engineering. The department offers UG and PG programmes with State-of-the-art Computer laboratories equipped with high end hardware and software packages provided with high-speed leased line connectivity. The department takes pride in its academic excellence and outstanding placement records. It has consistently produced 68 university rank holders till 2023 batch and accredited by National Board of Accreditation.

# DEPARTMENT OF ELECTRONICS ENGINEERING

The Electrical and Electronics Engineering Department, established in 2003, is expanding its offerings to M.E. program in Embedded System Technologies from the 2024-25 academic year. With a focus on knowledge - based training, the department faculty empowers students with a deep understanding of concepts and industry - ready skills. The department forged partnerships with 22 companies through MOUs, facilitating collaboration and knowledge exchange.

The Electrical Technocrats Association (ETA) is a vibrant platform for technical activities, including the publication and showcasing of newsletters by staff and students every fortnight. Our mission is to drive technological advancements, foster research, and address industry needs.

#### **DEPARTMENT OF MECHANICAL ENGINEERING**

Meenakshi Sundararajan Engineering College inaugurated the Department of Mechanical Engineering in the academic year 2011-12. The department has well qualified faculties with excellent teaching, training and industrial experience. It has state-of-the-art laboratories which include VMC, CNC Wire Cut, Spark Erosion, 3D CMM etc catering to academic, consultancy and research requirements. The department's endeavor is to develop its students to be industry ready when they graduate. Students of mechanical engineering department gain industrial exposure and are prepared to face future challenges by carrying out their Final Year Project work in various PSU/Private sectors as per their field of interest relevant to their program. The department has a memorandum of understanding with various Institutions, Industries and Research organizations for collaborative research and development work. There is a huge potential in the department for Consultancy as well as Technology and Product incubation.

### DEPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING

The Department of Electronics and Communication Engineering, established in 2001, has grown significantly increasing its sanctioned intake from 60 to 120 in 2010. With NBA accreditation, the department is committed to delivering quality education, producing graduates who excel technically, socially, and professionally. Its state-of-the-art infrastructure, featuring ICT-enabled classrooms and advanced laboratories with cutting-edge tools like Cortex M4, Spartan 6, IoT kits, MATLAB, Cadence and PSPICE that supports academic excellence.

The Department's industry linkages with renowned organizations including ISRO, DRDO, NLTVC, and Ericson enhance students' technical skills through interactive events.

The Department's achievements include academic excellence, impressive placement records, and students' accomplishments in sports, arts, and culture, with alumni globally represented in top companies like Intel, Yahoo, and Apple.

#### **DEPARTMENT OF INFORMATION TECHNOLOGY**

The department of Information Technology was started in the year 2001 with an intake of 60 students focusing on the area. The department has won laurels to to the college. The department constantly strives with the singular aim of producing students with outstanding academic excellence and sterling character to benefit the society, our nation and the world at large. The department's commitment to high academic standards and successful student placements. It has consistently produced 65 university rank holders till 2023 batch and accredited by National Board of accreditation. Campus Agreement has been signed with leading software and hardware giants like Microsoft, IBM, Adobe and HP. The department has received a certificate partnership as a "Center of Excellence" with Virtusa Technology.

# DEPARTMENT OF ARTIFICIAL INTELLIGENCE AND DATA SCIENCE

The Department of Artificial Intelligence & Data Science was established in 2021 with an initial intake of 60 students, which was subsequently increased to 120 in 2024. Our department boasts a team of highly qualified, experienced, and competent faculty members and features spacious infrastructure with modern amenities, including six well-equipped computer laboratories with backup and internet facilities. We emphasize continuous knowledge enrichment through seminars, guest lectures, workshops, and skill enhancement programs for both students and faculty, and engage in meticulous academic planning to ensure a well-structured approach to each semester. Additionally, our student-driven club, serves as an incubation center, nurturing innovative ideas and fostering creativity.

#### INTERNAL QUALITY ASSURANCE CELL (IQAC)

MSEC established the Internal Quality Assurance Cell (IQAC) in 2016 to develop and implement quality standards and benchmarks in key performance areas. In alignment with the National Education Policy (NEP) 2020 and subsequent reforms, the IQAC has been further strengthened to ensure compliance with the new policy directives.

Through IQAC, the institute strive to:

- Maintain and enhance the quality of education and services
- Align with our institution's vision and mission
- Foster a culture of continuous improvement and excellence
- Ensure accountability and transparency in institutional functioning
- Promote innovative practices in teaching, learning, and research
- Develop and implement effective quality benchmarks and parameters
- Facilitate student-centered learning and feedback mechanisms
- Enhance faculty development and capacity building
- Strengthen industry-academia partnerships and collaborations
- Ensure efficient governance and administrative processes
- Promote a culture of sustainability and social responsibility
- Facilitate accreditation and ranking processes
- Identify and mitigate quality assurance risks

#### **CONTROLLER OF EXAMINATION**

The institution, granted autonomous status by UGC and Anna University from the academic year 2024-2025, has established the Controller of Examinations (COE) office to oversee assessment processes with confidentiality, ensuring quality and standards. The COE conducts fair examinations, declares results, and manages examination activities for Internal Assessment Tests (IATs) and Semester End Examinations (SEE). Their yearly schedule includes planning, coordinating, conducting, evaluating, and reviewing exams, as well as issuing certificates and transcripts. The COE ensures smooth conduct, maintains exam integrity, and coordinates with stakeholders, adapting to the institution's specific needs and exam cycle.

#### MEENAKSHI SUNDARARAJAN RESEARCH CENTRE(MSRC)

The MSEC Research Centre has a steadfast commitment to fostering a strong research culture. It empowers students and faculties in their intellectual exploration and discovery. The center aims to advance knowledge, drive neoteric innovation, and contribute to the broader academic and industrial fraternity ultimately aimed at uplifting humankind.

# THE MEENAKSHI SUNDARARAJAN CAREER DEVELOPMENT COMMITTEE (MSCDC)

The Meenakshi Sundararajan Career Development Committee (MSCDC) is a strategic group dedicated to fostering students' professional growth and development. Our mission is to support students in achieving their career goals, fostering a culture of professional growth and development.

The MSCDC plays a vital role in aligning individual career goals through various initiatives, including:

- 1. Career Pathways
- 2. Specialised Expert Talk & Guidnace on Different Career Pathways
- 3. Higher Education Awareness Sessions on various Geographical Locations
- 4. University Fairs
- 5. Training/Coaching Programs for different Competitive Exams
- 6. Repository / Text Books for various Competitive Exams

By providing a career pathway, we help students understand the opportunities available to them and what is required to achieve their career goals. We encourage students as they navigate their professional journey, providing them with the tools, knowledge, and opportunities needed for successful career development.

#### **OFFICE OF STUDENTS AFFAIRS**

Our mission is to create a supportive and inclusive educational environment that empowers students to succeed in their academic, personal, and professional lives. We achieve this by:

- Providing individualized support and responding to student needs
- Fostering a culture of academic integrity and excellence
- Promoting personal hygiene, cleanliness, discipline and sprucing
- Encouraging a moral code of conduct and respect for others
- Cultivating a sense of campus decency and decorum
- Modeling exemplary behavior and attitudes

By fulfilling these responsibilities, the institution aims to inspire students to become responsible, successful, and compassionate individuals who make a positive impact in their communities.

#### **COLLEGE COUNSELING SERVICES**

College counseling services are essential in supporting students' overall well-being and academic success. These services often encompass various areas, including healthy mind well-being, career guidance, and academic counseling. Here's a breakdown of the typical counseling services available for college students in the institution:

**Individual Counseling:** One-on-one sessions with RCI registered counselors or psychologists to address personal issues such as stress, anxiety, depression, relationship problems, and any other psychological concerns.

**Group Counseling:** Support groups where students with similar issues can share experiences and strategies for coping in a safe and supportive environment.

**Crisis Intervention:** Immediate support for students in distress, trauma response, and any emergency psychological concerns.

#### TRAINING AND PLACEMENT CELL

Meenakshi Sundararajan Engineering College training and placement cell is committed to providing exceptional placement opportunities for its students. The Placement Cell takes meticulous efforts to ensure that students are recruited by topnotch companies in the industry.

The training pathway is established starting from the first semester with 180 Hours of Placement training which includes Communications Skills, Aptitude Training. Specialised Programming, Guidance on Certifications, Projects, Competitions, Grooming, Etiquette, Group Discussion and Mock Interviews.

The Placement Cell functions under the leadership of Placement Officer, Faculty representatives and Coordinators from each department. The Cell's ultimate aim is to achieve 100% placement. Its Other Functions include

- 1. Implementation of the training pathway at appropriate semesters
- 2. Industry Talks
- 3. Alumni Talks
- 4. Arranging Internships & Projects
- 5. Centers of Excellence with Industry
- 6. Industry Specialised training & guidance

This comprehensive training empowers students to face the campus interviews with confidence through enhancing their employability skills for a successful future.

#### **DEPARTMENT OF PHYSICAL EDUCATION**

Our college campus boasts an array of sports facilities, including

- Basketball Court
- Badminton Court
- Pickle Ball Court
- Volleyball
- Cricket/Foot Ball/Athletics Ground
- Tennis Court
- Kho Kho

The institution is much dedicated in nurturing the talent through specific college sports teams:

- Expert coaching and mentorship
- Formation of new sports teams
- Dedicated Sports Hour (1 hour/week)
- Regular Sports Day events that are meticulously planned for maximum student participation.

#### **DEPARTMENT OF SAFETY AND SECURITY**

MSEC's Safety Department include the Chief Security Officer (Retd. Lt. Col), Trained & Certified Safety Officers (18) and Chief Safety Officer.

The department ensures a secure and hazard-free environment within the campus through:

- Monitoring all areas of the campus to ensure a secure environment
- Conducting daily reviews and maintaining a register to track and address any safety issues
- Performing maintenance tasks such as securing compound walls, replacing damaged fencing, and ensuring proper drainage
- Educating the community through regular safety awareness programs and training sessions
- Organizing fire drills and evacuation procedures to prepare for emergencies
- Identifying and mitigating potential hazards to prevent accidents
- Developing and implementing comprehensive safety policies to guide the community
- Continuously monitoring CCTV cameras to quickly respond to any security incidents

The department's proactive approach helps to prevent accidents, minimizes risks, and fosters a culture of safety among students, staff, and faculty members.

# MEENAKSHI SUNDARARAJAN INNOVATION AND INCUBATION CENTRE (MSIIC)

Meenakshi Sundararajan Innovation and Incubation Centre (MSIIC) is a dynamic and forward-thinking organization dedicated to fostering innovation, entrepreneurship, and skill development etc. Our center serves as a catalyst for a transformative change - providing aspiring entrepreneurs with the resources, mentorship, and support that is needed to turn their ideas into successful ventures. MSIIC is dedicated to promoting entrepreneurship and an innovative mindset among students and entrepreneurs at institutions. Through mentorship MSIIC helps to develop talents and support their initiatives, provide knowledge on market access and funding, and empower individuals to identify opportunities, take risks, and create positive change. The institution solely believes in entrepreneurship as a catalyst for innovation and societal impact, providing resources and a supportive environment for individuals to thrive and make a difference in their communities and beyond. Its activities include

- 1. Managing the 100 Seat Innovation & Incubation Center
- 2. Guidance to both Internal & External Start-ups from Ideation to Funding
- 3. Competitions Identification & Mentoring
- 4. Conducting Competitions :- 30 Hour Hackathons, All India Hackathons etc.
- 5. Managing Student Clubs
- 6. Art & Music Festival
- 7. Skill Development/Value Added Courses
- 8. Societal Beneficial Projects

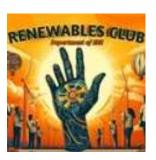
#### MSEC STUDENTS CLUBS

MSEC Students Clubs were initiated with the objective to provide a platform for students to discover, showcase and improve their interests, strengths and passion. There are 7 clubs in our college namely, AI Epoch Club, Eco Design Club, Adyant Coding Club, Renewables Club, Nodenova IOT Club, Dev Dynasty Web App Development Club and Product Development Club. Clubs foster vibrant student community in the campus by conducting variety of events and activities which include workshops, seminars, technical and non-technical events, campus benefit projects, long term projects such as SAE Baja etc that cater to diverse interests. Clubs help the students to collaborate with different disciplines and exchange knowledge with peer groups.

















	Vision of the department	Mission of the department						
To im comper Engine best su	<ul> <li>To provide quality education to students in the field of Electrical and Electronics Engineering.</li> <li>To inculcate innovative skills and improve research capabilities to bridge the gap between academia and industry.</li> <li>To develop social responsibility with moral and professional ethical values.</li> </ul>							
	PROGRAM OUTCOMES (PO) and PROGRAM SPECIFIC OUTCOMES (PSO)							
PO1	An ability to independently carry out resear to solve practical problems.	rch/investigation and development work						
PO2	An ability to write and present a substantia	I technical report/document.						
PO3	Students should be able to demonstrate a the specialization of the program. The mas the requirements in the appropriate bachel	stery should be at a level higher than						
PSO1	Versatile with modern tools, softwares and of energy utilities/system/better management	ent (technical and financial) of projects.						
PSO2	Proficiency to work autonomously and amount products and processes with environment development.	consciousness for sustainable						
PSO3	Development of competence and promotin amongst industry peers, business conglom and ethical manner.							



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Department: Electrical and Electronics Engineering, R2024, CBCS

M.E. Embedded System Technologies 2<sup>nd</sup>Board of Studies (BoS) Meeting

#### 17. M.E. Curriculum (Draft)

#### **SEMESTER I**

S. NO.	COURSE	COURSE TITLE	CATEGORY	ТСР		PERIOD PER WE		CREDITS
	CODE				L	Т	Р	
			THEORY					
1	P24MA104	Applied Mathematics for Embedded System Technologies	FC	60	3	1	0	4
2	P24RM101	Research Methodology and IPR	RMC	30	2	0	0	2
3	P24EM103	Design of Embedded Systems	PCC	45	3	0	0	3
4	P24EM104	Software for Embedded Systems	PCC	45	3	0	0	3
5	P24EM105	Microcontroller Based System Design	PCC	45	3	0	0	3
6	P24EM106	VLSI Design and Reconfigurable Architecture	PCC	45	3	0	0	3
7		Audit Course I <sup>#</sup> (Optional)	AC	30	2	0	0	0
			PRACTICAL					
8	P24EM107	Embedded System Laboratory – I	PCC	60	0	0	4	2
9	P24EM108	Embedded Programming Laboratory – I	PCC	60	0	0	4	2
		TOTAL		420	19	1	8	22

<sup>\*</sup>Audit Course is a Non-credit Course





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#### **SEMESTER II**

SL.	COURSE	COURSE TITLE	CATEGORY	ТСР		ERIOD R WE		CREDITS
NO.	CODE		5711 <b>23</b> 0111		L	Т	Р	JUNEDING
		Т	HEORY					
1	P24EM201	Real Time Operating System	PCC	45	3	0	0	3
2	P24EM202	Embedded System Networking	PCC	45	3	0	0	3
3	P24EM203	Embedded Control for Electric Drives	PCC	45	3	0	0	3
4	P24EM204	IoT for Smart Systems	PCC	45	3	0	0	3
5		Professional Elective I	PEC	45	3	0	0	3
6		Professional Elective II	PEC	45	3	0	0	3
7		Audit Course II#	AC	30	2	0	0	0
		PR	ACTICAL					
8	P24EM205	Embedded System Laboratory – II	PCC	60	0	0	4	2
9	P24EM206	Embedded Programming Laboratory – II	PCC	60	0	0	4	2
		TOTAL		420	20	0	8	22

<sup>\*</sup>Audit Course is a Non-credit Course





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#### SEMESTER III

SL.	COURSE	COURSE TITLE	CATEGORY	ТСР	PERIODS PER WEEK			CREDITS	
NO.	CODE	GGGRGE THEE	3711233111	. 0.	L	Т	Р		
	THEORY								
1		Professional Elective III	PEC	45	3	0	0	3	
2		Professional Elective IV	PEC	45	3	0	0	3	
3		Professional Elective V	PEC	45	3	0	0	3	
4		Open Elective	OEC	45	3	0	0	3	
		PR	ACTICAL						
5	P24EM301	Project Work I	EEC	180	0	0	12	6	
		TOTAL		360	12	0	12	18	





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#### **SEMESTER IV**

	COURSE		CATEGORY	ТСР		ERIOD ER WE	CREDITS	
NO.	CODE	GOORGE THEE	OATEOORT	ICF	L	Т	Р	OKEDITO
	PRACTICAL							
1	P24EM401	Project Work II	EEC	360	0	0	24	12
		TOTAL		360	0	0	24	12
	OVERALL TOTAL						74	





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# PROFESSIONAL ELECTIVES SEMESTER II ELECTIVES I & II

SI.	COURSE		CATEGORY	TOD		ERIOI R WE		CREDITS	
NO.	CODE	COURSE TITLE	CATEGORY	ТСР	L	T	Р	CREDITS	
	SEMESTER II - ELECTIVES I & II								
1	P24EM111	Wireless and Mobile Communication	PEC	45	3	0	0	3	
2	P24EM112	Virtual Instrumentation	PEC	45	3	0	0	3	
3	P24EM113	Embedded Processor Development	PEC	45	3	0	0	3	
4	P24EM114	Automotive Embedded System	PEC	45	3	0	0	3	
5	P24EM115	Intelligent Control and Automation	PEC	45	3	0	0	3	
6	P24EM116	Unmanned Aerial Vehicle	PEC	45	3	0	0	3	
7	P24EM117	DSP Based System Design	PEC	45	3	0	0	3	
8	P24EM118	Machine Learning and Deep Learning	PEC	45	3	0	0	3	

#### **SEMESTER III - ELECTIVES III, IV & V**

SI.	COURSE	COURSE TITLE CATEGORY TCP		ТСР	PERIODS PER WEEK			CREDITS
NO.	CODE				L	Т	Р	
1	P24EM119	Computer Vision	PEC	45	3	0	0	3
2	P24EM120	Multimedia Communication	PEC	45	3	0	0	3
3	P24EM121	Embedded Networking and Automation of Electrical System	PEC	45	3	0	0	3
4	P24EM122	Smart System Design	PEC	45	3	0	O .	RTME.
5	P24EM123	Embedded Computing	PEC	45	3/	ço l	PβR	OVED BY
6	P24EM124	Embedded Systems Security	PEC	45	3	0	9 P J	AN 2025
7	P24EM125	Robotics and Automation	PEC	45	3	0.5	ıGЫ	Roys



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8	P24EM126	Reconfigurable Processor and SoC Design	PEC	45	3	0	0	3
9	P24EM127	MEMS and NEMS Technology	PEC	45	3	0	0	3
10	P24EM128	Entrepreneurship and Embedded Product Development	PEC	45	3	0	0	3
11	P24EM129	Embedded System for Biomedical Applications	PEC	45	3	0	0	3
12	P24EM130	Renewable Energy and Grid Integration	PEC	45	3	0	0	3
13	P24EM131	Electric Vehicles and Power Management	PEC	60	3	1	0	4
14	P24EM132	Python Programming for Machine Learning	PEC	45	3	0	0	3
15	P24EM133	Smart Grid	PEC	45	3	0	0	3

#### **AUDIT COURSES**

SI.	COURSE	COURSE TITLE	CATEGORY	ТСР		ERIOI R WE	CREDITS	
NO.	CODE				L	Т	Р	
1	P24EMA01	English for Research Paper Writing	AC	30	2	0	0	0
2	P24EMA02	Disaster Management	AC	30	2	0	0	0
3	P24EMA03	Constitution of India	AC	30	2	0	0	0
4	P24EMA04	நற்றமிழ் இலக்கியம்	AC	30	2	0	0	0





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#### LIST OF OPEN ELECTIVES FOR PG PROGRAMMES

SI.	COURSE	COURSE TITLE	CATEGORY	ТСР		ERIOI R WE		CREDITS
NO.	CODE				L	Т	Р	
1	P24OT501	Sustainable Management	OEC	45	3	0	0	3
2	P24OT502	Micro and Small Business Management	OEC	45	3	0	0	3
3	P24OT503	Intellectual Property Rights	OEC	45	3	0	0	3
4	P24OT504	Ethical Management	OEC	45	3	0	0	3
5	P24OT505	Big Data Analytics	OEC	45	3	0	0	3
6	P24OT506	Internet of Things and Cloud	OEC	45	3	0	0	3
7	P24OT507	Medical Robotics	OEC	45	3	0	0	3
8	P24OT508	Embedded Automation	OEC	45	3	0	0	3
9	P24OT509	Environmental Sustainability	OEC	45	3	0	0	3
10	P24OT510	Textile Reinforced Composites	OEC	45	3	0	0	3
11	P24OT511	Nanocomposite Materials	OEC	45	3	0	0	3
12	P24OT512	IPR, Biosafety and Entrepreneurship	OEC	45	3	0	0	3
13	P24OC517	Security Practices	OEC	45	3	0	0	3
14	P24OC518	Cloud Computing Technologies	OEC	45	3	0	0	3
15	P24OC519	Design Thinking	OEC	45	3	0	0	3
16	P24OC520	Principles of Multimedia	OEC	45	3	0	0	3
17	P24OC521	Blockchain Technologies	OEC	45	3	0	PPR	OVED BY
18	P24OC522	Deep Learning	OEC	45	3	0	٩	AN 2025
19	P24OM523	Vibration and Noise Control Strategies	OEC	45	3 **	0/5	rGN	Royal

OF STUDIE



# Meenakshi Sundararajan Engineering College (An Autonomous Institution, Affiliated to Anna University, Chennai)

(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E.\_ Embedded System Technologies

I.E. Embedded System Technologie 2<sup>nd</sup>Board of Studies (BoS) Meeting

20	P24OM524	Energy Conservation and Management in Domestic Sectors	OEC	45	3	0	0	3
21	P24OM525	Additive Manufacturing	OEC	45	3	0	0	3
22	P24OM526	Electric Vehicle Technology	OEC	45	3	0	0	3
23	P24OM527	New Product Development	OEC	45	3	0	0	3
24	P24OC528	Integrated Water Resources Management	OEC	45	3	0	0	3
25	P24ON529	Water, Sanitation and Health	OEC	45	3	0	0	3
26	P24ON530	Principles of Sustainable Development	OEC	45	3	0	0	3
27	P24ON531	Environmental Impact Assessment	OEC	45	3	0	0	3





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2<sup>nd</sup>Board of Studies (BoS) Meeting

#### CATEGORY OF COURSES AND CREDIT DISTRIBUTION

S. No.	Subject Area	Cr	edits pe	Total Credits		
3. NO.	Subject Area	1	2	3	4	Total Credits
1	FC	4				4
2	PCC	16	16	0	0	32
3	PEC	0	6	9	0	15
4	RMC	2	0	0	0	2
5	OEC	0	0	3	0	3
6	EEC	0	0	6	12	18
7	Non-Credit / Audit Course	Υ	Y	0	0	0
	Total	22	22	18	12	74

FC - Foundation Courses

PCC - Professional Core Courses

PEC - Professional Elective Courses

**RMC** - Research Methodology Courses

**OEC** - Open Elective Courses

**EEC** - Employability Enhancement Courses

AC -Audit Courses / Non-Credit Courses





	W.L. Embedded System recimologies							
P24MA104	APPLIED MATHEMATICS FOR EMBEDDED SYSTEMS TECHNOLOGISTS	L	T	Р	С			
	TECHNOLOGISTS	3	1	0	4			
	Course Objectives							
1	To understand the techniques of Fourier transform to solve partial differential	equ	atior	ıs.				
2	To become familiar with graph theory for modelling the embedded system.							
3	o understand various optimization techniques for utilizing system and network resources.							
4	To understand the basic concepts of probability to apply in embedded technol	ogy	-					
5	To understand the basic concept of random variables and queuing theories to stochastic and dynamic environment in embedded technology.	ado	dres	s				
UNIT 1 FOUR EQUATIONS	IER TRANSFORM TECHNIQUES FOR PARTIAL DIFFERENTIAL		ç	)+3	1			
Convolution th	orm : Definitions - Properties – Transform of elementary functions - Dirac delta neorem – Parseval's identity – Solutions to partial differential equations : Heat e n - Laplace and Poison's equations.							
UNIT II GRAP	H THEORY		ç	)+3	;			
Shortest path	paths, trees, vector spaces - Matrix coloring and directed graphs - Some basic algorithms – Depth - First search on a graph – Isomorphism – Other Graph- Th Performance of graph theoretic algorithms – Graph theoretic computer language	neor		hm	s –			
UNIT III OPTII	MIZATION TECHNIQUES		ç	)+3	,			
	mming - Basic concepts – Graphical and simplex methods – Big M method - Tvod - Revised simplex method - Transportation problems – Assignment problems		has	е				
UNIT IV PRO	BABILITY AND RANDOM VARIABLES		Ş	)+3				
Probability fun	Axioms of probability – Conditional probability – Baye's theorem - Random varia action – Moments – Moment generating functions and their properties – Binomia Normal distributions – Two dimensional random variables - Poisson process.			son	,			
UNIT V QUEU	JEING THEORY		9	)+3	,			
	ıltiple servers - Markovian queuing models - Finite and infinite capacity queues – Queuing applications.	– F	inite	;				
	TOTAL PERIO	DS		60				





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	Course Outcomes					
At the	At the end of the course, the student will be able to					
CO1	Apply Fourier transform techniques to solve PDE technology.					
CO2	Model the networks in embedded systems using graph theory.					
СОЗ	Use the ideas of probability and random variables in solving engineering problems.					
CO4	Address stochastic and dynamic behaviour of data transfer using queuing theories in embedded systems technologies.					

#### **REFERENCES**

- 1. Taha H .A., " Operations Research: An Introduction " , 9th Edition, Pearson Education Asia, New Delhi, 2016.
- 2. Walpole R.E., Myer R.H., Myer S.L., and Ye, K., " Probability and Statistics for Engineers and Scientists ", 7th Edition, Pearson Education, Delhi, 2002.
- 3. Sankara Rao, K., "Introduction to Partial Differential Equations", Prentice Hall of India Pvt. Ltd., New Delhi, 1997.
- 4. NarasinghDeo, "Graph Theory with Applications to Engineering and Computer Science", Prentice Hall India, 1997.
- 5. S. S. Rao, "Engineering Optimization, Theory and Practice", 4th Edition, John Wiley and Sons, 2009.

		indicates the s	strength of corre			
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	2	2	1	3	2
CO2	3	2	2	2	3	2
СОЗ	3	2	2	2	3	3
CO4	3	2	2	1	3	3
CO5	3	2	2	3	3	3
AVG	3	2	2	1.8	3	2.6





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P24RM101	RESEARCH METHODOLOGY	AND IPR	L	Т	Р	С
			2	0	0	2
UNIT I RESEARCH DE	BIGN				6	
	process and design, Use of Secondary tative research, Observation studies, Expe			an	swer	the
UNIT II DATA COLLEC	TION AND SOURCES				6	
Measurements, Measu Preparing, Exploring, ex	ement Scales, Questionnaires and Instru amining and displaying.	ments, Sampling and	me	thod	s. Da	ata -
UNIT III DATA ANALYS	IS AND REPORTING				6	
	e analysis, Hypotheses testing and Measun reports and oral presentation	ures of Association. P	rese	enting	j Insi	ghts
UNIT IV INTELLECTUA	L PROPERTY RIGHTS				6	
UNIT V PATENTS	UNESCO in IPR maintenance.				6	
Types of patent appli	nd benefits of patent, Concept, features of cation, process E-filling, Examination of Licences, Licensing of related patents,	patent, Grant of pa	tent	, Re	voca	tion,
		TOTAL PERIO	DS		30	
REFERENCES						
1. Cooper Donald F Tata McGraw Hill Educa	, Schindler Pamela S and Sharma tion, 11e (2012).	JK, "Business Res	earc	ch N	/letho	ods",
Catherine J. H Secrets",Entrepreneur F	olland, "Intellectual property: Patents ress, 2007.	s, Trademarks, Co	opyri	ights	, T	rade
3. David Hunt, Long Ng	yen, Matthew Rodgers, "Patent searching	: tools & techniques", \	Wile	y,200	07.	
	ompany Secretaries of India, Statutory e Intellectual Property Rights, Law and pra			of pa	arlian	nent,





	W.E. Embedded System recimologies				
P24EM103	DESIGN OF EMBEDDED SYSTEMS	L	T	Р	C
		3	0	0	3
	Course Objectives				
1	To provide knowledge on the basics, building blocks of Embedded	Syste	em.		
2	To discuss Input/output Interfacing & Bus Communication with pro-	cesso	rs.		
3	To teach automation using scheduling algorithms and Real time op	eratir	ng sy	stem.	
4	To discuss on different Phases & Modeling of a new embedded pro	duct.			
5	To involve Discussions/ Practice/Exercise onto revising & familiarizacquired over the 5 Units of the subject for improved employability	_		ncept	S
UNIT 1 INTRODUC	CTION TO EMBEDDED SYSTEMS			9	
Embedded process replacement polici Development tool	nbedded Systems –built in features for embedded Target Archite sor – DMA- memory devices – Memory management methods-mer ries- Timer and Counting devices, Watchdog Timer, Real T s-IDE, assembler,compiler, linker, simulator, debugger, In circ ing- Overview of functional safety standards for embedded systems	nory r ime cuit e	mapp Clocl	ing, c k-Soft	ache tware
UNIT 2 EMBEDDE	D NETWORKING BY PROCESSORS			9	
mechanism - Se	rking: Introduction, I/O Device Ports & Buses- multiple interrupts a rial Bus communication protocols -RS232 standard–RS485–U N Bus –Wireless protocol based on Wifi , Bluetooth, Zigbee – In	SB-I	nter	İnteg	rated
UNIT 3 RTOS BAS	SED EMBEDDED SYSTEM DESIGN			9	
Multiprocessing communicationcon Interprocess Communication	sic concepts of RTOS- Need, Task, process & threads, interrup and Multitasking, Preemptive and non-preemptive text switching, interrupt latency and deadline shared memory, munication – synchronization between processes-semaphores, Ma nheritance, comparison of Real time Operating systems: VxWorks,	sche mes ailbox	duling sage (, pipe	g, pass es, pr	Task sing-, riority
UNIT 4 MODELLIN	NG WITH HARDWARE/SOFTWARE DESIGN APPROACHES			9	
with UML, UML Specification and &MultiProcessor A	ed systems- embedded software development approachOvervie Diagrams– Hardware/Software Partitioning , Co Design Appr I modeling- CoSynthesis- features comparing Single-proce rchitecturesdesign approach on parallelism in uniprocessors & Mu	oach essor	es fo Aro	or Sy chited	/stem
UNIT 5 EMBEDDI	ED SYSTEM APPLICATION DEVELOPMENT			9	
Application Devel	ifferent Phases & Modelling of the EDLC.choice of Target Archited opment-for Control Dominated-Data Dominated Systems-Case Cruise control in a Car, Mobile Phone software for key inputs.				



45

**TOTAL PERIODS** 



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	Course Outcomes
At the	end of the course, the student will be able to
CO1	Demonstrate the functionalities of processor internal blocks, with their requirement.
CO2	Analyze that Bus standards are chosen based on interface overheads without sacrificing processor performance.
соз	Explain the role and features of RT operating system, that makes multitask execution possible by processors.
CO4	Illustrate that using multiple CPU based on either hardcore or softcore helps data overhead management with processing- speed reduction for uC execution.
CO5	Recommend Embedded consumer product design based on phases of product development.

#### **REFERENCES**

- 1. Rajkamal, 'Embedded system-Architecture, Programming, Design', TMH,2011.
- 2. Peckol, "Embedded system Design", John Wiley & Sons, 2010
- 3. Lyla B Das," Embedded Systems-An Integrated Approach", Pearson 2013
- 4. EliciaWhite,"Making Embedded Systems",O'Reilly Series,SPD,2011
- 5. Bruce Powel Douglass,"Real-Time UML Workshop for Embedded Systems, Elsevier, 2011
- 6. Advanced Computer architecture, By Rajiv Chopra, S Chand, 2010
- 7. Jorgen Staunstrup, Wayne Wolf ,Hardware / Software Co- Design Principles and Practice, Springer, 2009.
- 8. Shibu.K.V, "Introduction to Embedded Systems", TataMcgraw Hill,2009
- 9. Tammy Noergaard, "Embedded System Architecture, A comprehensive Guide for Engineers and Programmers", Elsevier, 2006
- 10. Giovanni De Micheli, MariagiovannaSami , Hardware / Software Co- Design, Kluwer Academic Publishers , 2002

			strength of corre		ng 2-Medium, 1- c Outcomes PS	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	-	3	2	1	-
CO2	2	-	1	2	-	-
CO3	-	2	2	3	-	-
CO4	2	-	3	3	DEPAR	MEN
CO5	2	-	1	2	APPROV	ED BY
AVG	2	2	2	2.4	8/14	2025 2



		L	Т	Р	С				
P24EM104	SOFTWARE FOR EMBEDDED SYSTEMS	3	0	0	3				
	Course Objectives								
1	To expose the students to the fundamentals of embedded Program	ming.							
2	o Introduce the GNU C Programming Tool Chain in Linux.								
3	To study the basic concepts of embedded C.								
4	To teach the basics of Python Programming.								
5	To involve Discussions/ Practice/Exercise onto revising & familiarizi over the 5 Units of the subject for improved employability skills.	ng the	con	cepts	acquired				
UNIT 1 BAS	SIC C PROGRAMMING			9	•				
	rogram Development Environment - Introduction to C Programm in C - Data Types and Operators - C Program Control - C Functions								
UNIT 2 EME	BEDDED C			,	•				
Examples. M	cture to 'C' Code: Object oriented programming with C, Header to leeting Real-time constraints: Creating hardware delays - Need timeouts - Creating hardware timeouts.								
UNIT 3 C PI	ROGRAMMING TOOL-CHAIN IN LINUX			,	•				
	sor - Stages of Compilation - Introduction to GCC - Debugging with are and Build System - GNU Binary utilities - Profiling - using gpro								
UNIT 4 PYT	HON PROGRAMMING			,	9				
	- Parts of Python Programming Language - Control Flow Statemenaries - Tuples and Sets.	ents -	Func	tions	- Strings-				
UNIT 5 MOI	DULES, PACKAGES AND LIBRARIES IN PYTHON			,	9				
Python - Libr	ules and Packages - Creating Modules and Packages - Practica ary for Mathematical functionalities and Tools - Numerical Plotting								
Python - Ima	ging Libraries for Python - Networking Libraries.								





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	Course Outcomes						
At the	At the end of the course, the student will be able to						
CO1	Demonstrate C programming and its salient features for embedded systems.						
CO2	Deliver insight into various programming languages/software compatible to embedded process development with improved design & programming skills.						
CO3	Develop knowledge on C programming in Linux environment.						
CO4	Possess ability to write python programming for Embedded applications.						
CO5	Have improved Employability and entrepreneurship capacity due to knowledge upgradation on recent trends in embedded programming skills.						

#### **REFERENCES**

- 1.Paul Deitel and Harvey Deitel, "C How to Program", 8th Edition, Pearson Education Limited, 2016.
- 2. Michael J Pont, "Embedded C", Addison-Wesley, An imprint of Pearson Education, 2002.
- 3. William von Hagen, "The Definitive Guide to GCC", 2nd Edition, Apress Inc., 2006.
- 4. Gowrishankar S and Veena A, "Introduction to Python Programming", CRC Press, Taylor & Francis Group, 2019.
- 5. Noel Kalicharan, "Learn to Program with C", Apress Inc., 2015.
- 6. Steve Oualline, "Practical C programming", O'Reilly Media, 1997.
- 7. Fabrizio Romano, "Learn Python Programming", Second Edition, Packt Publishing, 2018.
- 8. John Paul Mueller, "Beginning Programming with Python for Dummies", 2nd Edition, John Wiley & Sons Inc., 2018.
- 9. Mark Lutz, "Programming Python", 4th Edition, O'Reilly Media Inc., 2010.

		1 indicates the ogram Outcon	strength of co		rong 2-Mediur	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	-	2	-	3	-
CO2	1	-	1	-	2	-
CO3	-	2	-	-	2	-
CO4	1	-	1	1	1	-
CO5	-	-	2	2	3	2
AVG	1	2	1.5	1.5	2.2	2





	MICHOCONTROLLER RECORD SYSTEM STORY	L	Т	Р	С
P24EM105	MICROCONTROLLER BASED SYSTEM DESIGN	3	0	0	3
	Course Objectives				
1	To teach the architecture of PIC Microcontroller and RISC processor.				
2	To compare the architecture and programming of 8,16,32 bit RISC process	sor.			
3	To teach the implementation of DSP in ARM processor.				
4	To discuss on memory management, application development in RISC pro	cess	or.		
5	To involve discussions/ Practice/Exercise onto revising & familiarizing the acquired over the 5 Units of the subject for improved employability skills.	conc	epts		
UNIT 1 PIC N	MICROCONTROLLER			9	
	<ul> <li>memory organization – addressing modes – instruction set – PIC</li> <li>I/O port, Data Conversion, RAM &amp; ROM Allocation, Timer programming</li> </ul>				
UNIT 2 ARM	ARCHITECTURE			9	
A   14				3	
	<ul> <li>memory organization – addressing modes –The ARM Programmer's merrupts – Coprocessors – Interrupt Structure.</li> </ul>	node	I -Re		ers-
Pipeline - Inte		node	I -Re		ers-
Pipeline - Inte	errupts – Coprocessors – Interrupt Structure.	ory -		egiste	
Pipeline - Inte UNIT 3 PERI PIC: ADC, DA I/O Ports – SI	errupts – Coprocessors – Interrupt Structure.  PHERALS OF PIC AND ARM MICROCONTROLLER  AC and Sensor Interfacing –Flash and EEPROM memories. ARM: I/O Mem	ory -		egiste	
Pipeline - Inte UNIT 3 PERII PIC: ADC, DA I/O Ports - SI UNIT 4 ARM ARM general	PHERALS OF PIC AND ARM MICROCONTROLLER  AC and Sensor Interfacing –Flash and EEPROM memories. ARM: I/O Memories – UART - Serial Communication with PC – ADC/DAC Interfacing MICROCONTROLLER PROGRAMMING  Instruction set – Thumb instruction set –Introduction to DSP on ARM -	ory ng.	-EE	9 PRO	M -
Pipeline - Intel UNIT 3 PERII PIC: ADC, DA I/O Ports - SI UNIT 4 ARM ARM general example of Fi	PHERALS OF PIC AND ARM MICROCONTROLLER  AC and Sensor Interfacing –Flash and EEPROM memories. ARM: I/O Memories – UART - Serial Communication with PC – ADC/DAC Interfacing MICROCONTROLLER PROGRAMMING  Instruction set – Thumb instruction set –Introduction to DSP on ARM -	ory ng.	-EE	9 PRO	M -
Pipeline - Intel UNIT 3 PERII PIC: ADC, DA I/O Ports - SI UNIT 4 ARM ARM general example of Fi UNIT 5 DESI PIC impleme Controlling D	PHERALS OF PIC AND ARM MICROCONTROLLER  AC and Sensor Interfacing –Flash and EEPROM memories. ARM: I/O Mem RAM –Timer –UART - Serial Communication with PC – ADC/DAC Interfacin  MICROCONTROLLER PROGRAMMING  Instruction set – Thumb instruction set –Introduction to DSP on ARM - Iters.	nory ng. - Im Moto	plemor Con S	9 PRO 9 nenta	M -





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	Course Outcomes							
At the	At the end of the course, the student will be able to							
CO1	Understand the basics and requirement of processor functional blocks.							
CO2	Observe the specialty of RISC processor Architecture.							
CO3	Incorporate I/O hardware interface of a processor-based automation for consumer application with peripherals.							
CO4	Incorporate I/O software interface of a processor with peripherals.							
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in commercial embedded processors .							

#### **REFERENCES**

- 1. Steve Furber, 'ARM system on chip architecture', Addision Wesley, 2010.
- 2. Andrew N. Sloss, Dominic Symes, Chris Wright, John Rayfield 'ARM System Developer's Guide Designing and Optimizing System Software', Elsevier 2007.
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- 4. John lovine, 'PIC Microcontroller Project Book', McGraw Hill 2000.
- 5. William Hohl, 'ARMAssembly Language' Fundamentals and Techniques, 2009
- 6. Rajkamal, Microcontrollers Architecture, Programming, Interfacing, & System Design', Pearson, 2012.
- 7. ARM Architecture Reference Manual, LPC213x User Manual.
- 8. www.Nuvoton .com/websites on Advanced ARM Cortex Processors.

	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'								
	PO1	PO1 PO2 PO3 PSO1 PSO2 PSO3							
CO1	-	-	2	-	-	-			
CO2	1	-	3	2	-	-			
CO3	-	- 1 3 1 -							
CO4	1	-	-	1	2	-			
CO5	-	- 2							
AVG	1	-	2	2	1.5	-			





P24EM106	VLSI DESIGN AND RECONFIGURABLE ARCHITECTURE	L	T	Р	С					
		3	0	0	3					
	Course Objectives									
1	To expose the students to the fundamentals of sequential system design, synchronous and Asynchronous circuits.									
2	To understand the basic concepts of CMOS and to introduce the IC fabrication methods .									
3	To introduce the Reconfigurable Processor technologies, To provide an insi architecture significance of SOC.	ght	and	ł						
4	To introduce the basics of Analog VLSI design and its importance.									
5	To learn about the programming of Programmable device using Hardware c Language.	lesc	cript	ion						
UNIT 1 INTRO	DUCTION TO ADVANCED DIGITAL SYSTEM DESIGN			9						
Sequential Circ	ocked Synchronous Sequential Network(CSSN), Design of CSSN, Design of cuits (ASC), Designing Vending Machine Controller, Races in ASC, Stationtial Hazards, Designing Hazard free circuits.									
UNIT 2 CMOS	BASICS & IC FABRICATION			9						
based combina	MOSFET Scaling - MOS Transistor Model-Determination of pull up / pull down ational logic & sequential design- Dynamic CMOS –Transmission Gates- CMOS IC Fabrications - Stick Diagrams, Design Rules and Layout.									
UNIT 3ASIC A	ND RECONFIGURABLE PROCESSOR AND SoC DESIGN			9						
Architecture -F	ASIC, ASIC design flow- programmable ASICs- Introduction to reconfigura Reconfigurable Computing, SoC Overview, recent trends in Reconfigura gurable processor based DC motor control.									
UNIT 4 ANALOG VLSI DESIGN										
	analog VLSI- Design of CMOS 2stage-3 stage Op-Amp –High Speed and r MOS- Analog primitive cells- Introduction to FPAA.	Hig	h fr	eque	ncy					
UNIT 5 HDL P	ROGRAMMING			9						
	igital design with VHDL, structural, data flow and behavioural modeling clation-Design examples, Ripple carry Adders, Carry Look ahead adders, I, Test Bench.									
	TOTAL PERIO	DS		45						





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	Course Outcomes							
At the e	At the end of the course, the student will be able to							
CO1	Incorporate synchronous and asynchronous switching logics, with clocked circuits design.							
CO2	Deliver insight into developing CMOS design techniques and IC fabrication methods.							
CO3	Explain the need of reconfigurable computing, hardware-software co design and operation of SoCproc							
CO4	Design and development of reprogrammable analog devices and its usage for Embedded applications.							
CO5	Illustrate and develop HDL computational processes with improved design strategies.							

#### **REFERENCES**

- 1. Donald G. Givone, "Digital principles and Design", Tata McGraw Hill 2002.
- 2. Charles H. Roth Jr., "Fundamentals of Logic design", Thomson Learning, 2004.
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- 4. Joao Cardoso, Michael Hübner, "Reconfigurable Computing: From FPGAs to Hardware/Software Codesign" Springer, 2011.
- 5. Pierre-Emmanuel Gaillardon, Reconfigurable Logic: Architecture, Tools, and Applications, 1st Edition, CRC Press, 2015
- 6. Mohamed Ismail ,TerriFiez, "Analog VLSI Signal and information Processing", McGraw Hill International Editions,1994.
- 7. William J. Dally / Curtis Harting / Tor M. Aamodt," Digital Design Using VHDL:A Systems Approach, Cambridge Univerity Press,2015.
- 8. ZainalatsedinNavabi, 'VHDL Analysis and Modelling of Digital Systems', 2n Edition, Tata McGraw Hill, 1998.

	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'								
	PO1	PO1 PO2 PO3 PSO1 PSO2 PSO3							
CO1	-	-	-	1	-	-			
CO2	2	-	2	2	-	-			
CO3	-	-	3	3	2	1			
CO4	2	-	2	3	1 -				
CO5	-	1	1	3	3 1				
AVG	2	1	2	2.4	(3) DODO	WENZ			



D0451445	EMPERRED OVOTEM LABORATORY	L	Т	Р	С								
P24EM107	EMBEDDED SYSTEM LABORATORY – I	Ī	0	0	4	2							
	Course Objectives												
1	To involve the students to Practice on Workbench /Software Tools/ Hardware Processor Boards with the supporting Peripherals.												
2	To teach the concepts of algorithm development & program processors with peripheral interfaces.	nming or	n softwa	re tools	and Dig	jital							
3	To encourage students to practice in open source software	/ packa	ges /too	ls.									
4	To train though hands-on practices in commercial and licer	nsed Ha	rdware-s	oftware	suites.								
5	Practicing through the subdivisions covered within experim students into the revising the concepts acquired from theorem.			v to expo	ose the								
DOMAIN		EQUIPMENT/ SUPPORTS REQUIRED											
1	Programming with 8 bit Microcontrollers # Assembly programming.	8051/ other 8 bit Microcontrollers with peripherals; IDE, Board Support Software Tools / Compiler/others.											
2	Programming with 8 bit Microcontrollers # C	8051 Microcontrollers with peripherals; IDE,Board Support Software Tools /C Compiler/others.											
3	I/O Programming with 8 bit Microcontrollers I/O Interfacing : Serial port programming/ LCD/ Sensor Interfacing/PW/M Constition/ Meter Control	8051 Microcontrollers with peripherals; Board Support Software Tools, peripherals with interface.											
4	1. Assembly.	PIC Microcontrollers with peripherals; ;IDE, Board Support Software Tools /C Compiler/others											
5	I/O Programming with PIC Microcontrollers I/O Interfacing : PWM Generation/ Motor Control/ADC/DAC/LICD/Sensor Interfacing	PIC Microcontrollers with peripherals; Board Support Software Tools, peripherals with interface.											
			то	TAL PE	RIODS	TOTAL PERIODS : 60							





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	Course Outcomes						
Experiment insight into various embedded processors of CISC and RISC architecture / computational processors with peripheral interface.							
CO2	Understand the fundamental concepts of how process can be controlled with uC.						
CO3	Experimenting on programming logic of Processor based on software suites(simulators, emulators)						
CO4	Incorporate I/O software interface of a processor with peripherals.						
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in interfacing and use of commercial embedded processors						

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- 1.Mohamammad Ali Mazidi&Mazidi 8051 Microcontroller and Embedded Systems', Pearson Education
- 2. Mohammad Ali Mazidi, RolindMckinley and Danny Causey, 'PIC Microcontroller and Embedded Systems' Pearson Education
- 3. Simon Monk," Make Action-with Arduino and Raspberry Pi,SPD ,2016.
- 4. Wesley J.Chun,"Core Python Applications Programming, 3rd ed, Pearson, 2016
- 5. Kraig Mitzner, 'Complete PCB Design using ORCAD Capture and Layout', Elsevier
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# CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'

	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	2	1	2	1	-	-			
CO2	-	-	1	1	2	1			
CO3	2	3	1	2	3	TME			
CO4	2	-	2	1	(C) 20000	THE WAY			
CO5	-	-	1	1 /	3	2 P			
AVG	2	2	1.4	1.2	2.5	.5			



DO 4EM400	EMPERED RECORAMINAL ARCRATORY I	L	Т	Р	С					
P24EM108	EMBEDDED PROGRAMMING LABORATORY – I	0	0	4	2					
	Course Objectives		•	1	-					
1	Boards with the supporting Peripherals.									
2	To teach the concepts of algorithm development & programming on software tools and Digital processors with peripheral interfaces.									
3	To encourage students to practice in open source so	oftware / pa	ackages /to	ols.						
4	To train though hands-on practices in commercial ar	d licensed	Hardware-	-software s	uites					
5	Practicing through the subdivisions covered within exstudents into the revising the concepts acquired from			w to expos	se the					
DOMAIN	EXPERIMENT DETAILS	EQUIPME	ENT/ SUPP	ORTS RE	QUIRED					
1	Programming in Higher Level Languages/Open Source Platforms		va/Embedd npilers &Pla							
2	Programming with Arduino Microcontroller Board	Arduino Boards with peripherals ;IDE, Board Support Software Tools /Compiler/others								
3	HDL Programming in FPGA processors	Processo Tools & Ir	r Boards wi nterfaces	th Board S	Support					
4	Programming & Simulation in Simulators /Tools/others	Simulatio	n Tools as l	Proteus/ O	RCAD					
5	Programming & Simulation in Simulators /Tools/others	Simulatio	n Tools as I	MATLAB /d	others					
			T	OTAL PER	RIODS : 60					
	Course Outcomes									
At the end	of the course, the student will be able to									
CO1	Developing Optimized code for embedded processor	r.								
CO2	Understanding the fundamental concepts of how pro Modules.	cess can l	oe realized	using Soft	ware					
CO3	Circuit and System level simulators to develop soluti	on for emb	edded bas	ed applicat	tions.					
CO4	Incorporate I/O software interface of a processor with	n periphera	als.							
CO5	Improved Employability and entrepreneurship capac Embedded computing and algorithm development w				on on					





	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'								
	PO1 PO2 PO3 PSO1 PSO2 PSO3								
CO1	2	1	1	2	2	1			
CO2	2	-	2	-	3	2			
CO3	2	1	3	1 2 2					
CO4	2	1	2	2	2	-			
CO5	-	-	2	-	3	1			
AVG	2	1	2	1.6	2.4	1.5			





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P24EM201	REAL TIME OPERATING SYSTEM	L	Т	Р	С			
		3	0	0	3			
	Course Objectives							
1	To expose the students to the fundamentals of interaction of OS with a computation.	comp	uter a	nd Us	er			
2	trolle	d with	OS.					
To study on programming logic of modeling Process based on range of OS features								
To compare types and Functionalities in commercial OS, application development using RTOS								
5	To involve Discussions/ Practice/Exercise onto revising & familiarizing the over the 5 Units of the subject for improved employability skills	ne coi	ncept	s acqı	uired			
UNIT 1 REV	IEW OF OPERATING SYSTEMS			9				
Implementati	oles - Operating System structures – System Calls – Files – Processes – I ion of processes – Communication between processes – Introduction to E abedded operating systems	_			ting			
UNIT II OVE	RVIEW OF RTOS			9				
	and Task state –Multithreaded Preemptive scheduler- Process Synchroniz il boxes -pipes – Critical section – Semaphores – Classical synchronizatio							
UNIT III REA	LTIME MODELS AND LANGUAGES			9				
	<ul> <li>Process Based and Graph based Models – Real Time Languages – R'</li> <li>Interrupt processing – Synchronization – Control Blocks – Memory Requi</li> </ul>			s – RT	•			
UNIT IV REA	ALTIME KERNEL			9				
	Design issues – Polled Loop Systems – RTOS Porting to a Target – Compus RTOS like – VX works – Linux supportive RTOS – C Executive.	pariso	on an	d Bas	ic			
UNIT V APP	LICATION DEVELOPMENT			9				
Discussions Application –	on Basics of Linux supportive RTOS – uCOS-C Executive for developmenter.	nt of I	RTOS	3				
	TOTAL	- HR		45				
	Course Outcomes							
At the end o	of the course, the student will be able to							
CO1	Outline Operating System structures and types.							
CO2	Insight into scheduling, disciplining of various processes execution.							
CO3	Illustrate knowledge on various RTOS support modelling							
CO4	Demonstrate commercial RTOS Suite features to work on real time proc	esse	s des	ign.				
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on							



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	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'										
	PO1 PO2 PO3 PSO1 PSO2 PSO										
CO1	2	-	1	-	2	-					
CO2	-	-	2	-	3	1					
CO3	2	-	2	1	2	2					
CO4	2	2	3	2	1	3					
CO5	-	-	1	-	3	1					
AVG	2	2	1.8	1.5	2.2	1.75					





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		. 1	Т	Р	С			
P24EM202	EMBEDDED SYSTEM NETWORKING	L 3	0	0	3			
	Course Objectives	<u> </u>	U	U				
1	To expose the students to the fundamentals of wired embedded netw	orkir	g ted	hniqu	ies.			
2 To introduce the concepts of embedded ethernet.								
To expose the students to the fundamentals of wireless embedded networking.								
4	To discuss the fundamental building blocks of digital instrumentation.							
5	To introduce design of Programmable measurement & control of elec	trical	Dev	ice.				
UNIT 1 EMBEDDE	ED PROCESS COMMUNICATION WITH INSTRUMENT BUS			9				
	king: Introduction – Cluster of instruments in System: Introduction to be protocols – RS 232C, RS 422, RS 485 and USB standards – embedos and CAN bus.							
UNIT II EMBEDDE	ED ETHERNET			9				
and network speed	work – Inside Ethernet – Building a Network : Hardware options – Cab d – Ethernet controllers – Inside the internet protocol – Exchanging me for Embedded systems using FTP – Keeping devices and network sec	essa						
UNIT III WIRELES	SS EMBEDDED NETWORKING			9				
synchronization -	etworks – Introduction – Node architecture – Network topology -Locali Energy efficient MAC protocols – SMAC – Energy efficient and robust 'SN Applications - Home Control - Building Automation - Industrial Aut	routi	ng –					
UNIT IV BUILDING	G SYSTEM AUTOMATION			9				
- Data acquisition for automation and	haracteristics: Sensing Voltage, Current, flux, Torque, Position, Proxir system- Signal conditioning circuit design- Uc Based & PC based data protection of electrical appliances –processor based digital controller motors, Relays –System automation with multi-channel Instrumentat	a acq s for	uisiti swite	on – ching	JC			
UNIT V COMMUN	ICATION FOR LARGE ELECTRICAL SYSTEM AUTOMATION			9				
principles - outage	Monitoring, Communication, Event Processing, and Polling Principles, e management— Decision support application - substation automation, , Performance measure and response time, SCADA Data Models, nee	exte	nded	cont				
	TOTAL	HR		45				
	Course Outcomes							
At the end of the	course, the student will be able to							
CO1	Analyze the different bus communication protocols used for embedde	d ne	twork	king				
CO2	Explain the basic concepts of embedded networking	40	TAL					
and Separtification								
CO3	Apply the embedded networking concepts in wireless networks	parties and the latest and	-	WIT	11/1			
CO3		PRO	VED	BY				



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- 3. Jan Axelson 'Embedded Ethernet and Internet Complete', Penram publications
- 4. Krzysztof Iniewski,"Smart Grid ,Infrastructure & Networking",TMcGH,2012
- 5. Control and automation of electrical power distribution systems, James Northcote-Green, Robert Wilson, CRC, Taylor and Francis, 2006

	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Program Outcomes (POs) and Program Specific Outcomes PSOs'									
	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	1	2	-	-	3	1				
CO2	-	2	-	-	2	1				
CO3	3	2	2	3	2	3				
CO4	2	-	3	3	-	2				
CO5	3	-	3	3	-	2				
AVG	2.2	2	2.6	3	2.3	1.8				





P24EM203	EMBEDDED CONTROL FOR ELECTRIC DRIVES	, T	T	Р	C					
	Course Objectives	3	0	0	3					
1	To provide the control concept for electrical drives .									
2	2 To emphasis the need for embedded system for controlling the electrical drives									
3	To provide knowledge about various embedded system based control strategy for electrical drives									
4	To Impart the knowledge of optimization and machine learning techniques used for electrical drives									
5	To familiarize the high performance computing for electrical drives									
UNIT 1 INTROD	UCTION ELECTRICAL DRIVES			9						
Dynamics of mot	d its classifications, Four-quadrant drive, Dependence of load torque on va tor-load combination-Solid State Controlled Drives-Machine learning and o ectrical drives- loT for Electrical drives applications.									
UNIT II OVERVI	EW OF EMBEDDED PROCESSOR			9						
Embedded Proce processors.	essor architecture-RTOS – Hardware/software co-design-Programming wi	th S	οС							
UNIT III INDUCT	TION MOTOR CONTROL			9						
	ontrol methods-PWM techniques- VSI fed three-phase induction motor- Furthree phase induction motor-FPGA based three phase induction motor co			Bas	ed					
UNIT IV BLDC N	MOTOR CONTROL			9						
	OC Motor -Speed control methods -PWM techniques- ARM processor base BLDC Motor control and operation	ed B	DLC	mote	or					
UNIT V SRM MC	OTOR CONTROL			9						
	M Motor -Speed control methods -PWM techniques- FPGA based SRM moontrol and operation.	otor	cont	rol- [	NN					
	TOTAL	HR		45						
	Course Outcomes									
At the end of th	e course, the student will be able to									
CO1	Interpret the significance of embedded control of electrical drives									
CO2	Deliver insight into various control strategy for electrical drives.									
CO3	Developing knowledge on Machine learning and optimization techniques control.	for r	noto	r						
CO4	Develop embedded system solution for real time application such as Elec UAVs.	ctric	vehi	cles	and					
	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded system skills required for motor control strategy.									



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- 3. K. Venkataratnam, Special Electrical Machines, Universities Press, 2014.
- 4. Steve Furber, 'ARM system on chip architecture', Addision Wesley, 2010.
- 5. Ron Sass and AnderewG.Schmidt, "Embedded System design with platform FPGAs: Principles and Practices", Elsevier, 2010.
- 6. Steve Kilts, "Advanced FPGA Design: Architecture, Implementation, and Optimization" Willey, 2007

	(3/2	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)									
	PO1	PO2	PO3	PO4	PO5	PO6					
CO1	1	_	2	-	2	_					
CO2	1	1	3	-	-	2					
CO3	2	-	-	-	3	-					
CO4	1	2	3	1	-	-					
CO5	-	-	-	-	3	-					
AVG	1.2	1.5	2.6	1	2.6	2					





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DO 451400 4		L	Т	Р	С					
P24EM204	IOT FOR SMART SYSTEMS		0	0	3					
	Course Objectives	3								
1	To study about Internet of Things technologies and its role in real	time a	applic	ations.						
2	To introduce the infrastructure required for IoT									
3	To familiarize the accessories and communication techniques for	loT.								
4	To provide insight about the embedded processor and sensors re	quire								
5	To familiarize the different platforms and Attributes for IoT									
UNIT I INTRODU	CTION TO INTERNET OF THINGS			9						
	are and software requirements for IOT, Sensor and actuators, Tech Typical IoT applications, Trends and implications.	nnolog	gy dri	vers,						
UNIT II IOT ARCH	HITECTURE			9						
	del and architecture -Node Structure - Sensing, Processing, Commologies, Layer/Stack architecture, IoT standards, Cloud computing ergy beacons.									
UNIT III PROTOC PROTOCOLS	COLS AND WIRELESS TECHNOLOGIES FOR IOT			9						
			∟ ၊ ∟,	GPRS	,					
	ogies for IoT: WiFi (IEEE 802.11), Bluetooth/Bluetooth Smart, Zig 5.4), 6LoWPAN, Proprietary systems-Recent trends.	gBee/Z								
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO	5.4), 6LoWPAN, Proprietary systems-Recent trends.		ZigBe	e Smaı	rt,					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut	5.4), 6LoWPAN, Proprietary systems-Recent trends.	urity, I	ZigBe Maint	e Smaı 9 ainabili	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce	tes: Big-Data Analytics for IOT, Dependability,Interoperability, Securessors for IOT :Introduction to Python programming -Building IOT	urity, I	ZigBe Maint	e Smaı 9 ainabili	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor	tes: Big-Data Analytics for IOT, Dependability,Interoperability, Securessors for IOT :Introduction to Python programming -Building IOT	urity, l with F	ZigBe Maint RASF	e Smar 9 ainabili PERRY 9	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor	(5.4), 6LoWPAN, Proprietary systems-Recent trends.  CESSORS  tes: Big-Data Analytics for IOT, Dependability, Interoperability, Securessors for IOT: Introduction to Python programming -Building IOT  CUDIES  me Automation, smart cities, Smart Grid, connected vehicles, elections.	urity, I with F	ZigBe Maint RASF	e Smar 9 ainabili PERRY 9	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor	tes: Big-Data Analytics for IOT, Dependability,Interoperability, Sectessors for IOT:Introduction to Python programming -Building IOT  TUDIES  The Automation, smart cities, Smart Grid, connected vehicles, electiculture, Productivity Applications, IOT Defense	urity, I with F	ZigBe Maint RASF	e Smai 9 ainabili PERRY 9 chargin	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor Environment, Agri	(5.4), 6LoWPAN, Proprietary systems-Recent trends.  (CESSORS)  (Les: Big-Data Analytics for IOT, Dependability, Interoperability, Sectors for IOT: Introduction to Python programming -Building IOT  (UDIES)  (The Automation, Smart cities, Smart Grid, connected vehicles, electriculture, Productivity Applications, IOT Defense  (TOTAL)	urity, I with F	ZigBe Maint RASF	e Smai 9 ainabili PERRY 9 chargin	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor Environment, Agri	(CESSORS)  tes: Big-Data Analytics for IOT, Dependability, Interoperability, Sectors for IOT: Introduction to Python programming -Building IOT  TUDIES  The Automation, smart cities, Smart Grid, connected vehicles, electriculture, Productivity Applications, IOT Defense  TOTAL  Course Outcomes	urity, I with F	ZigBe Maint RASF	e Smai 9 ainabili PERRY 9 chargin	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor Environment, Agri	(CESSORS)  tes: Big-Data Analytics for IOT, Dependability, Interoperability, Sectors for IOT: Introduction to Python programming -Building IOT  TUDIES  me Automation, smart cities, Smart Grid, connected vehicles, electriculture, Productivity Applications, IOT Defense  TOTAL  Course Outcomes	urity, I with F ric vel	ZigBe Maint RASF	e Smai 9 ainabili PERRY 9 chargin	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor Environment, Agri  At the end of the CO1	CESSORS  tes: Big-Data Analytics for IOT, Dependability, Interoperability, Sectessors for IOT: Introduction to Python programming -Building IOT  TUDIES  me Automation, smart cities, Smart Grid, connected vehicles, electriculture, Productivity Applications, IOT Defense  TOTAL  Course Outcomes  course, the student will be able to  Analyze the concepts of IoT and its present developments.	urity, I with F ric vel	ZigBe Maint RASF nicle	e Smai 9 ainabili PERRY 9 chargin	ty.					
Wireless technol UWB (IEEE 802.1 UNIT IV IOT PRO Services/Attribut Embedded proce and Arduino. UNIT V CASE ST Industrial IoT, Hor Environment, Agri  At the end of the CO1 CO2	CESSORS  tes: Big-Data Analytics for IOT, Dependability, Interoperability, Sectessors for IOT: Introduction to Python programming -Building IOT  TUDIES  The Automation, smart cities, Smart Grid, connected vehicles, electriculture, Productivity Applications, IOT Defense  TOTAL  Course Outcomes  Course, the student will be able to  Analyze the concepts of IoT and its present developments.  Compare and contrast different platforms and infrastructures available.	urity, I with F	ZigBe Maint RASF nicle	e Smai 9 ainabili PERRY 9 chargin	ty.					



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- 13. UpenaDalal,"Wireless Communications & Networks, Oxford, 2015

	(3	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)											
	PO1	PO2	PO3	PSO1	PSO2	PSO3							
CO1	1	2	1	-	-	-							
CO2	-	2	-	-	-	-							
СОЗ	1	2	-	1	3	-							
CO4	2		3	3	3	3							
CO5	3	2	3	3	3	3							
AVG	1.75	2	2.3	2.3	3	3							





P24EM205	EMBEDDED SYSTEM LABORATORY - II	L	Т	Р	С			
PZ4EIVIZU5	EMBEDDED STSTEM LABORATORY - II	0	0	4	2			
	Course Objectives	•						
1	To involve the students to Practice on Workbench /Softv Boards with the supporting Peripherals.	vare Tools	/ Hardwa	re Process	sor			
2	To teach the concepts of algorithm development & programming on software tools and Digit processors with peripheral interfaces.							
3	To encourage students to practice in open source software	vare / packages /tools						
4	To train though hands-on practices in commercial and lie	censed Ha	ırdware-s	oftware su	iites			
5	Practicing through the subdivisions covered within expensionate into the revising the concepts acquired from the			to expose	e the			
DOMAIN	EXPERIMENT DETAILS	EQUIPM REQUIRI		PPORTS				
1	Programming ARM processor : ARM7 / ARM9/ARM Cortex Study on Incircuit Emulators, crosscompilers, debuggers	Microcontrollers with peripherals; ;IDE, Board Support Software Tool /Keil/uCOS Compiler/others						
2	I/O Programming with ARM processor : ARM7 / ARM9/ARM Cortex Microcontrollers I/O Interfacing : Timers/ Interrupts/ Serial port programming/PWM Generation/ Motor Control/ADC/DAC/ LCD/ RTC Interfacing/ Sensor Interfacing	Cortex Microcon	trollers w pport Sot	ARM7 / AR ith periphe ftware Too terface	erals;			
3	Programming with Rasberry Pi Microcontroller Board : Study on incircuit Emulators, crosscompilers, debuggers	;IDE, Boa	ard Suppo	s with peri ort Softwar ners				
4	I/O Programming with Arduino ,Rasberry Pi Microcontroller Boards I/O Interfacing : Timers/ Interrupts/ Serial port programming/PWM Generation/ Motor Control/ADC/DAC/ LCD/ RTC Interfacing/ Sensor Interfacing/IoT Applications	Tools/Compiler/others  Arduino,Rasberry Pi Microcontroller Boards with peripherals; Board Support Software Tools, peripherals with interface			ard			
5	Programming with DSP processors	Processo Tools & I			rd Support			
6	Study of one type of Real Time Operating Systems (RTOS)  Compilers & Platfor with VXWorks/ Keil, Linux Support/any I Semaphore implem				va			
			TOTAL	. HR : 60				





	Course Outcomes								
At th	At the end of the course, the student will be able to								
CO1	Experiment and demonstrate with simulators, in programming processor boards, processor interfacing/ designing digital controllers								
CO2	Design & simulate Arithmetic ,Logic programs, Filters, Signal analysis with simulators/experiments ,in programming processor boards, processor interfacing/ Tools								
CO3	Develop real time solution for embedded applications.								
	Program and compile in various tools & software domains.								
	Improved Employability and entrepreneurship capacity due to knowledge up gradation onrecent trends in commercial embedded processors and its programmable interfacing.								

	(3	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)										
	PO1	PO2	PO3	PSO1	PSO2	PSO3						
CO1	1	3	1	1	2	1						
CO2		1	2	-	-	-						
CO3	1	-	3	2	3	-						
CO4	2	2	3	3	3	3						
CO5	3	2	3	3	3	3						
AVG	1.7	2	2.4	2.2	2.7	2.3						





		L	т	Р	С	
P24EM206	EMBEDDED PROGRAMMING LABORATORY – II	0	0	4	2	
	Course Objectives	l	<u> </u>	<u> </u>		
1	To involve the students to Practice on Workbench /So Boards with the supporting Peripherals.	oftware Too	ols/ Hardwa	re Proces	sor	
2	To teach the concepts of algorithm development & processors with peripheral interfaces.	ogramming	j on softwai	re tools an	d Digital	
3	To encourage students to practice in open source sof	tware / pac	kages /too	ls	,	
4	To train though hands-on practices in commercial and	d licensed l	Hardware-s	oftware su	uites	
5	Practicing through the subdivisions covered within ex students into the revising the concepts acquired from			to expose	e the	
S.NO	EXPERIMENT DETAILS	EQUIPME	neory subjects.  EQUIPMENT/ SUPPORTS REQUIR			
1	Programming in Freeware softwares/ Platforms	Programn freeware	ning Compi	lers&Platfo	orms on	
2	Software & Modelling tools 1. Study on MEMS Tools 2. Study on process Controller modeling 3. PLC/SCADA/PCB 4. one type CAD Tool	Personal Computers, Software & programming/modelling tools Simulation Tools as Labview /others				
3	Programming & Simulation in GUI Simulators/Tools/others ü Graphical User interface simulations &modeling of instrumentation & controllers					
4	Programming & Simulation in Python Simulators/Tools/others	Programn	ning in Pyth	on Platfor	m	
5	Programming with wired/wireless communication protocol/Network Simulators	Support S	Communica oftware Too ommunicati	ols for BU		
	Linux programming Tool chain	PC with Li	nux OS		-	
			TOTAL	HR : 60		
	Course Outcomes					
At the end	of the course, the student will be able to					
CO1	Developing Optimized code for embedded processor					
CO2	Outline the concepts of how process can be realized				<u>'</u>	
CO3	Compare and analyze device, Circuit and System lever embedded applications.	el simulato	1	s to devel	The same of the sa	
CO4	Incorporate I/O software interface using IDE and High	level langu	uages with	processor		
CO5	Improved Employability and entrepreneurship capacit Embedded programming concepts.	y due to kr	owledge u		n on	



DO 4511004		L	Т	Р	С					
P24EM301	PROJECT WORK I	0	0	12	6					
	Course Objectives									
1										
2	To improve the design ability and the oral, written presentation skill	s of the	student	S						
3	To provide an insight of developing optimized embedded solution for system automation									
4	To emphasize the need of Hardware & Software design tools usage for	or real t	ime app	lications.						
5	To enhance capacity to compete for placement and developing abili-	ty for								
	Course Outcomes									
At the end	of the course, the student will be able to									
CO1	Any of the listed Domains their Design, Development capability in Buthrough Hardware & Software Tools.	uilding A	utomat	ion for a p	rocess					
CO2	Interpreting Pre-Requisites insists choice of project title from the enlisted broad domain of research topics for Project work:									
CO3	Demonstrate project work to enhance students' capacity to work in Research Areas of the Department interests or of Industrial importance.									
CO4	Demonstrate the skill in Oral and Written Communication as presented in the Thesis Book via Viva-Voc Examination									
CO5	Improved Employability and entrepreneurship capacity due to know skilled up through learning & practicing in Design / development t analysis with project report submission (relevant to the candidates	pment through simulation/experimental								

	(3	3/2/1 indicates	the strength of	O/PO Mapping of correlation) 3-St ome Outcomes (PC		Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	3
CO2	3	-	-	-	-	-
CO3	3	-	-	-	-	3
CO4	3	3	3	3	3	3
CO5	2	3	3	3	3	3
AVG	2.8	3	3	3	3	3





D24EM404	DDO ISCT. WORK II		Т	Р	С			
P24EM401	PROJECT WORK II	0	0	24	12			
	Course Objectives							
1	To provide a hands on skills by training on domains of embedded s	systems	techno	logies				
2	To improve the design ability and the oral, written presentation sk	ills of th	e stude	nts				
3	To provide an insight of developing optimized embedded solution for system automation							
4	To emphasize the need of Hardware &Software design tools usage	for real	time ap	plications.				
5	To enhance capacity to compete for placement and developing ab	lity for						
	Course Outcomes							
At the end	of the course, the student will be able to							
CO1	Any of the listed Domains their Design, Development capability in through Hardware & Software Tools.	Building	Autom	ation for a	process			
CO2	Interpreting Pre-Requisites insists choice of project title from the enlisted broad domain of research topics for Project work:							
CO3	Demonstrate project work to enhance students' capacity to work in Research Areas of the Department interests or of Industrial importance.							
CO4	Demonstrate the skill in Oral and Written Communication as presented in the Thesis Book via Viva-Voce Examination							
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation with getting skilled up through learning & practicing in Design / development through simulation / experimental analysis with project report submission (relevant to the candidates project area) by individuals.							

	(3	3/2/1 indicates	the strength of	D/PO Mapping of correlation) 3-St me Outcomes (PC		Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	3	3	3	3
CO2	3	-	-	-	-	-
CO3	3	-	-	-	-	3
CO4	3	3	3	3	3	3
CO5	2	3	3	3	3	3
AVG	2.8	3	3	3	3	3





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P24EM111	WIRELESS AND MOBILE COMMUNICATION	L	Т	Р	С
PZ4EIVIIII	WIRELESS AND MOBILE COMMUNICATION	3	0	0	3
	Course Objectives				_
1	To study the Channel planning for Wireless Systems				
To study the Mobile Radio Propagation and Equalization and Diversity					
3	T o study the Equalization and Diversity				
4	To provide insight about wideband code division based access.				
5	To study the Wireless multiple access and IP				
UNIT 1 THE CE	LLULAR CONCEPT			9	

System Design Fundamentals: Introduction, Frequency Reuse, Channel Assignment Strategies, Handoff Strategies-Prioritizing Handoffs, Practical Handoff Considerations, Interference and system capacity -Co channel Interference and system capacity, Channel planning for Wireless Systems, Adjacent Channel interference, Power Control for Reducing interference, Trunking and Grade of Service, Improving Coverage & Capacity in Cellular Systems-Cell Splitting, Sectoring.

### UNIT II MOBILE RADIO PROPAGATION: LARGE-SCALE PATH LOSS

9

Introduction to Radio Wave Propagation, Free Space Propagation Model, Relating Power to Electric Field, Diffraction-Fresnel Zone Geometry, Knife edge Diffraction Model, Multiple knife-edge Diffraction, Scattering, Outdoor Propagation Models-Longley-Ryce Model, Okumura Model, Hata Model, Indoor Propagation Models-Partition losses, Partition losses between Floors, Log-distance path loss model, Ericsson Multiple Breakpoint Model, Attenuation Factor Model, Signal penetration into buildings, Ray Tracing and Site Specific Modelling.

#### **UNIT III MOBILE RADIO PROPAGATION**

9

Small -Scale Fading and Multipath: Small Scale Multipath propagation-Factors influencing small scale fading, Doppler shift, Impulse Response Model of a multipath channel-Relationship between Bandwidth and Received power, Small-Scale Frequency Domain Channels Sounding, Parameters of Mobile Multipath Channels-Time Dispersion Parameters, Coherence Bandwidth, Doppler Spread and Coherence Time, Types of Small-Scale Fading-Fading effects Due to Multipath Time Delay Spread, Flat fading, Frequency selective fading, Fading effects Due to Doppler Spread-Fast fading, slow fading, Fundamentals of Equalization, Training A Generic Adaptive Equalizer, Equalizers in a communication Receiver, Linear Equalizers, Nonlinear Equalization

#### UNIT IV WIDEBAND CODE DIVISION MULTIPLE ACCESS

CDMA system overview -air interface -physical and logical channel-speech coding, multiplexing and channel coding -spreading and modulation: frame structure, spreading codes-uplink-downlink -physical layer procedures: cell search and synchronization-establishing a connection-power control- handoveroverload control.

### **UNIT V IP MOBILITY FRAMEWORK**

9

Challenges of IP Mobility -Address Management -Dynamic Host Configuration Protocol and Domain Name Server Interfaces -Security -Mobility-Based AAA Protocol -IP Mobility Architecture Framework -x Access Network -IPv6 Challenges for IP Mobility.

TOTAL HR



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	Course Outcomes
At the	end of the course, the student will be able to
CO1	Understand Cellular communication concepts
CO2	Explain the mobile radio propagation
CO3	Perceive the wireless network different type of MAC protocols
CO4	Analyse the Equalization and Diversity
CO5	Build the Wireless multiple access and IP
REFE	RENCES
1.Wirel	ess Communications, Principles, Practice –Theodore, S. Rappaport, 2nd Ed., 2002, PHI.
2. Wire	eless Communications Andrea Goldsmith, 2005 Cambridge University Press.
3. Princ	ciples of Wireless Networks –KavehPahLaven and P. Krishna Murthy, 2002, PE
4. Mob	ile Cellular Communication –GottapuSasibhushana Rao, Pearson Education, 2012.
5. Wire	eless Digital Communications –KamiloFeher, 1999, PHI.

	(3	/2/1 indicates	the strength o	D/PO Mapping f correlation) 3-St me Outcomes (PC	rong 2-Medium, 1 Ds)	-Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	2	1	-	-
CO2	3	3	2	2	-	-
CO3	3	3	2	3	2	2
CO4	2	3	3	3	2	2
CO5	3	3	3	3	2	3
AVG	2.8	3	2.4	2.4	1.2	1.4

6. Wireless Communication and Networking –William Stallings, 2003, PHI





			_				
P24EM112	VIRTUAL INSTRUMENTATION	L	T	Р	С		
		3	0	0	3		
	Course Objectives						
1	Understanding the difference between conventional and graphica	l pro	gramn	ning.			
2	Introducing the basics of Lab VIEW and programming concepts.						
3	Differentiating the real time and virtual instrument.	ferentiating the real time and virtual instrument.					
4	epresent and review signals acquire process in digital domain.						
5	Analyzing the basics of data acquisition and learning the concept with Lab VIEW.	s of c	lata a	cquisit	tion		
UNIT 1 FUNDAME	NTALS OF VIRTUAL INSTRUMENTATION			9			
Traditional instrume	epts of Virtual Instrumentation (VI) and Graphical Programming - Vents, Hardware and Software in virtual instrumentation, Data Flow Fition of VI Properties - VI Documentation.						
UNIT II VI PROGRAMMING STRUCTURES							
	ent - Modular programming - Formula Nodes - Loops - Shift Regist Case and Sequence Structures - Arrays and Clusters - Graphs and nd File I/O.						
UNIT III DATA ACC	QUISITION AND INTERFACING STANDARDS			9			
sampling methods a Interfacing of extern	uisition – DAQ hardware and software architecture – DAQ hardwal and grounding techniques, analog I/O, digitaI I/O, counter/timer - C nal instruments to a PC - RS232 - RS485 - GPIB – System Interfac bus protocols of MOD bus and CAN bus - Industrial Ethernet.	omm	unica	tion:	PCI,		
UNIT IV ADVANCE	D PROGRAMMING			9			
Introduction, File For READ Function Stri examples Use of an	ion of State Machine, A Simple State Machine, Event Structures. Formats, File I/O Functions, Path Functions, Sample VIs to Demonsing Handling: Introduction, String Functions, Lab VIEW String Formalysis tools and application of VI: Fourier transforms, Power spect Development of Control system, Image acquisition and processing.	trate nats, :rum,	File W	/RITE al	and		
UNIT V CASE STU	UNIT V CASE STUDIES						
Configuration of Reprogramming Structure	oring System using PC based Data Acquisition System - Machine al-Time I/O Hardware in MAX - Host & Target VI – Prioritization of tures in Lab VIEW – Real-Time Application Deployment using my bloyed Applications – Running Web Services in my RIO.	Task	s – Ti	med	ntrol,		
	TOTAL	HR		45			





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	Course Outcomes					
At the	At the end of the course, the student will be able to					
CO1	Infer and Interpret the fundamentals of Virtual Instrumentation and data Acquisition.					
CO2	Explain the difference between the traditional and virtual instrumentation.					
CO3	Illustrate the theoretical concepts to realize practical systems.					
CO4	Analyze and evaluate the performance of Virtual Instrumentation Systems					
CO5	Build a VI system to solve real time problems using data acquisition.					

- 1.Jovitha Jerome, —Virtual Instrumentation using Lab VIEWII, PHI Learning Pvt. Ltd., 2010.
- 2. Sanjay Gupta and Joseph John, "Virtual Instrumentation Using Lab VIEW", Tata McGraw Hill, 2008.
- 3. Gary Johnson and Richard Jennings, —Lab VIEW Graphical Programmingll, McGraw Hill Inc., Fourth Edition, 2006.
- 4. Rick Bitter, TaqiMohiuddin and Matt Nawrocki, "Lab VIEW Advanced Programming Techniques", CRC Press, 2009.
- 5.Lisa. K. Wills, "Lab VIEW for Everyone", Prentice Hall of India, 2nd Edition, 2008.
- 6. William Buchanan, —Computer Buses Design and Application II, CRC Press, 2000.
- 7. Clyde F Coombs, —Electronic Instruments Handbook, McGraw Hill Inc., Third Edition, 1999.

	(3	/2/1 indicates	the strength o	D/PO Mapping f correlation) 3-St me Outcomes (PC		-Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	2	1	2	-	-
CO2	-	-	2	-	-	-
CO3	1	3	3	3	1	1
CO4	2	2	3	3	2	2
CO5	3	3	3	3	3	3
AVG	2	2.5	2.4	2.7	2	2





	M.E. Embedded System Technologies		
P24EM113	EMBEDDED PROCESSOR DEVELOPMENT  3	+ +	P 0
	Course Objectives		
1	To learn about basic concepts of embedded system		
2	To learn about ARM architecture		
3	To learn C language and assembly programming.		
4	To learn Object orientation for programming and C++.		
5	To learn software modelling fundamentals.		
UNIT 1 EMB	EDDED CONCEPTS		9
embedded s Architecture	to embedded systems, Application Areas, Categories of embedded systems, Overview ystem architecture, Specialties of embedded systems, recent trends in embedded syste of embedded systems, Hardware architecture, Software architecture, Application Softw ion Software, Development and debugging Tools.	ems	
UNIT II ARM	ARCHITECTURE AND OVERVIEW OF CORTEX		9
Cortex-M3 B Special Regi Tables, Stac Instruction D	d Instruction Set Architecture. Overview of Cortex-M3. asics: Registers, General Purpose Registers, Stack Pointer, Link Register, Program Costers, Operation Mode, Exceptions and Interrupts, Vector. k Memory Operations, Reset Sequence. Instruction Sets: Assembly Basics, Instruction escriptions. Cortex-M3 Implementation Overview: Pipeline, Block Diagram, Bus Interfact-Code Bus, D-Code Bus, System Bus, External PPB and DAP Bus.	List	,
UNIT III COF	RTEX-M3/M4 PROGRAMMING		9
Standard), U Software Inte	pical Development Flow, Using C, CMSIS (Cortex Microcontroller Software Interface Ising Assembly Exception Programming: Using Interrupts, Exception/Interrupt Handlers, errupts, Vector Table Relocation. Memory Protection Unit and other Cortex-M3 features etting Up the MPU, Power Management, Multiprocessor Communication.		<b>-</b> U
UNIT IV UNI	FIED MODELING LANGUAGE		9
basics. Obje Timing diagr	he object model with the use case model – Key strategies for object identification – UMct state behaviour – UML state charts – Role of scenarios in the definition of behaviour ams – Sequence diagrams – Event hierarchies – types and strategies of operations – design in UML concurrency design – threads in UML.		
UNIT V EME	SEDDED SOFTWARE DEVELOPMENT TOOLS AND RTOS		9
	tion process – libraries – porting kernels – C extensions for embedded systems – emula ng techniques – RTOS - system design using RTOS .	itior	1



TOTAL HR

45



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	Course Outcomes					
At the e	At the end of the course, the student will be able to					
CO1	Demonstrate about basic concepts of embedded system					
CO2	Build ARM architecture					
CO3	Understand C language and assembly programming.					
CO4	Build and compile Object orientation for programming and C++					
CO5	Create software modelling					

- 1. The Definitive Guide to the ARM Cortex-M3, Joseph Yiu, econd Edition, Elsevier Inc. 2010.
- 2. Embedded/Real Time Systems Concepts, Design and Programming Black Book, Prasad, KVK.
- 3. David Seal "ARM Architecture Reference Manual", 2001 Addison Wesley, England; Morgan Kaufmann Publishers
- 4. Andrew N Sloss, Dominic Symes, C0hris Wright, "ARM System Developer's Guide -Designing and Optimizing System Software", 2006, Elsevier.
- 5. Steve Furber, "ARM System-on-Chip Architecture", 2ndEdition, Pearson Education.
- 6. Cortex-M series-ARM Reference Manual .
- 7. Cortex-M3 Technical Reference Manual (TRM).
- 8. STM32L152xx ARM Cortex M3 Microcontroller Reference Manual.
- 9. ARM Company Ltd. "ARM Architecture Reference Manual-RM DDI 0100E".
- 10. ARM v7-M Architecture Reference Manual (ARM v7-M ARM).
- 11. Ajay Deshmukh, "Microcontroller -Theory & Applications", Tata McGraw Hill.
- 12. Arnold. S. Berger, "Embedded Systems Design -An introduction to Processes, Tools and Techniques", Easwer Press.
- 13. David E. Simon, "An Embedded Software Primer", Pearson Education, 2003.

	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)								
	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	2	3	1	1	-	3			
CO2	3	-	3	3	2	-			
CO3	-	-	2	2	3	-			
CO4	-	-	3	-	3	_			
CO5	2	-	3	2	3 DEPA	RTMENT			
AVG	2.3	3	2.4	2	29 APPR	OVED B			





	M.E. Embedded dystem recimologies						
P24EM114	AUTOMOTIVE EMBEDDED SYSTEM	L T	+	C 3			
	Course Objectives	<u>-   -</u>	1-				
1	To expose the students to the fundamentals and building of Electronic Engine Control systems.	 )l					
2	teach on functional components and circuits for vehicles.						
3	To discuss on programmable controllers for vehicles management systems.						
4	To teach logics of automation & commercial techniques for vehicle communication.						
5	To introduce the embedded systems concepts for E-vehicle system development.						
UNIT 1 BASI	C OF ELECTRONIC ENGINE CONTROL SYSTEMS	1	9				
Automotive a Introduction t modeling of a	nicrocontrollers- Electronic control Unit- Hardware & software selection and requireme pplications – open source ECU- RTOS - Concept for Engine management-Standards; o AUTOSAR and Introduction to Society SAE- Functional safety ISO 26262- Simulation automotive system components.		ınd				
	SORS AND ACTUATORS FOR AUTOMOTIVES	丄	9				
	nsors- sensors interface to the ECU, conventional sensors and actuators, Modern sen DAR sensor- smart sensors- MEMS/NEMS sensors and actuators for automotive app						
UNIT III VEH	ICLE MANAGEMENT SYSTEMS		9				
electronic ign suspension - for interfacing system, pow	gine Control-engine mapping, air/fuel ratio spark timing control strategy, fuel control, ition- Adaptive cruise control - speed control-anti-locking braking system-electronic electronic steering, Automatic wiper control-body control system; Vehicle system so with EMS, ECU. Energy Management system for electric vehicles- Battery managemer management system-electrically assisted power steering system-Adaptive lighting ollision Avoidance.	nent	t				
UNIT IV ONE	SOARD DIAGONSTICS AND TELEMATICS		9				
communication communication	gnosis of vehicles -System diagnostic standards and regulation requirements Vehicle on protocols Bluetooth, CAN, LIN, FLEXRAY, MOST, KWP2000 and recent trends in vons-Navigation- Connected Cars technology – Tracking- Security for data communicasplay and Virtual Instrumentation, multimedia electronics- Role of IOT in Automotive s	itior	۱-				
UNIT V ELEC	CTRIC VEHICLES	$\top$	9				
	les –Components- Plug in Electrical vehicle- Charging station – Aggregators- Fuel cel cles- Autonomous vehicles.	ls/S	iola	ır			
		- 1					



**TOTAL HR** 

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	Course Outcomes							
At the er	At the end of the course, the student will be able to							
CO1	Insight into the significance of the role of embedded system for automotive applications.							
CO2	Illustrate the need, selection of sensors and actuators and interfacing with ECU							
CO3	Develop the Embedded concepts for vehicle management and control systems.							
CO4	Demonstrate the need of Electrical vehicle and able to apply the embedded system technology for various aspects of EVs							
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design and its application in automotive systems.							

- 1. William B. Ribbens, "Understanding Automotive Electronics", Elseiver, 2012
- 2. Ali Emedi, Mehrdedehsani, John M Miller, "Vehicular Electric power system- land, Sea, Air and Space Vehicles" Marcel Decker, 2004.
- 3. L.Vlacic, M.Parent, F.Harahima, "Intelligent VehiclTechnologies", SAE International, 2001.
- 4. Jack Erjavec, JeffArias, "Alternate Fuel Technology-Electric, Hybrid& Fuel Cell Vehicles", Cengage, 2012.
- 5. Electronic Engine Control technology Ronald K Jurgen Chilton's guide to Fuel Injection Ford.
- 6. Automotive Electricals / Electronics System and Components, Tom Denton, 3rd Edition, 2004.
- 7. Uwe Kiencke, Lars Nielsen, "Automotive Control Systems: For Engine, Driveline, and Vehicle", Springer; 1 edition, March 30, 2000.
- 8. Automotive Electricals Electronics System and Components, Robert Bosch Gmbh, 4 2004.
- 9. Automotive Hand Book, Robert Bosch, Bently Publishers, 1997.
- 10. Jurgen, R., Automotive Electronics Hand Book.

	CO/PO, PSO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)								
	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	-	2	1	1	-	2			
CO2	2	3	2	2	2	3			
СОЗ	3	3	3	3	3	2			
CO4	3	3	3	3	3	2			
CO5	3	3	3	3	3	2			
AVG	2.7	2.8	2.4	2.4	2.7	2.2			





P24EM115	INTELLIGENT CONTROL AND AUTOMATION					
	Course Objectives	3	0   0	1 -		
1	To Impart the knowledge of various optimization techniques and hybrid schemes					
2	To introduce the concept, Analysis and implementation of ANN and Fuzzy logic	cont	roller	s.		
3	To Emphasis the need for Genetic algorithm and its role for automation.					
4	To provide the basics of automation and its requirements					
5	To demonstrate the role of Intelligent controller in automation applications.					
UNIT 1 AR	TIFICIAL NEURAL NETWORK & FUZZY LOGIC			9		
Back propa Fuzzy Logi	NEURAL NETWORK: Learning with ANNs, single-layer networks, multi-layer per gation algorithm (BPA) ANNs for identification, ANNs for control, Adaptive neuro c c Control: Introduction, fuzzy sets, fuzzy logic, fuzzy logic controller design, Fuzzy n, Adaptive Fuzzy Control Design.	ontr	oller.			
UNIT II GE	NETIC ALGORITHM			9		
typical cont	ept of Genetic algorithm and detail algorithmic steps- Hybrid genetic algorithm - So rol problems using genetic algorithm. Concept on some other search techniques lil -colony search and Particle Swarm Optimization					
UNIT III HY	BRID CONTROL SCHEMES			9		
	n and rule base using ANN–Neuro fuzzy systems-ANFIS–Optimization of member se using Genetic Algorithm and Particle Swarm Optimization	ship	func	tion		
UNIT IV AL	ITOMATION			9		
Basic Elem Industrial A	n to Automation - Automation in Production System, Principles and Strategies of Auents of an Automated System, Advanced Automation Functions, Levels of Automautomation -computer vision for automation-PLC and SCADA based Automation-Industry 4.0.	tion	S-	١,		
UNIT V INT	ELLIGENT CONTROLLER FOR AUTOMATION APPLICATION			9		
	s of Intelligent controllers in Industrial Monitoring, optimization and control- Smart A concept for Electrical vehicle- Intelligent controller and Automation for Power Syst		iance	s-		
	TOTAL	HR	4	15		
	Course Outcomes					
At the and	of the course, the student will be able to					
At the end						
CO1	Demonstrate the basic architectures of NN and Fuzzy logics					
	Demonstrate the basic architectures of NN and Fuzzy logics  Design and implement GA algorithms and know their limitations					
CO1						
CO1	Design and implement GA algorithms and know their limitations	RA				



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- 1.Laurene V.Fausett, "Fundamentals of Neural Networks, Architecture, Algorithms, and Applications", Pearson Education, 2008.
- 2. Timothy J.Ross, "Fuzzy Logic with Engineering Applications", Wiley, Third Edition, 2010.
- 3.David E.Goldberg, "Genetic Algorithms in Search, Optimization, and Machine Learning", Pearson Education, 2009.
- 4. W.T.Miller, R.S.Sutton and P.J.Webrose, "Neural Networks for Control", MIT Press, 1996.
- 5.Srinivas Medida, Pocket Guide on Industrial Automation for Engineers and Technicians, IDC Technologies.
- 6. ChanchalDey and Sunit Kumar Sen, Industrial Automation Technologies,1st Edition,CRC Press, 2022

	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)								
	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	1	1	1	1	-	1			
CO2	2	2	3	3	3	2			
CO3	3	2	2	2	-	-			
CO4	3	2	2	2	-	-			
CO5	3	-	3	3	-	2			
AVG	2.4	1.7	2.2	2.2	3	1.6			





		L	Т	Р	С					
P24EM116	UNMANNED AERIAL VEHICLE	3	0	0	3					
	Course Objectives									
1	To make the students to understand the basic concepts and components	ents o	of UA\	/ syst	ems.					
2	To teach the UAV design concepts.									
3	o provide an insight about the hardware structure for UAVs.									
4	To emphasis the communication protocol requirements and control st	trateg	y for I	UAVs.	ı					
5	To highlight the need and the role of UAVs for real time applications a real time UAVs.	and d	evelo	oment	of					
UNIT 1 INTRO	DUCTION TO UAV			9						
	packground - History of UAV –classification – societal impact and future (UAS) componentsmodels and prototypes – System Composition- ap			nman	ned					
UNIT II THE DI	ESIGN OF UAV SYSTEMS			9						
Characteristics	Design and Selection of the System-Aerodynamics and Airframe Confi of Aircraft Types- Design Standards-Regulatories and regulations - De			ealth-						
CONTION SURFACE	s-specifications.									
	s-specifications.  WAREs for UAVs			9						
UNIT III HARD Real time Emb	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and			<b>9</b> wer	.Vs-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and			<b>9</b> wer	\Vs-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and L.	l actu	ators	9 wer for UA						
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-act tion, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for the control of the contro	l actu	ators	9 wer for UA						
Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for y system-simulation-ground test-analysis-trouble shooting	frequ	ency i	9 wer for UA 9 range 9	-					
Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control fory system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-flig	frequ ght Tenent	ency i	9 wer for UA 9 range 9	-					
Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-act tion, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for y system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-flig to UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager	frequ ght Tenent	ency i	9 wer for UA  9 range  9 - Mini, defens	-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav Micro and Nand	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-act tion, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS igation-ground control software- System Ground Testing- System In-flig to UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager	frequ ght Tenent	ency i	9 wer for UA  9 range  9 - Mini, defens	-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav Micro and Nand	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control fory system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-fligo UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager  TOTAL  Course Outcomes	frequ ght Tenent	ency i	9 wer for UA  9 range  9 - Mini, defens	-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMN Payloads-Teler modems-memo UNIT V THE D Waypoints nav Micro and Nand	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer —gyros-action, installation, configuration, and testing —MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-fligo UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager  TOTAL  Course Outcomes	frequ ght Tement	ency (	9 wer for UA  9 range  9 - Mini, defens	-					
UNIT III HARD Real time Emb supply- integra Autopilot – AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav Micro and Nand	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer —gyros-act tion, installation, configuration, and testing —MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for y system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-flig to UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager  TOTAL  Course Outcomes  the course, the student will be able to  Identify different hardware for UAV	frequ ght Tement	ency (	9 wer for UA  9 range  9 - Mini, defens	-					
UNIT III HARD Real time Emb supply- integra Autopilot — AGI UNIT IV COMI Payloads-Teler modems-memo UNIT V THE D Waypoints nav Micro and Nand  At the end of t CO1 CO2	WAREs for UAVs  edded processors for UAVs - sensors-servos-accelerometer –gyros-action, installation, configuration, and testing –MEMS/NEMS sensors and L.  MUNICATION PAYLOADS AND CONTROLS  metry-tracking-Aerial photography-controls-PID feedback-radio control for y system-simulation-ground test-analysis-trouble shooting  EVELOPMENT OF UAV SYSTEMS  igation-ground control software- System Ground Testing- System In-flig to UAVs- Case study: Agriculture- Health- Surveying- Disaster Manager  TOTAL  Course Outcomes  the course, the student will be able to  Identify different hardware for UAV  Determine preliminary design requirements for an unmanned aerial version.	frequ ght Tement	ency (	9 wer for UA  9 range  9 - Mini, defens	-					





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- 1.Reg Austin "Unmanned Aircraft Systems UAV design, development and deployment", Wiley, 2010.
- 2. Paul G Fahlstrom, Thomas J Gleason, "Introduction to UAV Systems", UAV Systems, Inc, 1998
- 3. Dr. Armand J. Chaput, "Design of Unmanned Air Vehicle Systems", Lockheed Martin Aeronautics Company, 2001
- 4. Kimon P. Valavanis, "Advances in Unmanned Aerial Vehicles: State of the Art and the Road to Autonomy", Springer, 2007
- 5. Robert C. Nelson, Flight Stability and Automatic Control, McGraw-Hill, Inc, 1998.

	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)								
	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	1	3	2	-	-	2			
CO2	3	3	3	-	-	2			
CO3	3	3	3	3	3	3			
CO4	-	-	2	3	3	2			
CO5	3	-	3	3	3	3			
AVG	2.5	3	2.6	3	3	2.4			





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P24EM117 DSP BASED SYSTEM DESIGN	L 3	T 0	P 0	C 3				
Course Objectives	<u> </u>	U	U	<u> </u>				
1 To understand various representation methods of DSP system								
2 To provide insight about different DSP algorithms								
To familiarize the various architectures of DSP system								
To perform analysis of DSP architectures and to learn the implement in programmable hardware	tatior	n of DS	SP sys	tem				
5 To learn the details of DSP system interfacing with other peripherls								
JNIT 1 REPRESENTATION OF DSP SYSTEM			9					
code size, embedded applications. Representation of digital signal processing system signal flow graphs, data-flow graphs, dependence graphs. Techniques for enhancing hroughput - parallelism and pipelining.				ns,				
JNIT II DSP ALGORITHMS			9					
DSP algorithms - Convolution, Correlation, FIR/IIR filters, FFT, adaptive filters, sampli DCT, Decimator, Expander and Filter Banks. DSP applications. Computational charact algorithms and applications, Numerical representation of signals-word length effect ar free adders, Multiplier.	cteris	stics of	f DSP					
JNIT III SYSTEM ARCHITECTURE			9					
ntroduction, Basic Architectural Features, DSP Computational Building Blocks, Bus A Memory, Data Addressing Capabilities, Address Generation Unit, Programmability and Features for External Interfacing. VLIW architecture. Basic performance issue in pipel mplementation of MIPS, Instruction Level Parallelism, Dynamic Scheduling, Dynamic Memory hierarchy.Study of Flxed point and floating point DSP architectures	d Pro ining	ogram <sub>I</sub> , Sim <sub>l</sub>	Execu ole					
JNIT IV ARCHITECTURE ANALYSIS ON PROGRAMMABLE HARDWARE			9					
Analysis of basic DSP Architectures on programmable hardwares. Algorithms for FIR structures, architectures for real and complex fast Fourier transforms, 1D/2D Convoluminimal filtering algorithm. FPGA: Architecture, different sub-systems, design flow for mapping of DSP algorithms onto FPGA.	tions	s, Wind	ograd					
JNIT V SYSTEM INTERFACING			9					
Examples of digital signal processing algorithms suitable for parallel architectures suc		GPU:	s and					
multiGPUs. Interfacing: Introduction, Synchronous Serial Interface CODE, A CODEC ADC interface.	Inter	face (						





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	Course Outcomes					
At the en	At the end of the course, the student will be able to					
CO1	Evaluate the DSP system using various methods.					
CO2	Design algorithm suitable for different DSP applications.					
CO3	Explain various architectures of DSP system.					
CO4	Implement DSP system in programmable hardware.					
CO5	Build interfacing of DSP system with various peripherals.					

- 1.Sen M Kuo, Woon Seng S Gan, Digital Signal Processors
- 2. Digital Signal Processing and Application with C6713 and C6416 DSK, RulphChassaing, Worcester Polytechnic Institute, A Wiley Interscience Publication
- 3. Architectures for Digital Signal Processing, Peter Pirsch John Weily, 2007
- 4. DSP Processor and Fundamentals: Architecture and Features. Phil Lapsley, JBier, AmitSohan, Edward A Lee; Wiley IEEE Press
- 5. K. K. Parhi VLSI Digital Signal Processing Systems Wiley 1999.
- 6. RulphChassaing, Digital signal processing and applications with C6713 and C6416 DSK, Wiley, 2005
- 7. Keshab K Parhi, VLSI Digital Signal Processing Systems:Design and Implementation, student Edition, Wiley, 1999.
- 8. Nasser Kehtarnavaz, Digital Signal Processing System Design: LabVIEW-Based Hybrid Programming, Academic Press, 2008

	(3	CO/PO Mapping (3/2/1 indicates the strength of correlation) 3-Strong 2-Medium, 1-Weak Programme Outcomes (POs)								
	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	-	3	-	-	-	-				
CO2	3	3	3	2	3	2				
CO3	-	3	-	-	-	-				
CO4	3	-	3	3	3	3				
CO5	2	-	3	2	3	3				
AVG	2.6	3	3	2.3	3	2.6				





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		L	Т	Р	С
P24EM118	MACHINE LEARNING AND DEEP LEARNING	3	0	0	3
	Course Objectives				
1	Understanding about the learning problem and algorithms				
2	Providing insight about neural networks				
3	Introducing the machine learning fundamentals and significance				
4	Enabling the students to acquire knowledge about pattern recognition.				
5	Motivating the students to apply deep learning algorithms for solving re	al lif	e pro	oblen	ns.
UNIT 1 LEARNIN	G PROBLEMS AND ALGORITHMS			9	
Various paradigm:	s of learning problems, Supervised, Semi-supervised and Unsupervised	algo	orithr	ns	
UNIT II NEURAL	NETWORKS			9	
propagation Traini Auto associative, l Quantization, Gra	yer neural network, Linear Separability, Hebb Net, Perceptron, Adaline, ng Algorithms for Pattern Association - Hebb rule and Delta rule, Hetero Kohonen Self Organising Maps, Examples of Feature Maps, Learning V dient descent, Boltzmann Machine Learning.	ass	socia		CK
UNIT III MACHINI CLASSIFICATION	E LEARNING – FUNDAMENTALS & FEATURE SELECTIONS & NS			9	
dimensionality, tra stopping, regulariz	es: The confusion matrix, Accuracy, Precision, Recall, F1- Score, the cuining, testing, validation, cross validation, overfitting, under-fitting the datation, bias and variance. Feature Selection, normalization, dimensional SVM, Decision trees, Naïve Bayes, Binary classification, multi class class	ita, e ity re	early educt		
UNIT IV DEEP LE	ARNING: CONVOLUTIONAL NEURAL NETWORKS			9	
	vorks, Activation functions, back propagation in CNN, optimizers, batch , pooling layers, fully connected layers, dropout, Examples of CNNs.	norn	naliza	ation	
UNIT V DEEP LE	ARNING: RNNS, AUTOENCODERS AND GANS			9	
	RNN Cell, LSTM and GRU, Time distributed layers, Generating Text, Aubencoders, Denoisingautoencoders, Variationalautoencoders, GANs: The Ns				or,
	TOTAL	HR		45	
	Course Outcomes				
At the end of the	course, the student will be able to				
CO1	Illustrate the categorization of machine learning algorithms.				
CO2	Compare and contrast the types of neural network architectures, activa	ation	func	ctions	
CO3	Acquaint with the pattern association using neural networks		-		
CO4	Elaborate various terminologies related with pattern recognition and ar convolutional neural networks	chite	-	es of	12
CO5	Construct different feature selection and classification techniques and network architectures such as RNN, Autoencoders, and GANs.	adva	ance	d neu	ıral



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- J. S. R. Jang, C. T. Sun, E. Mizutani, Neuro Fuzzy and Soft Computing A Computational Approach to Learning and Machine Intelligence, 2012, PHI learning
- 2. Deep Learning, lan Good fellow, YoshuaBengio and Aaron Courville, MIT Press, ISBN: 9780262035613, 2016.
- 3. The Elements of Statistical Learning. Trevor Hastie, Robert Tibshirani and Jerome Friedman. Second Edition. 2009.
- 4. Pattern Recognition and Machine Learning. Christopher Bishop. Springer. 2006.
- 5. Understanding Machine Learning. Shai Shalev-Shwartz and Shai Ben-David. Cambridge University Press. 2017.

	(3/	2/1 indicates	the strength o	D/PO Mapping f correlation) 3-St me Outcomes (PC		-Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	3	1	-	-	-
CO2	2	3	2	-	-	-
СОЗ	3	-	3	-	3	-
CO4	2	3	3	-	-	-
CO5	3	3	3	-	3	-
CO6	3	3	3	-	3	-
CO7	3	3	3	-	3	-
AVG	2.42	3	2.57	-	3	-





	W.E. Embedded System recimologies				
P24EM119	COMPUTER VISION	L 3	T 0	P 0	C 3
	Course Objectives	<u> </u>	U	U	
1	To introduce the fundamentals of Human and Computer Vision.				
2	To introduce the major ideas, concepts, methods and techniques in Comput	ter \	/ieic	nn.	
3	To impart Computer Vision knowledge by way of learning related algorithms		VISIC	<i>)</i> 11.	
3			utin	a w.i	th.
4	To make them familiar with both the Theoretical and Practical aspects of Colmages.	тір	utin	g wi	LT1
5	To provide the student with programming experience for implementing Comand algorithms.	pute	er V	isior	ı
UNIT I INTROD	DUCTION TO COMPUTER VISION			9	
Image Process Recent Resear Formation: Intro	rocessing – Various Fields that use Image Processing – Fundamentals Step ing – Components of an Image Processing System. Applications of Compute ch in Computer Vision. Introduction to Computer Vision and Basic Concepts oduction and Goals – Image Formation and Radiometry – Geometric Transfo nera Models – Image Reconstruction from a Series of Projections.	er Vi of In	isior mag	n – je	
UNIT II IMAGE	PROCESSING CONCEPTS AND IMAGE FEATURES			9	
Image Process Features: Tex Shape Repres	sing Concepts: Fundamentals – Image Transforms – Image Filtering sing – Mathematical Morphology – Image Segmentation. Image Descriture Descriptors – Colour Features – Edge Detection – Object Boursentation – Interest or Cornet Point Detectors – Histogram Oriented Gratter Transform.	ipto ndai	rs a	and and	
UNIT III IMAGE	PROCESSING WITH OPENCV			9	
and Images -	OpenCV and Python: Setting up OpenCV – Image Basics in OpenCV – F Constructing Basic Shapes in OpenCV. Image Processing in OpenCV: Im chniques – Constructing and Building Histograms – Thresholding Techniq	age	•	g Fil	es
UNIT IV OBJE	CT DETECTION			9	
Structure – Mo Applications: V	pes – Importance of Object Detection. The Working: Inputs and outputs – odel Architecture Overview – Object Detection on the Edge. Use Cases a l'ideo Surveillance – Self-driving Cars. Embedded Boards: Connecting Cards – Simple algorithms for processing Images and Videos.	nd		to	
UNIT V APPLIC	CATIONS AND CASE STUDIES			9	
<ul> <li>Motion Estir</li> </ul>	Machine Learning algorithms and their Applications in Medical Image Seg nation and Object Tracking – Face and Facial Expression Recognition Studies: Face Detection – Object Tracing – Eye Tracking – Ha th HoG.	۱ –	lma	age	





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	Course Outcomes
At the e	nd of the course, the student will be able to
CO1	Understand the major concepts and techniques in computer vision and image processing
CO2	Infer known principles of human visual system
CO3	Demonstrate a thorough knowledge of OpenCV.
CO4	Develop real-life Computer Visions Applications.
CO5	Build design of a Computer Vision System for a specific problem.

- 1. "Digital Image Processing", 4<sup>th</sup> Edition (Global Edition), Rafael C Gonzalez and Richard EWoods, Pearson Education Limited, 2018.
- 2. "Computer Vision and Image Processing Fundamentals and Applications", Manas KamalBhuyan, CRCPress, 2020.
- 3. "MasteringOpenCV4withPython", Alberto Fernández Villán, PacktPublishing, 2019.
- 4. "Practical Python and Open CV: Case Studies", 3<sup>rd</sup> Edition, Adrian Rosebrock, Pylmage Search, 2016.

	(3/2/1 indic		CO/PO Map rength of correlate Programme Outc	tion) 3-Strong 2-	Medium, '	1-Weak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	2	3	2	-	-	-
CO2	2	2	2	2	-	-
CO3	3	3	3	3	3	2
CO4	3	3	3	3	3	3
CO5	3	3	3	3	3	3
AVG	2.6	2.8	2.6	2.75	3	2.67





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P24EM120	MULTIMEDIA COMMUNICATIONS	L 3	0	+-	C 3
	Course Objectives		U	<u> </u>	3
1	To define the Multimedia Communication Models				
2	To explain Multimedia Transport in Wireless Networks				
	·				
3	To Solve the Security issues in multimedia networks				
4	To Illustrate real-time multimedia network applications.				
5	To explain different network layer based application				
UNIT 1 INTRO	DUCTION TO MULTIMEDIA COMMUNICATIONS		9		
Application and	ultimedia information representation, multimedia networks, multimedia applic I networking terminology, network QoS and application QoS, Digitization prinaudio and video.				
UNIT 2 COMP	RESSION TECHNIQUES FOR TEXT AND IMAGE			9	
predictive cod	o compression, audio compression – principles, DPCM, ADPCM, Adaptive ling, Code-Excited LPC, Perceptual coding, MPEG and Dolby codideo compression principles.	and lers	Li	inear /ideo	
UNIT 3 COMPI	RESSION TECHNIQUESFORAUIDOAND VIDEO			9	
	eo compression, audio compression – principles, DPCM, ADPCM, Adapt ng, Code-Excited LPC, Perceptual coding, MPEG and Dolby coders vide sion principles.				
UNIT 4 STAND	PARDSANDFRAMEWORK			9	
	ssion standards: H.261, H.263, MPEG, MPEG 1, MPEG 2, MPEG-4 and 7 standardization process of multimedia content description, MPEG 21				
UNIT 5 SYNCH	IRONIZATIONANDMANAGEMENT			9	
	nchronization, presentation requirements, reference model for synch SMIL, Multimedia operating systems, Resource management, process ma				
	TOTAL PERIO	DS		45	

	Course Outcomes	
At the e	nd of the course, the student will be able to	
CO1	Deploy the right multimedia communication models	
CO2	Apply QoS to multimedia network applications with efficient rou	ting techniques.
CO3	Solve the security threats in the multimedia networks.	
CO4	Develop the real-time multimedia network applications	DEPARTMENT
CO5	Improve to synchronize and manage the multimedia systems.	APPROVED BY



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- 1. Fred Halsall, "Multimedia Communications", Pearson education, 2001.
- 2. Raif Steinmetz, Klara Nahrstedt, "Multimedia: Computing, Communications and Applications", Pearsoneducation, 2002.

	(3/2/1	indicates the s	CO/PO Ma trength of correl Programme Out	ation) 3-Strong 2	-Medium, 1-We	ak
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	2	-	1	-	3	-
CO2	2	-	1	3	2	2
CO3	3	-	-	-	-	-
CO4	-	-	-	2	3	2
CO5	2	-	-	-	-	-
AVG	2.25	-	1	2.5	2.66	2





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P24EM121	EMBEDDED NETWORKING AND AUTOMATION	L	Т	Р	С
PZ4EWI1Z1	OF ELECTRICAL SYSTEM	3	0	0	3
	Course Objectives	•			
1	To discuss the fundamentals building blocks of a digital instrument.				
2	Introduce wired, WSN for configuring metering network				
3	Discuss requirements for grid automation using meters.				
4	To discuss networking configuration to develop PAN.				
5	To discuss the functions of digital instrument Power quality monitoring				
	1				

### **UNIT 1 BUILDING SYSTEM AUTOMATION**

9

Sensor Types & Characteristics: Sensing Voltage, Current, flux, Torque, Position, Proximity, Accelerometer - Data acquisition system- Signal conditioning circuit design- Uc Based & PC based data acquisition – uC for automation and protection of electrical appliances –processor based digital controllers for switching Actuators: Stepper motors, Relays –System automation with multi channel Instrumentation and interface.

#### UNIT 2 EMBEDDED NETWORKING OF INSTRUMENT CLUSTER

9

Embedded Networking: Introduction – Cluster of Instruments in System- Comparison of bus protocols – RS 232C- embedded ethernet - MOD bus and CAN bus, LIN BUS- Introduction to WSN-- Commercially available sensor nodes-Zigbee protocol -Network Topology Energy efficient MAC protocols –SMAC –Data Centric routing Applications of sensor networks- Database perspective on sensor networks- IoT Applications .

### **UNIT 3 AUTOMATION OF SUBSTATION**

q

Substation automation- Distribution SCADA system principles -role of PMU,RTU, IEDs, BUS for smart Substation automation- Introduction to Role of IEC 61850,IEEEC37.118 std- Interoperability and IEC 61850-challenges of Substations in Smart Grid - challenges of Energy Storage and Distribution Systems monitoring - Communication Challenges in monitoring electric utility asset .

### **UNIT 4 METERING OF SMART GRID**

9

Characteristics of Smart Grid- Generation by Renewable Energy Sources based on solar grid Challenges in Smart Grid and Microgrids- electrical measurements with AMI -Smart meters for EV plug in electric vehicles power management -Home Area Netmetering and Demand side Energy Management applications..

#### **UNIT 5 SMART METERS FOR PQ MONITORING**

9

Power Quality issues of Grid connected Renewable Energy Sources -Smart meters for Power Quality monitoring and Control - Power Quality issues -Surges - Flicker - Interharmonics - Transients - Power Quality Benchmarking - Power Quality Meters- Meter data management In Smart Grid-, communication enabled Power Quality metering

**TOTAL PERIODS** 

45





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	Course Outcomes
At the e	nd of the course, the student will be able to
CO1	Demonstrate criteria of choice of sensors, components to build meters.
CO2	Illustrate the demand for BUS communication protocols are introduced
CO3	Analyse the need and standards in Substation automation
CO4	Deployment of PAN for metering networked commercial applications
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded networked communications

- 1. Control and automation of electrical power distribution systems, James Northcote-Green, Robert Wilson, CRC, Taylor and Francis, 2006
- 2. Krzysztof Iniewski, "Smart Grid ,Infrastructure & Networking", TMcGH, 2012
- 3. Robert Faludi,"Building Wireless Sensor Networks, O'Reilly, 2011
- 4. Mohammad Ilyas And Imad Mahgoub, 'Handbook of sensor Networks: Compact wireless and wired sensing systems', CRC Press,2005
- 5. Shih-Lin Wu, Yu-Chee Tseng, {"Wireless Ad Hoc Networking, PAN, LAN, SAN, Aurebach Pub, 2012
- 6. Sanjay Gupta, "Virtual Instrumentation, LABVIEW", TMH, New Delhi, 2003
- 7. Ernest O. Doeblin and Dhanesh N Manik, "Measrement Systems Application and Design", 5th Edn, TMH, 2007.
- 8. BhaskarKrishnamachari, 'Networking wireless sensors', Cambridge press 2005

	(3/2/1 indicates the Program Outcome	CO/PO, I e strength of es (POs) and	<b>PSO Mapping</b> correlation) 3-Stror Program Specific C	ng 2-Mediur Outcomes (I	m, 1-Weak) PSOs')	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	1	2	1	2	1
CO2	1	-	2	2	3	1
CO3	3	1	2	-	-	-
CO4	2	-	2	3	3	2
CO5	2	1	2	-	-	3
Avg.	2.2	1	2	2	2.66	1.25





		L	Т	Р	C
P24EM122	SMART SYSTEM DESIGN	3	0	0	3
	Course Objectives				
1	To understand about the smart system technologies and its role in real time a	ppli	cat	ions	;
2	To expose students to different open-source platforms and attributes.				
3	To teach the architecture and requirements of Home Automation.				
4	To provide an insight into smart appliances and energy management concepts	S.			
5	To familiarize the design and development of embedded system based system	n de	sig	jn.	
UNIT 1 INTRO	DDUCTION			9	
Need & Types	s and Actuators – Communication protocols used in smart systems – Data Anal s – Open-source Analytics Platform for embedded systems (IFTTT &Thingspeak ontrollers - Embedded system for Smart card design and development – Recen	κ) –	-		
		Lue	ma		
UNIT II HOME	AUTOMATION			s. <b>9</b>	
UNIT II HOME Home Automa Data Security Real-Time imp	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Desi olementation.	atio	n,	9	
UNIT II HOME Home Automa Data Security Real-Time imp	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Desi	atio	n,	9	
Home Automa Data Security Real-Time imp UNIT III SMAI Energy Mana appliances in Smart Meters	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Desi olementation.	atio ign e of	on, and	9 9 nart ent -	
Home Automa Data Security Real-Time imp UNIT III SMAI Energy Mana appliances in Smart Meters Embedded A	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Design Elementation.  RT APPLIANCES AND ENERGY MANAGEMENT  gement: Demand-side Load Management: Energy scheduling – Significance energy management - Embedded and Integrated Platforms for Energy Management: Significance, Architecture & Energy Measurement Technique - Smart Network	atio ign e of	on, and	9 9 nart ent -	
Home Automate Data Security Real-Time impunit III SMAI Energy Manate Appliances in Smart Meters Embedded Apunit IV SMAI Application of Selection of becommunication	E AUTOMATION  ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Designation.  RT APPLIANCES AND ENERGY MANAGEMENT  gement: Demand-side Load Management: Energy scheduling – Significance energy management - Embedded and Integrated Platforms for Energy Management: Significance, Architecture & Energy Measurement Technique - Smart Netwood	eationign e of age	on, and smeme	9 nartent -	
Home Automathome Automathome Automathome Automathome Automathome Including I	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Designementation.  RT APPLIANCES AND ENERGY MANAGEMENT  gement: Demand-side Load Management: Energy scheduling – Significance energy management - Embedded and Integrated Platforms for Energy Managements: Significance, Architecture & Energy Measurement Technique - Smart Network popularity Considerations.  RTWEARABLE DEVICES  Smart Wearables in Healthcare & Activity Monitoring - Functional requirements ody sensors, Hardware platform, OS and Software platform – Selection of suitan protocol. Case Study: Design of a wearable, collecting heart-beat, temperature	eationign e of age	on, and smeme	9 nartent -	
Home Automate Data Security Real-Time important III SMAI Energy Manate appliances in Smart Meters Embedded Application of Selection of	ation – Design Considerations: Control Unit, Sensing Requirements, Communic - System Architecture - Essential Components - Linux and Raspberry Pi – Designementation.  RT APPLIANCES AND ENERGY MANAGEMENT  gement: Demand-side Load Management: Energy scheduling – Significance energy management - Embedded and Integrated Platforms for Energy Manageriance, Architecture & Energy Measurement Technique - Smart Network populances – Security Considerations.  RTWEARABLE DEVICES  Smart Wearables in Healthcare & Activity Monitoring - Functional requirements ody sensors, Hardware platform, OS and Software platform – Selection of suitan protocol. Case Study: Design of a wearable, collecting heart-beat, temperatural alth status using a smartphone application.	eationign e of age	on, and sme sme	9 9 nart ent - or	





(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

	Course Outcomes
At the	e end of the course, the student will be able to
CO1	Understand the concepts of smart system design and its present developments.
CO2	Illustrate different embedded open-source and cost-effective techniques for developing solution for real time applications.
CO3	Acquire knowledge on different platforms and Infrastructure for Smart system design.
CO4	Infer about smart appliances and energy management concepts.
CO5	Apply and improve Employability and entrepreneurship capacity due to knowledge upgradation on embedded system technologies.

- 1. Thomas Bräunl, Embedded Robotics, Springer, 2003.
- 2. Grimm, Christoph, Neumann, Peter, Mahlknech and Stefan, Embedded Systems for Smart Appliances and Energy Management, Springer 2013.
- 3. Raj Kamal, Embedded Systems Architecture, Programming and Design, McGraw- Hill, 2008
- 4. NilanjanDey, Amartya Mukherjee, Embedded Systems and Robotics with Open-Source Tools, CRC press, 2016.
- 5. Karim Yaghmour, Embedded Android, O'Reilly, 2013.
- 6. Steven Goodwin, Smart Home Automation with Linux and Raspberry Pi, Apress, 2013
- 7. C.K.Toh, AdHoc mobile wireless networks, Prentice Hall, Inc, 2002.
- 8. KazemSohraby, Daniel Minoli and TaiebZnati, Wireless Sensor Networks Technology,Protocols, and Applications, John Wiley & Sons, 2007.
- 9. Anna Ha'c, Wireless Sensor Network Designs, John Wiley & Sons Ltd, 2003.
- 10. Robert Faludi, Wireless Sensor Networks, O'Reilly, 2011.

		I indicates the s ogram Outcome	strength of corre			
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	3	2	-	-	-
CO2	2	-	-	-	2	3
CO3	-	-	-	2	3	Tal
CO4	-	-	-	-	COETAN	MENT
CO5	-	-	-	-	APPRO	VED BY
AVG	2	3	2	2	2.5 / JA	N 2025 <sub>8</sub>



		1	т	Р	С
P24EM123 EMBEDDED COMPUTING L					
	Course Objectives	<u> </u>	0	0	3
	·				
1	To expose the students to the fundamentals of Network communication technology	ogi	ies.		
2	To teach the fundamentals of Java , Internet and Java card				
3	To develop distributed embedded system with Java				
4	To teach the smart card and Apps development				
5	To involve Discussions/ Practice in familiarizing the concepts acquired over the the subject for improved employability skills.	5 l	Unit	s o	f
UNIT 1 NETW	ORK INFRASTRUCTURE			9	
Network diag	Transmission facilities —Open Interconnection standards — networking or am —Network management — Network Security — Cluster computers.	101			
IIAIIT II IAV/A	TECHNOLOGY FOR EMPERRED SYSTEMS				
UNII II JAVA	TECHNOLOGY FOR EMBEDDED SYSTEMS			9	
Basic concep  – distributed	ots of Java - IO streaming – Object serialization – Networking – Threading databases — Advantages and limitations of Internet – Web architect ystems – security model for embedded systems.		RM	11	
Basic concep – distributed embedded s	ots of Java - IO streaming – Object serialization – Networking – Threading databases — Advantages and limitations of Internet – Web architect		RM e fo	11	
Basic conceptus distributed embedded structured unit iii SMAI Smart Card components	ots of Java - IO streaming – Object serialization – Networking – Threading databases — Advantages and limitations of Internet – Web architect ystems – security model for embedded systems.	ure	RM e fo	11 or 9	
Basic conceptus distributed embedded sy UNIT III SMAI Smart Card components Operating Sy	ots of Java - IO streaming – Object serialization – Networking – Threading databases — Advantages and limitations of Internet – Web architect systems – security model for embedded systems.  RT CARD TECHNIQUES  basics – Java card technology overview – Java card Types - SMART CARD MICROCONTROLLERS - Contactless Cards - Smart	ure	RM e fo Car Car	11 or 9	
Basic conception of the concep	ots of Java - IO streaming — Object serialization — Networking — Threading databases — Advantages and limitations of Internet — Web architect systems — security model for embedded systems.  RT CARD TECHNIQUES  basics — Java card technology overview — Java card Types — SMART CARD MICROCONTROLLERS — Contactless Cards — Smart stems— smart card Security Techniques.	ure	RM e fo	9 dd	oid
Basic conception of the concep	ots of Java - IO streaming — Object serialization — Networking — Threading databases — Advantages and limitations of Internet — Web architect systems — security model for embedded systems.  RT CARD TECHNIQUES  basics — Java card technology overview — Java card Types — SMART CARD MICROCONTROLLERS — Contactless Cards — Smart stems— smart card Security Techniques.  ROID FRAMEWORK  — Access to Hardware - Framework development - Peer-to-Peer communications.	ure	RM e fo	9 dd	oid
Basic conceptuding and components Operating Syunit IV ANDIA Android SDK security designations.	ots of Java - IO streaming — Object serialization — Networking — Threading databases — Advantages and limitations of Internet — Web architect systems — security model for embedded systems.  RT CARD TECHNIQUES  basics — Java card technology overview — Java card Types — SMART CARD MICROCONTROLLERS — Contactless Cards — Smart stems— smart card Security Techniques.  ROID FRAMEWORK  — Access to Hardware — Framework development — Peer-to-Peer communication and architecture — Case study.  ELOPINGDISTRIBUTEDREAL-TIMESYSTEMAPPLICATIONS  ATLAB Real-Time Targets — Using the xPC Target — Building various Distributed	ure	RM e fo	9 d d	oid





(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

	Course Outcomes						
At the	t the end of the course, the student will be able to						
CO1	Deliver insight into involving JAVA concepts&internet based Communication to establish decentralized control mechanism of system						
CO2	Interpret the software and hardware architecture for distributed computing						
CO3	Develop solution for smart card						
CO4	Develop Apps based on android SDK.						
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded system computing environment.						

- 1. AmitavaGupta, Anil Kumar Chandra and Peter Luksch "Real-Time and Distributed Real-Time Systems Theory and Applications" CRC Press 2016 International Standard Book Number-13: 978-1-4665-9849-2 (eBook PDF)
- 2. Wolfgang Rankl and Wolfgang Effing "Smart Card Handbook" John Wiley & Sons Ltd,Third Edition,2003
- 3. Reto Meier "Professional Android application development" Wiley Publishing, Inc, 2009.
- 4. Joshua " Android hacker's Handbook" John Wiley & sons , 2014
- 5. Dietel&Dietel, "JAVA how to program", Prentice Hall 1999.
- 6. SapeMullender, "Distributed Systems", Addison-Wesley, 1993

			strength of corre	O Mapping elation) 3-Stron rogram Specific		
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	2	-	1	-	2	2
CO2	2	3	2	-	-	-
CO3	3	1	2	3	2	3
CO4	3	1	2	3	2	3
CO5	2	1	2	-	-	3
AVG	2.4	1.5	1.8	3	2	2.25





P24EM124	EMBEDDED SYSTEMS SECURITY	L	-+	P C
-		3	0	0   3
1	Course Objectives  To introduce the fundamentals related to Cryptography and Data Security			
	To teach the mathematical foundations for Cryptography.			
2	j. c , j	+	. I a	
3	To impart knowledge about Embedded Cryptography and Data Protection Pro		DIS	
4	To make them understand the practical aspects of Embedded System Securit			
5	To involve the students in Discussions/Tutorials/Programming to familiarize the for improved employability skills.	ne c	onc	epts
UNIT 1 BACK	GROUND AND INTRODUCTION			9
Architecture of Security De Introduction to Modular Arithmetics	d Network Security Concepts: Computer Security Concepts – The Concepts – Security Attacks – Security Services – Security Mechanisms – Foreign Principles – Attack Surfaces and Attack Trees – A Model for Netwon Number Theory: Divisibility and the Division Algorithm – The Euclidean metric – Prime Numbers – Fermet's and Euler's Theorems – Testing for Remainder Theorem – Discrete Logarithms.	und ork Al	ame Se gori	entals curity hm –
UNIT II SYMN	METRIC CIPHERS			9
Cipher Structu Encryption Sta	Block Ciphers and the Data Encryption Standard (DES): Traditional re – The Data Encryption Standard – A DES Example – Strength of DES. Advandard: Finite Field Arithmetic – AES Structure – AES Transformation.	ance	ed	ctions
UNIT III EMBI	EDDED SYSTEMS SECURITY			9
Considerations Embedded O	ecurity Trends – Security Policies – Security Threats. System Software s: The Role of Operating System – Microkernel versus Monolithic – S Security Requirements – Access Control and Capabilities – Hypenalization – I/O Virtualization – Remote Management – Assuring Integrity of the	viso	rs	
UNIT IV EMB	EDDED CRYPTOGRAPHY AND DATA PROTECTION PROTOCOLS			9
Key Cryptogra Cryptography Generation – Protection Pro	Pad – Cryptographic Modes – Block Ciphers – Authenticated Encryption phy – Key Agreement – Public Key Authentication – Elliptic Curve – Cryptographic Hashes – Message Authentication Codes – Randon Key Management for Embedded Systems – Cryptographic Certifications blocols for Embedded Systems: Data-in-Motion Protocols – Data-at-Resplications: Embedded Network Transactions – Automotive Security – Secured	e n N st F	lum Dat Prote	ber a ocols.
UNIT V PRAC	CTICAL EMBEDDED SYSTEM SECURITY			9
The Secured Client/Server F	munications Protocols and Built-in Security – Security Protocols and Algo Socket Layer – Embedded Security – Wireless – Application-Layer Protocols – Choosing and Optimizing Cryptographic Algorithms for Resou Systems – Hardward Based Security	an	ā.√	167

TOTAL PERIODS 45



(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

	Course Outcomes					
At the	at the end of the course, the student will be able to					
CO1	Explain the significance of Security.					
CO2	Understand the major concepts and techniques related to Cryptography.					
CO3	Demonstrate thorough knowledge about the aspects of Embedded System Security.					
CO4	Delivers insight onto role of Security Aspects during Data Transfer and Communication.					
CO5	Applying the Security Algorithms for Real-time Applications.					

- 1. "Cryptography and Network Security Principles and Practice", 7<sup>th</sup> Edition Global Edition, William Stallings, Pearson Education Limited, 2017.
- 2. "Embedded Systems Security Practical Methods for Safe and Secure Software and Systems Development", David Kleidermacher and Mike Kleidermacher, Newnes (an imprint of Elsevier), 2012.
- 3. "Practical Embedded Security Building Secure Resource-Constrained Systems", Timothy Stapko, Newnes (an imprint of Elsevier), 2008.

			CO/PO, PS strength of corre es (POs) and P			
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	1	-	1	1	1
CO2	3	2	2	-	3	2
CO3	1	3	-	1	1	3
CO4	3	1	2	-	3	1
CO5	3	2	3	2	3	2
AVG	2.2	1.8	2.33	1.33	2.2	1.8





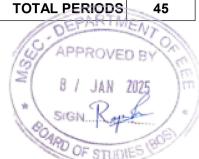
robots.

# Meenakshi Sundararajan Engineering College

(An Autonomous Institution, Affiliated to Anna University, Chennai) Department: Electrical and Electronics Engineering, R2024, CBCS M.E. Embedded System Technologies

P24EM125	ROBOTICS AND AUTOMATION	L	Т	Р	С
		3	0	0	3
	Course Objectives				
1	To teach the need of embedded system technology for robot building				
2	To study the Various Parts of Robots and Fields of Robotics.				
3	To study the Various Kinematics and Inverse Kinematics of Robots.				
4	To study the Trajectory Planning for Robot.				
5	To study the Control of Robots for Some Specific Applications.				
UNIT 1 INTRO	DDUCTION TO ROBOTICS & AUTOMATION			9	
Criteria for Sel trends.	rations of Robots - Asimov's Laws Of Robotics – Key components of a robot - lection of a Robot – Role of embedded system in Robotics and Automation - F			9	
torque, friction Ratio – Varial Optical, Acous	eumatic And Electric Drive Systems – Understanding how motor power, co-efficient affect the design of a Robot - Determination of Motor HP at DIE Speed Arrangements. Sensors – Classification based on sensing type stic, Magnetic) - Proximity Sensors – Ranging Sensors – Speed & Displastile Sensors – Vision Sensing - Smart Sensors - MEMS sensors.	nd (ir	Ge nclu	arin ding	
UNIT III MAN	IIPULATORS AND GRIPPERS			9	
Manipulators	o Manipulators - Joints and Degrees of Freedom - Construction of - Manipulator Dynamics And Force Control - Electronic And Pneumatic ts - End Effectors - Various Types Of Grippers - Design Considerations.	Maı	nipu	lato	or
UNIT IV KINE	MATICS AND PATH PLANNING			9	
<ul> <li>Jacobian ba</li> </ul>	uations – Forward and Inverse Kinematics - Solution Of Inverse Kinemati used Velocity Kinematics– Various Path Planning Algorithms – Hill Climbir Robot Operating System - Simulation and modeling of a simple Path Planning	ng			
UNIT V CASE	STUDIES			9	
	sign - Humanoid Robot - Robots in healthcare applications – Robot Machine In Inufacturing and Non-Manufacturing Applications - Self balancing robots -				10

**TOTAL PERIODS** 





(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

	Course Outcomes						
At the	end of the course, the student will be able to						
CO1	Choose suitable embedded boards for robots						
CO2	Demonstrate the concepts of robotics & automation and Working of Robot						
СОЗ	Analyze the Function of Sensors and actuators In the Robot						
CO4	Develop Program to Use a Robot for a Typical Application						
CO5	Apply and improve Employability and entrepreneurship capacity due to knowledge upgradation on Embedded system based robot development						

- 1. Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., "Industrial Robotics", Mc Graw-Hill Singapore, 1996.
- 2. Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied Publishers, Chennai, 1998.
- 3 .Deb. S.R., "Robotics Technology And Flexible Automation", John Wiley, USA 1992.
- 4. Klafter R.D., Chimielewski T.A., Negin M., "Robotic Engineering An Integrated Approach", Prentice Hall of India, New Delhi, 1994.
- 5. Mc Kerrow P.J. "Introduction to Robotics", Addison Wesley, USA, 1991.
- 6. Issac Asimov "Robot", Ballantine Books, New York, 1986.
- 7 .Barry Leatham Jones, "Elements of Industrial Robotics" PITMAN Publishing, 1987.
- 8. MikellP.Groover, Mitchell Weiss, Roger N.Nagel Nicholas G.Odrey, "Industrial Robotics Technology, Programming And Applications", McGraw Hill Book Company 1986.
- 9. Fu K.S. Gonzaleaz R.C. And Lee C.S.G. "Robotics Control Sensing, Vision and Intelligence" McGraw Hill International Editions, 1987

			strength of corre		ng 2-Medium, 1- ic Outcomes PS	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	2	-	3	-	-
CO2	-	3	-	-	-	-
CO3	-	-	-	-	DAD	TAL
CO4	-	-	-	2	S APPRO	INTENT OF
CO5	-	-	2	1	W -	AFD BA
AVG	1	2.5	2	2	* SIRN K	N 20252



mobile robot- Crypto-processor.

# Meenakshi Sundararajan Engineering College

(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

		, ,				
P24EM126	RECONFIGURABLE PROCESSOR AND SoC DESIGN	L 3	T 0	P 0	<b>C</b>	
Course Objectives						
1	To familiarize the need and role of Reconfigurable Processor for embedded sapplications.	yste	m			
2	To introduce the Reconfigurable Processor technologies					
3	To teach the salient features and architecture of FPGA.					
4	To provide an insight and architecture significance of SoC.					
5	To impart the knowledge of Reconfigurable embedded Processor for real time	• ap	plica	atio	ns.	
UNIT 1 INTR	ODUCTION			9		
FPGA Progra	A TECHNOLOGIES  mming technology - Alternative FPGA architectures: MUX Vs LUT based  AB Vs Slices- Fast carry chains- Embedded RAMs- Routing for FPGAs		_			
	or Low-Power FPGAs- Physical Design.					
UNIT III FPG	A ARCHITECTURE			9		
design- Desig	cture overview- Challenges of FPGA processor design-Opportunities of FPGA ning SoftCore Processors – Designing Hardcore Processors –hardware/s GA to multi core embedded computing- FPGA based on-board computer	oftw	/are	СО	1	
UNIT IV REC	ONFIGURABLE SOC PROCESSORS			9		
	–Architecture and applications of Virtex II pro ,Zynq-7000, Excalibur, Cyclo Multicore SoCs.	ne \	<b>/</b>	A7,		
UNIT V REC	ONFIGURABLE PROCESSOR AND SOC APPLICATIONS			9		
High Speed	e processor based DC motor control- digital filter design- mobile phone Data Acquisition -Image Processing application-controller implementati			me	nt-	

TOTAL PERIODS

45

APPROVED BY

8 / JAN 2025

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(An Autonomous Institution, Affiliated to Anna University, Chennai)
Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

	Course Outcomes
At the	end of the course, the student will be able to
CO1	Illustrate the need of reconfigurable computing and hardware-software co design
CO2	Demonstrate the significance of FPGA technology
CO3	Apply the concept of FPGA technology and understand FPGA architectures
CO4	Interpret the operation of SoC processor.
CO5	Relate and improve Employability and entrepreneurship capacity due to knowledge up-gradation on reconfigurable computing and SoC design.

- 1. Nurmi, Jari (Ed.) "Processor Design System-On-Chip Computing for ASICs and FPGAs" Springer, 2007.
- 2. Ian Grout, "Digital system design with FPGAs and CPLDs" Elsevier, 2008 Joao Cardoso, Michael Hübner, "Reconfigurable Computing: From FPGAs to Hardware/Software Codesign" Springer, 2011.
- 3 Ron Sass and AnderewG.Schmidt, "Embedded System design with platform FPGAs: Principles and Practices", Elsevier, 2010.
- 4. Steve Kilts, "Advanced FPGA Design: Architecture, Implementation, and Optimization" Willey, 2007
- 5. Pierre-Emmanuel Gaillardon, Reconfigurable Logic: Architecture, Tools, and Applications, 1st Edition, CRC Press , 2015

			CO/PO, PS strength of corre es (POs) and P			
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	-	-	-	-	-
CO2	-	2	3	-	-	-
CO3	-	-	2	1	2	-
CO4	-	1	3	-	-	-
CO5	-	-	-	-	-	3
AVG	0	1.5	2.66	1	2	3





			_	
P24EM127	MEMS and NEMS TECHNOLOGY	<u>Г</u>	T 0	P (
	Course Objectives			
	To introduce the diverse technological and functional approaches of MEMS/NI	<u> </u>	S an	
1	applications.	LIVIS	o an	.u
2	To understand the microstructures and fabrication methods.			
3	To provide an insight of micro and nano sensors, actuators.			
4	To emphasis the need for NEMS techology.			
5	To update the ongoing trends and real time applications of MEMS and NEMS	tecl	hnol	ogy.
UNIT 1 INTR	RODUCTION TO MEMS and NEMS			9
technologies,	Laws of scaling- Survey of materials- Smart Sensors-Applications of MEMS at	ndľ	$N \vdash N$	
	O-MACHINING AND MICROFABRICATION TECHNIQUES			9
Photolithograp				9
Photolithograp surface micro	O-MACHINING AND MICROFABRICATION TECHNIQUES  ohy- Film deposition, Etching Processes- wafer bonding- Bulk micro mach			9
Photolithograpsurface micro  UNIT III MICF  Transduction	co-MACHINING AND MICROFABRICATION TECHNIQUES  Chy- Film deposition, Etching Processes- wafer bonding- Bulk micro machining- LIGA process.	ninin	ıg, s	9 silico
Photolithograph surface micro  UNIT III MICF  Transduction , piezoresistiv	O-MACHINING AND MICROFABRICATION TECHNIQUES  Ohy- Film deposition, Etching Processes- wafer bonding- Bulk micro mach machining- LIGA process.  RO SENSORS AND MICRO ACTUATORS  mechanisms in different energy domain- Micromachined capacitive, F	ninin	ıg, s	9 silico
Photolithograpsurface micro  UNIT III MICF  Transduction, piezoresistiv  UNIT IV NEM  Atomic scale	co-MACHINING AND MICROFABRICATION TECHNIQUES  chy- Film deposition, Etching Processes- wafer bonding- Bulk micro mach machining- LIGA process.  RO SENSORS AND MICRO ACTUATORS  mechanisms in different energy domain- Micromachined capacitive, Fe and Electromechanical and thermal sensors/actuators and applications	Piez	og, s	9 silico 9 ectric
Photolithograpsurface micro  UNIT III MICF  Transduction, piezoresistiv  UNIT IV NEW  Atomic scale sensing, actua	CO-MACHINING AND MICROFABRICATION TECHNIQUES  Ohy- Film deposition, Etching Processes- wafer bonding- Bulk micro mach machining- LIGA process.  RO SENSORS AND MICRO ACTUATORS  mechanisms in different energy domain- Micromachined capacitive, Fe and Electromechanical and thermal sensors/actuators and applications  IS TECHNOLOGY  precision engineering- Nano Fabrication techniques - NEMS in measured	Piez	og, s	9 silico 9 ectric
Photolithograpsurface micro  UNIT III MICE  Transduction, piezoresistiv  UNIT IV NEM  Atomic scale sensing, actua  UNIT V MEM  Introduction t	CO-MACHINING AND MICROFABRICATION TECHNIQUES  Ohy- Film deposition, Etching Processes- wafer bonding- Bulk micro machining- LIGA process.  RO SENSORS AND MICRO ACTUATORS  mechanisms in different energy domain- Micromachined capacitive, Fe and Electromechanical and thermal sensors/actuators and applications  IS TECHNOLOGY  precision engineering- Nano Fabrication techniques - NEMS in measuredation and systems design.	ninin	oele	9 9 ectric





(An Autonomous Institution, Affiliated to Anna University, Chennai)
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M.E. Embedded System Technologies

	Course Outcomes
At the	end of the course, the student will be able to
CO1	Explain the material properties and the significance of MEMS and NEMS for industrial automation.
CO2	Demonstrate knowledge delivery on micromachining and micro fabrication.
СОЗ	Apply the fabrication mechanism for MEMS sensor and actuators.
CO4	Apply the concepts of MEMS and NEMS to models ,simulate and process the sensors and actuators.
CO5	Improved Employability and entrepreneurship capacity due to knowledge up gradation on MEMS and NEMS technology.

- 1. Chang Liu, "Foundations of MEMS", Pearson International Edition, 2006.
- 2. Marc F madou" Fundamentals of micro fabrication" CRC Press 2002 2nd Edition Marc Madou.
- 3. M.H.Bao "Micromechanical transducers :Pressure sensors, accelerometers and gyroscopes",Elsevier, Newyork, 2000.
- 4. Maluf, Nadim "An introduction to Micro Electro-mechanical Systems Engineering "AR Tech house, Boston 2000.
- 5. Mohamed Gad el Hak "MEMS Handbook" Edited CRC Press 2002 2. Sabriesolomon "Sensors Handbook", Mc Graw Hill 1998.
- 6. Tai-.Ran Hsu, "MEMS and Microsystems: design , manufacture, and Nanoscale"- 2nd Edition, John Wiley & Sons, Inc., Hoboken, New Jersey, 2008
- 7. Lyshevski, S.E. "Nano- and Micro-Electromechanical Systems: Fundamentals of Nano-and Microengineering" (2nd ed.). CRC Press, 2005.

			strength of corre		ng 2-Medium, 1 c Outcomes PS	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	2	3	-	2	-
CO2	3	3	2	-	2	2
CO3	3	3	3	-	2	2
CO4	3	3	3	-	3	2
CO5	3	2	3	2	APPRO	WED DAY
AVG	3	2.6	2.8	2	2.4	2.25



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	W.L. Linbedded System recimologies				
P24EM128	ENTREPRENEURSHIP AND EMBEDDED PRODUCT DEVELOPMENT	L		Р	С
		3	0	0	3
	Course Objectives				
1	To develop an understanding on business promotion process.				
2	To expose students on the skills required for success in business.				
3	To impart embedded system technology based entrepreneurship. Architecture	Э			
4	Creative thinking in developing automation into consumer products of market	valı	ıe		
5	Developing an embedded product with hardware-software components.				
UNIT 1 INTRO	DDUCTION TO ENTREPRENEURSHIP			9	
- establishing	al culture and structure -theories of entrepreneurship - entrepreneuric entrepreneurial systems - financial information and intelligence, rewards an -Role of industrial Fairs- challenges in entrepreneurship.				
UNIT II RESI	PONSIBILITIES IN ENTREPRENEURSHIP			9	
Licensing requincentives for	es and State Govt. Schemes -incentives to SSI -registration, Registration airements for sales tax, CST, Excise Duty -Power -Exploring export poss exports -import of capital goods and raw materials- Entrepreneurship de in India- Role and Improvement in Indian Economy.	ibilit	ties-	ent	
UNIT III CON	ICEPTS OF PRODUCT DEVELOPMENT			9	
Concept Gene concepts- Pro	uct Development Phases- Product Development Process Flows- Basic eration-Five Step Method- Creative thinking methods and problem solvin educt Architecture- component standardization —Bill of materi management- Portfolio Architecture- Benchmarking	g- d	desig		t
UNIT IV APP	ROACHES FOR NEW PRODUCT DEVELOPMENT			9	
Testing- Risk Engineering M	on- Industrial Design -Brainstorming Methods - SWOT Analysis-Concept Deve Management Process- Critical Path Analysis & PERT- Revers lethodology- need for Involving CAE, CAD, CAM tools -Prototype basic Prototyping Techniques - Planning for prototypes- Economic & Cost Analysis	e s -			
UNIT V SCOP	PE IN EMBEDDED SYSTEM FIELD			9	
development software and h field- case str	hip opportunities in Embedded system technologies - Embedded sy -Entrepreneurial skills for embedded system hardware and software nardware co-design and challenges; problems of entrepreneurship in Embedoudies: Mobile phone development- automation components-Washing madestem and devices- High Performance embedded computers- Industrial Control	arc ded : chin	hite syste e- F	ctu em	re,



45

**TOTAL PERIODS** 



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Course Outcomes
end of the course, the student will be able to
Analyze the internal/external factors affecting a business/organization to evaluate business opportunities.
Demonstrate extemporaneous speaking skills developed through in-class discussion of text materials, case study analyses, and current entrepreneurship-related issues.
Apply and Relate Key concepts underpinning entrepreneurship and its application in the recognition and exploitation of product/ service/ process opportunities.
Interpret various aspects of design such as industrial design, design of Consumer specific product, its Reverse Engineering manufacture ,economic analysis through
Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design.

- 1.Kuratko, Entrepreneurship: A Contemporary Approach, Thomson Learning, 2001.
- 2 Thomas Zimmerer et.al., Essentials of Entrepreneurship and small business Management 3rd Ed. Pearson Education, 2002.
- 3 Greene, Entrepreneurship: Ideas in Action, Thomson Learning, Mumbai, 2000
- 4 Jeffry Timmons, New Venture creation, McGraw Hill, 1999.
- 5 Gupta and Smivasan, Entrepreneurial Development, New Delhi, Sultan Chand, 1992
- 6 James K.peckol," Embedded Systems: A contemporary Design Tool", Wiley,2014.
- 7 Anita Goyal, Karl T Ulrich, Steven D Eppinger, "Product Design and Development", 4th Edition, 2009, Tata McGraw-Hill Education, ISBN-10-007-14679-9
- 8 George E.Dieter, Linda C.Schmidt, "Engineering Design", McGraw-Hill International Edition,4th Edition, 2009, ISBN 978-007-127189-9

			strength of corre		ig 2-Medium, 1- c Outcomes PS	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	2	-	-	-	3
CO2	3	3	-	-	-	-
CO3	3	3	-	-	_	1
CO4	3	3	-	1	COEPAR	IMENT
CO5	3	2	3	2	S APPRO	VED BY
AVG	3	2.6	3	1.5	* 3 / JA	N 2025 <sub>2</sub>



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P24EM129	EMBEDDED SYSTEM FOR BIOMEDICAL APPLICATIONS	L	-+	Р	С
		3	0	0	3
	Course Objectives				
1	To Introduce Fundamentals of Biomedical Engineering				
2	To understand the concept of wearable health devices				
3	To study the hardware for image processing applications				
4	To have a basic knowledge of Embedded system in diagnostic applications				
5	To study about the various assist devices used in the hospitals.				
UNIT 1 INTRO	ODUCTION TO BIOMEDICAL ENGINEERING			9	
	otential and its propagation- Resting and Action Potential – Bio signals charact - Types of transducers and applications-Bio-amplifiers- Types of recorderscomp stem.				
UNIT II WEA	RABLE HEALTH DEVICES			9	
glucose senso	rearable technology in health care-Components of wearable devices- Biosenson ors - Head worn- Hand worn- Body worn-pulse oxymeter- Cardiac pacemakers of cent advancements-wearable artificial kidney.				
UNIT III EMB	EDDED SYSTEM FOR MEDICAL IMAGE PROCESSING			9	
power consum	to embedded image processing . ASIC vs FPGA - memory require nption- parallelism - Design issues in VLSI implementation of Image procenterfacing. Hardware implementation of image processing algorithms: Segment	ess	ing	ıd	
UNIT IV EMB	EDDED SYSTEM FOR DIAGNOSTIC APPLICATIONS			9	
ICCU patient Sonography.	monitoring system – ECG-EEG-EMG acquisition system-MRI scanner - C	т	scar	nne	r-
UNIT V CASE	STUDY			9	
	measurement using spirometer- IPPB unit for monitoring respiratory Defibrillator- Glucometer-Heart- Lung machine.	pa	ram	ete	rs
	TOTAL PERIOR	วร		45	





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	Course Outcomes				
At the	t the end of the course, the student will be able to				
CO1	Demonstrate the fundamental art of biomedical engineering.				
CO2	Illustrate about wearable health devices and its importance.				
CO3	Implement image processing applications using software and hardware.				
CO4	Compare various embedded diagnostic applications.				
CO5	Build and analyze of some biomedical equipment.				

### **REFERENCES**

2.Leslie Cromwell, "Biomedical Instrumentation and Measurement", Prentice Hall of India, New Delhi, 2007.

3.John G.Webster, "Medical Instrumentation Application and Design", 3rd Edition, Wiley India Edition, 2007

Khandpur R.S, Handbook of Biomedical Instrumentation, Tata McGraw Hill, New Delhi, 3rd Edition, 2014.

4.L.A Geddes and L.E.Baker, Principles of Applied Biomedical Instrumentation, 3rd Edition, John Wiley and Sons, Reprint 2008.

5.Richard S.Cobbold, Transducers for Biomedical Measurements; Principle and applications- John Wiley and sons, 1992.

			strength of corre	O Mapping elation) 3-Stron rogram Specific		
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	2	3	-	-	-
CO2	-	3	2	3	-	-
CO3	-	-	2	-	3	3
CO4	3	1	1	-	2	2
CO5	1	3	3	-	-	-
AVG	1.66	2.25	2.2	3	2.5	2.5





D04E11406	DENEMARI E ENERGY AND CRIP INTEGRATION	L	Т	PC
P24EM130	RENEWABLE ENERGY AND GRID INTEGRATION	3	0	0 3
	Course Objectives			•
1	To provide knowledge about the stand alone and grid connected renewable e systems.	nerg	ĵУ	
2	To equip with required skills to derive the criteria for the design converters for renewable energy applications.	of	ро	wer
3	To analyse and comprehend the various operating modes of wind electrical gand solar energy systems.	jene	rato	rs
4	To design different power converters namely AC to DC, DC to DC and A converters for renewable energy systems.	C to	) A	С
5	To develop maximum power point tracking algorithms.			
UNIT 1 INTRO	DDUCTION			9
UNIT II PHOT Introduction, F characteristics PV system,	ers, three phase AC voltage controllers- AC-DC-AC converters, PWM Inverters-matrix converters.  O VOLTAIC ENERGY CONVERSION SYSTEMS  Photo Voltaic (PV) effect, Solar Cell, Types, Equivalent circuit of PV cell (I/V and P/V) for variation of insolation, temperature and shading effect Grid connected PV system, Design of PV system-load calculation, inverter/inverter, battery sizing.	, P\	√ ce	9 ell alone
UNIT III WIND	ENERGY CONVERSION SYSTEMS			9
Introduction, F control strateg Electrical mac Grid Connecte and Variable S	Power contained in wind, Efficiency limit in wind, types of wind turbines, ies, Power curve and Operating area, Types of wind generators system be nines-Induction Generator and Permanent Magnet Synchronous General description of Induction of Induction of PMSG.	asec rato	d on r(PN	/ISG),
Introduction, Fountrol strateg Electrical macl Grid Connecte and Variable S	Power contained in wind, Efficiency limit in wind, types of wind turbines, ies, Power curve and Operating area, Types of wind generators system be nines-Induction Generator and Permanent Magnet Synchronous Generator.	asec rato	d on r(PN	/ISG),
Introduction, Fountrol strateg Electrical mack Grid Connecte and Variable SUNIT IV MPP	Power contained in wind, Efficiency limit in wind, types of wind turbines, ies, Power curve and Operating area, Types of wind generators system be nines-Induction Generator and Permanent Magnet Synchronous General description of Induction of Induction of PMSG.	asec rato	d on r(PN	ISG), or
Introduction, Fountrol strateg Electrical mack Grid Connecte and Variable SUNIT IV MPP	Power contained in wind, Efficiency limit in wind, types of wind turbines, ies, Power curve and Operating area, Types of wind generators system be nines-Induction Generator and Permanent Magnet Synchronous General description of Induction Generator and Double output system, Self-excited operation of Induction Generator PMSG.  TECHNIQUES IN SOLAR AND WIND SYSTEMS	asec rato	d on r(PN	ISG), or
Introduction, Foontrol strateg Electrical macl Grid Connecte and Variable SUNIT IV MPP  Case studies of UNIT V HYBF Energy Storag	Power contained in wind, Efficiency limit in wind, types of wind turbines, ies, Power curve and Operating area, Types of wind generators system be nines-Induction Generator and Permanent Magnet Synchronous General description of Induction Generator and Double output system, Self-excited operation of Induction Generator PMSG.  TIECHNIQUES IN SOLAR AND WIND SYSTEMS  of PV-Maximum Power Point Tracking (MPPT) and Wind Energy system	ased rato Gend	d on r(PM erate	1SG) or 9

**TOTAL PERIODS** APPROVED BY



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	Course Outcomes								
At the	end of the course, the student will be able to								
CO1	Relate the power generation of different renewable energy sources to grid impact and grid codes								
CO2	Explain the design principles of solar energy management systems								
CO3	Understand the power conversion system of wind generators								
CO4	Analyze the different Maximum Power Point tracking Techniques								
CO5	Build grid connected and stand alone renewable energy management system								

- 1. S.N.Bhadra, D. Kastha, & S. Banerjee "Wind Electrical Systems", Oxford University Press, 2009.
- 2. Haitham Abu-Rub, Mariusz Malinowski and Kamal Al-Haddad, "Power Electronics for Renewable Energy Systems, Transportation and Industrial Applications", IEEE Press and John Wiley & Sons Ltd Press, 2014.
- 3. Rashid .M. H "power electronics Hand book", Academic press, 2001.
- 4. Rai. G.D, "Non-conventional energy sources", Khanna publishes, 1993
- 5. Gray, L. Johnson, "Wind energy system", prentice hall linc, 1995
- 6. Non-conventional Energy sources B.H.Khan Tata McGraw-hill Publishing Company, New Delhi

			strength of corre		ng 2-Medium, 1- c Outcomes PS	
	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	2	1	-	1	-
CO2	1	1	2	-	1	-
CO3	2	-	1	1	1	2
CO4	1	2	1	2	-	2
CO5	3	3	2	-	2 SEPAR	TMEAN
AVG	1.6	2	1.4	1.5	S 1.25 PPRO	VED BY



I ZTE WITO I	P24EM131 ELECTRIC VEHICLES AND POWER MANAGEMENT		T	Р				
	MANAGEMENT	3	1	0				
	Course Objectives							
1	To understand the concept of electric vehicles and its operations							
2	To present an overview of Electric Vehicle (EV), Hybrid Electric vehicle (HEV) architecture	) and	d the	eir				
3	o understand the need for energy storage in hybrid vehicles							
4	To provide knowledge about various possible energy storage technologies that can be used in electric vehicles							
5	To understand the concept of electric vehicles and its operations							
UNIT 1 ELEC	TRIC VEHICLES AND VEHICLE MECHANICS			12				
	ustion Engine vehicles- Fundamentals of vehicle mechanics.  HITECTURE OF EV's AND POWER TRAIN COMPONENTS			12				
Architecture o	f EV's and HEV's – Plug-n Hybrid Electric Vehicles (PHEV)- Power train comp							
	Clutches, Transmission and Brakes.	onei	nts a	and				
sizing, Gears,		onei	nts a	and 12				
sizing, Gears,  UNIT III POW  Electric drive Induction mo	Clutches, Transmission and Brakes.	C dr	ves	12				
sizing, Gears,  UNIT III POW  Electric drive Induction mo Switched reluc	Clutches, Transmission and Brakes.  VER ELECTRONICS AND MOTOR DRIVES  components – Power electronic switches- four quadrant operation of DC tor and permanent magnet synchronous motor-based vector control	C dr	ves	12				
sizing, Gears,  UNIT III POW  Electric drive Induction mo Switched reluct  UNIT IV BAT  Battery Basic	Clutches, Transmission and Brakes.  VER ELECTRONICS AND MOTOR DRIVES  components – Power electronic switches- four quadrant operation of DC tor and permanent magnet synchronous motor-based vector control ctance motor (SRM) drives- EV motor sizing.	c dr	ives ratio	12 				
sizing, Gears,  UNIT III POW  Electric drive Induction mo Switched reluct  UNIT IV BAT  Battery Basic modeling-Des	Clutches, Transmission and Brakes.  ZER ELECTRONICS AND MOTOR DRIVES  components — Power electronic switches- four quadrant operation of DC tor and permanent magnet synchronous motor-based vector control ctance motor (SRM) drives- EV motor sizing.  TERY ENERGY STORAGE SYSTEM  cs- Different types- Battery Parameters-Battery life & safety impacts	c dr	ives ratio	12 				
sizing, Gears,  UNIT III POW  Electric drive Induction mo Switched reluct  UNIT IV BAT  Battery Basic modeling-Des  UNIT V ALTE Introduction to	Clutches, Transmission and Brakes.  ZER ELECTRONICS AND MOTOR DRIVES  components — Power electronic switches- four quadrant operation of DC tor and permanent magnet synchronous motor-based vector control ctance motor (SRM) drives- EV motor sizing.  TERY ENERGY STORAGE SYSTEM  cs- Different types- Battery Parameters-Battery life & safety impacts ign of battery for large vehicles.	-Ba	ives ratio	12 				





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	Course Outcomes							
At the	At the end of the course, the student will be able to							
CO1	Understand the concept of electric vehicle and energy storage systems.							
CO2	Describe the working and components of Electric Vehicle and Hybrid Electric Vehicle							
CO3	Know the principles of power converters and electrical drives							
CO4	Illustrate the operation of storage systems such as battery and super capacitors							
CO5	Analyze the various energy storage systems based on fuel cells and hydrogen storage							

- 1.Iqbal Hussain, "Electric and Hybrid Vehicles: Design Fundamentals, Second Edition" CRC Press, Taylor & Francis Group, Second Edition (2011).
- 2. Ali Emadi, Mehrdad Ehsani, John M.Miller, "Vehicular Electric Power Systems", Special Indian Edition, Marcel dekker, Inc 2010.
- 3. Mehrdad Ehsani, YiminGao, Sebastian E. Gay, Ali Emadi, 'Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design', CRC Press, 2004.
- 4. C.C. Chan and K.T. Chau, 'Modern Electric Vehicle Technology', OXFORD University Press, 2001.
- **5.** Wie Liu, "Hybrid Electric Vehicle System Modeling and Control", Second Edition, John Wiley & Sons, 2017.

			CO/PO, PS strength of corre es (POs) and P							
	PO1									
CO1	3	3	3	2	3	2				
CO2	3	3	3	2	3	2				
CO3	3	3	3	2	3	2				
CO4	3	3	3	2	3	2				
CO5	3	3	3	2	3	2				
AVG	3	3	3	2	3	2				





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		.   1	-	Р	С
P24EM132	Course Objectives		)	0	3
	Course Objectives				
1	Students will understand and be able to use the basic programming principles stypes, variable, conditionals, loops, recursion and function calls.	uch	as	s da	ata
2	Students will learn how to use basic data structures such as List, Dictionary and manipulate text files and images.	d be	e a	ble	to
3	Students will understand and be able to use the basic programming principles such as data types, variable, conditionals, loops, recursion and function calls.  Students will learn how to use basic data structures such as List, Dictionary and be able to manipulate text files and images.  To make the students familiar with machine learning concepts & techniques.  Students will understand the process and will acquire skills necessary to effectively attempt a machine learning problem and implement it using Python.  To involve Discussions/ Practice/Exercise onto revising & familiarizing the concepts acquired over the 5 Units of the subject for improved research/employability skills  NIT 1 INTRODUCTION TO MACHINE LEARNING AND PYTHON  9  troduction to Machine Learning: Significance, Advantage and Applications — Categories of achine Learning — Basic Steps in Machine Learning: Raw Data Collection, Pre-processing, Training Model, Evaluation of Model, Performance Improvement				
To make the students familiar with machine learning concepts & techniques.  Students will understand the process and will acquire skills necessary to effectively attempt a machine learning problem and implement it using Python.  To involve Discussions/ Practice/Exercise onto revising & familiarizing the concepts acquired over the 5 Units of the subject for improved research/employability skills					
5			ts		
UNIT 1 INTRO	DUCTION TO MACHINE LEARNING AND PYTHON			9	
Machine Learn a Model, Evalu Introduction to Compiler and Syntax: Variate	ning – Basic Steps in Machine Learning: Raw Data Collection, Pre-processin	g, <sup>.</sup> ang nmi	Tra ua( ng	ges	s;
UNIT II PYTH	ON FUNCTIONS AND PACKAGES			9	
Modules – Pa Installing the Multi-Dimension	Reading and Writing Data – Errors and Exceptions Handling – Functions ackage Handling in Python – Pip Installation & Exploring Functions in python pactory and exploring various operations on Arrays: Indexing, and Arrays, Joining Numpy Arrays, Array intersection and Difference, Saving and Introduction to SciPy Package & its functions - Introduction to Object Country with Python	kag Slic d Lo	ing oac	l, ding	9
UNIT III IMPL	EMENTATION OF MACHINE LEARNING USING PYTHON			9	
Boston Housir	of Standard Datasets: Coco, ImageNet, MNIST (Handwritten Digits) Data ng Dataset – Introducing the concepts of Regression – Linear, Polynomial & Logi th analytical understanding - Introduction to SciPy Package & its functions	stic		/the	on

Regression with analytical understanding - Introduction to SciPy Package & its functions - Python Application of Linear Regression and Polynomial Regression using SciPy – Interpolation, Overfitting and

Underfitting concepts & examples using SciPy

### UNIT IV CLASSIFICATION AND CLUSTERING CONCEPTS OF ML

Introduction to ML Concepts of Clustering and Classification - Types of Classification Algorithms Support Vector Machines (SVM) - Decision Tree - Random Forest - Introduction to ML using scikit-learn - Using scikit-learn, Loading a sample dataset, Learning & prediction, interpolation & fitting, Multiclass fitting - Implementation of SVM using Blood Cancer Dataset, Decision Tree using data from csv.

Types of Clustering Algorithms & Techniques - K-means Algorithm, Mean Shift Algorithm & Hierarchical Clustering Algorithm - Introduction to Python Visualization using Matpiotlib: Plotting 2dimensional, 3-dimensional graphs; formatting axis values; plotting multiple rows of data in same graph - Implementation of K-means Algorithm and Mean Shift Algorithm using Python



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# UNIT V INTRODUCTION TO NEURAL NETWORKS AND EMBEDDED MACHINE LEARNING

9

Introduction to Neural Networks & Significance – Neural Network Architecture – Single Layer Perceptron & Multi-Layer Perceptron (MLP) – Commonly Used Activation Functions - Forward Propagation, Back Propagation, and Epochs – Gradient Descent – Introduction to Tensorflow and Keras ML Python packages – Implementation of MLP Neural Network on Iris Dataset – Introduction to Convolution Neural Networks – Implementation of Digit Classification using MNIST Dataset ML for Embedded Systems: Comparison with conventional ML – Challenges & Methods for Overcoming –TinyML and Tensorflow Lite for Microcontrollers – on-Board AI – ML Edge Devices: Arduino Nano BLE Sense, Google Edge TPU and Intel Movidius

TOTAL PERIODS

45

	Course Outcomes
At the	end of the course, the student will be able to
CO1	Develop skill in system administration and network programming by learning Python
CO2	Demonstrating understanding in concepts of Machine Learning and its implementation using Python
CO3	Relate to use Python's highly powerful processing capabilities for primitives, modelling etc
CO4	Improved Employability and entrepreneurship capacity due to knowledge up gradation on recent trends in embedded systems design
CO5	Apply the concepts acquired over the advanced research/employability skills

- 1. Mark Lutz,"LearningPython,Powerful OOPs,O'reilly,2011
- 2. Zelle, John "M. Python Programming: An Introduction to Computer Science.", Franklin Beedle& Associates, 2003
- 3. Andreas C. Müller, Sarah Guido, "Introduction to Machine Learning with Python", O'Reilly,2016
- 4. Sebastian Raschka ,VahidMirjalili, "Python Machine Learning Third Edition", Packt, December 2019





			strength of corre		g 2-Medium, 1- c Outcomes PS				
	PO1	PO1 PO2 PO3 PSO1 PSO2 PSO3							
CO1	-	-	2	3	3	-			
CO2	3	1	3	-	3	1			
CO3	2	1	2	-	3	3			
CO4	3	2	3	3	3	3			
CO5	-	-	-		3	-			
AVG	2.66	1.33	2.5	3	3	2.33			





	, ,				
P24EM133	SMART GRID	L 3	T 0	P 0	C 3
	Course Objectives	•		•	_
1	To Study about Smart Grid technologies, different smart meters a advanced metering infrastructure.	nd			
2	To know about the function of smart grid.				
3	To familiarize the power quality management issues in Smart Grid.		-		
4	To familiarize the high performance computing for Smart Grid applications				
5	To get familiarized with the communication networks for Smart Grid application	าร			
UNIT 1 INTRO	DDUCTION TO SMART GRID			9	
opportunities, o Micro grid and	ectric Grid, Concept, Definitions and Need for Smart Grid, Smart grid drivers, fuchallenges and benefits, Difference between conventional & Smart Grid, Compaded Smart grid, Present development & International policies in Smart Grid, ower Distribution Utility in India – Case Study.	ariso	on of	f	id
UNIT II SMAR	RT GRID TECHNOLOGIES			9	
monitoring, P Detection, Isola Transformers,	Feeder Automation ,Transmission systems: EMS, FACTS and HVDC, rotection and control, Distribution systems: DMS, Volt/Var control, Faation and service restoration, Outage management, High-Efficiency Diphase Shifting Transformers, Plug in Hybrid Electric Vehicles (PHEV) – Grid to charging concepts.	ult strib	utio	n	
UNIT III SMAI	RT METERS AND ADVANCED METERING INFRASTRUCTURE			9	
AMI protocols, Unit(PMU) & t	o Smart Meters, Advanced Metering infrastructure (AMI) drivers and standards and initiatives, AMI needs in the smart grid, Phasor Measure heir application for monitoring & protection. Demand side manageme onse programs, Demand pricing and Time of Use, Real Time Pricing, Peak Time	men nt	ıt and		
UNIT IV POW	ER QUALITY MANAGEMENT IN SMART GRID			9	
	& EMC in Smart Grid, Power Quality issues of Grid connected Renewals er Quality Conditioners for Smart Grid, Web based Power Quality monito				r
UNIT V HIGH	PERFORMANCE COMPUTING FOR SMART GRID APPLICATIONS			9	
Network (WAN	nd Standards -Local Area Network (LAN), House Area Network (HAN), V l), Broadband over Power line (BPL), PLC, Zigbee, GSM, IP based Protocols, E _OUD Computing, Cyber Security for Smart Grid.				eb
	TOTAL PERIO	DS		45	





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	Course Outcomes					
At the	At the end of the course, the student will be able to					
CO1	Relate with the smart resources, smart meters and other smart devices.					
CO2	Explain the function of Smart Grid.					
CO3	Experiment the issues of Power Quality in Smart Grid.					
CO4	Analyze the performance of Smart Grid.					
CO5	Recommend suitable communication networks for smart grid applications					

- 1. Stuart Borlase 'Smart Grid: Infrastructure, Technology and Solutions', CRC Press 2012.
- 2. Janaka Ekanayake, Nick Jenkins, KithsiriLiyanage, Jianzhong Wu, Akihiko Yokoyama, 'Smart Grid: Technology and Applications', Wiley, 2012.
- 3. Mini S.Thomas, John D McDonald, 'Power System SCADA and Smart Grids', CRC Press, 2015
- 4. Kenneth C.Budka, Jayant G. Deshpande, Marina Thottan, 'Communication Networks for Smart Grids', Springer, 2014
- 5. SMART GRID Fundamentals of Design and Analysis, James Momoh, IEEE press, A John Wiley & Sons, Inc., Publication.

			CO/PO, PS strength of corre es (POs) and P							
	PO1									
CO1	3	2	-	2	2	2				
CO2	3	-	2	2	-	2				
CO3	2	-	1	-	-	-				
CO4	1	-	-	3	3	1				
CO5	-	2	2	2	2	3				
AVG	2.25	2	1.66	2.25	2.3	2				





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D04E84604	ENCLISH FOR RESEARCH PARER WRITING			Р	С
P24EMA01	ENGLISH FOR RESEARCH PAPER WRITING		0	0	0
	Course Objectives		•		
1	Teach how to improve writing skills and level of readability.				
2	Tell about what to write in each section.				
3	Summarize the skills needed when writing a Title.				
4	Infer the skills needed when writing the Conclusion.				
5	Ensure the quality of paper at very first-time submission.				
UNIT 1 INTRODU	ICTION TO RESEARCH PAPER WRITING			6	
	paration, Word Order, Breaking up long sentences, Structuring Paragra Concise and Removing Redundancy, Avoiding Ambiguity and Vaguer		and		
UNIT 2 PRESENT	FATION SKILLS			6	
	d What, Highlighting Your Findings, Hedging and Criticizing, Paraphrasons of a Paper, Abstracts, Introduction.	sing a	and		
UNIT 3 TITLE WE	RITING SKILLS			6	
needed when writ	ded when writing a Title, key skills are needed when writing an Abstracting an Introduction, skills needed when writing a Review of the Literatur on, Conclusions, The Final Check.				
	WRITING SKILLS			6	
	when writing the Methods, skills needed when writing the Results, skill Discussion, skills are needed when writing the Conclusions.	ls are	nee	ded	
UNIT 5 VERIFICA	ATION SKILLS			6	
Useful phrases, c submission.	hecking Plagiarism, how to ensure paper is as good as it could possibl	y be	the fi	rst- ti	m
	TOTAL PERIO	ODS		30	
	Course Outcomes				
At the end of the	course, the student will be able to				
CO1	Understand that how to improve your writing skills and level of readab	ility .			
CO2	Learn about what to write in each section.				
CO3	Understand the skills needed when writing a Title.				
CO4	Understand the skills needed when writing the Conclusion .				
CO5	Ensure the good quality of paper at very first-time submission.				
REFERENCES					
1. Adrian Wallwor	k , English for Writing Research Papers, Springer New York Dordrecht	Hei	lelbe	rg	

- 2. Day R How to Write and Publish a Scientific Paper, Cambridge University Press 2006. ROVED P.
- 3. Goldbort R Writing for Science, Yale University Press (available on Google Books) 2006.
- 4. Highman N, Handbook of Writing for the Mathematical Sciences, SIAM. Highman's book 1998.

SOMED OF STUDIES



P24EMA02	DIGAGED HANAGEMENT	L	ТР		С
	DISASTER MANAGEMENT	2	0	0	0
Course Objectives					
1					
2	Explain a critical understanding of key concepts in disaster risk reduhumanitarian response.	iction a	and		
3	Illustrate disaster risk reduction and humanitarian response policy a multiple perspectives.	nd pra	ctic	e fro	m
4	Describe an understanding of standards of humanitarian response a relevance in specific types of disasters and conflict situations.	and pra	actio	cal	
5	Develop the strengths and weaknesses of disaster management ap	proach	nes		
UNIT 1 INTRODUC	CTION		6		
	, Factors and Significance; Difference between Hazard And Disaster; s: Difference, Nature, Types and Magnitude.	Natura	ıl ar	nd	
UNIT 2 REPERCU	SSIONS OF DISASTERS AND HAZARDS		6		
Earthquakes, Volca Avalanches, Man-r	, Loss of Human and Animal Life, Destruction Of Ecosystem. Natural lanisms, Cyclones, Tsunamis, Floods, Droughts And Famines, Landslid nade disaster: Nuclear Reactor Meltdown, Industrial Accidents, Oil Slidase And Epidemics, War And Conflicts.	des An	ıd		
UNIT 3 DISASTER	PRONE AREAS IN INDIA		6		
	ones; Areas Prone To Floods and Droughts, Landslides And Avalanch pastal Hazards with Special Reference To Tsunami; Post-Disaster Dis				ne
UNIT 4 DISASTER	PREPAREDNESS AND MANAGEMENT		6		
	nitoring Of Phenomena Triggering a Disaster or Hazard; Evaluation of I, Data from Meteorological And Other Agencies, Media Reports: Gove edness.				ion
UNIT 5 RISK ASS	ESSMENT		6		
Situation. Techniqu	cept and Elements, Disaster Risk Reduction, Global and National Disa les of Risk Assessment, Global Co-Operation in Risk Assessment and ion in Risk Assessment. Strategies for Survival			,	
	TOTAL PERIODS		3(	)	





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	Course Outcomes						
At the	At the end of the course, the student will be able to						
CO1	Ability to summarize basics of disaster						
CO2	Ability to explain a critical understanding of key concepts in disaster risk reduction and humanitarian response.						
CO3	Ability to illustrate disaster risk reduction and humanitarian response policy and practice from multiple perspectives.						
CO4	Ability to describe an understanding of standards of humanitarian response and practical relevance in specific types of disasters and conflict situations.						
CO5	Ability to develop the strengths and weaknesses of disaster management approaches						

- 1. Goel S. L., Disaster Administration And Management Text And Case Studies", Deep& Deep Publication Pvt. Ltd., New Delhi, 2009.
- 2. NishithaRai, Singh AK, "Disaster Management in India: Perspectives, issues and strategies "NewRoyal book Company,2007.
- 3. Sahni, PardeepEt.Al.," Disaster Mitigation Experiences And Reflections", Prentice Hall OfIndia, New Delhi,2001.





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			-	_	
P24EMA03	CONSTITUTION OF INDIA		Т 0	P 0	0 0
		U	-		
Students will	Course Objectives be able to:				
1	Understand the premises informing the twin themes of liberty and frights perspective.	eedor	n from	a civi	
2	To address the growth of Indian opinion regarding modern Indian in constitutional	itellec	tuals'		
3	Role and entitlement to civil and economic rights as well as the emethe early years of Indian nationalism.	ergeno	cenatio	n hoo	d in
4	To address the role of socialism in India after the commencement of Revolutionin1917and its impact on the initial drafting of the Indian C			vik	
UNIT 1 HISTO	RY OF MAKING OF THE INDIAN CONSTITUTION			6	
History, Draftin	g Committee, (Composition &Working)				
UNIT 2 PHILO	SOPHY OF THE INDIAN CONSTITUTION			6	
Preamble, Sali	ent Features				
UNIT 3 CONT	OURS OF CONSTITUTIONAL RIGHTS AND DUTIES			6	
	Rights, Right to Equality, Right to Freedom, Right against Exploitation ral and Educational Rights, Right to Constitutional Remedies, Directinental Duties.				
UNIT 4 ORGA	NS OF GOVERNANCE			6	
	emposition, Qualifications and Disqualifications, Powers and Function rernor, Council of Ministers, Judiciary, Appointment and Transfer of J unctions.				ons,
UNIT 5 LOCAL	_ ADMINISTRATION			6	
Elected Repres	nistration head: Role and Importance, □Municipalities: Introduction, Nesentative, CEO, Municipal Corporation. Pachayati raj: Introduction, Pes and their roles, CEO ZilaPachayat: Position and role. Block level: Cerent departments), Village level:Roleof Elected and Appointed officials.	RI: Zi Organi	laPach zation	nayat. al	grass
<b>UNIT 6 ELECT</b>	TION COMMISSION			6	
	nission: Role and Functioning. Chief Election Commissioner and Election the welfare of SC/ST/OBC and women.	ction (	Comm	ssione	ers -
	TOTAL PER	IODS		30	
	Course Outcomes				
Students will	be able to:	-E0	ARTI	ME	No.
CO1	Discuss the growth of the demand for civil rights in India for the bulk arrival of Gandhi in Indian politics.	of in		before	the
CO2	Discuss the intellectual origins of the framework of argument that in	-			11



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CO3	Discuss the circumstances surrounding the foundation of the Congress Socialist Party[CSP] under the leadership of Jawaharlal Nehru and the eventual failure of the proposal of direct elections through adult suffrage in the Indian Constitution.
CO4	Discuss the passage of the Hindu Code Bill of 1956.
SUGGESTE	D READING
1.The Const	itution of India,1950(Bare Act),Government Publication.
2. Dr.S.N.Bu	si, Dr.B.R.Ambedkar framing of Indian Constitution,1stEdition, 2015.
3. M.P. Jain,	Indian Constitution Law, 7thEdn., Lexis Nexis,2014.
4. D.D. Bası	, Introduction to the Constitution of India





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P24EMA04			Т	Р	С			
PZ4EIVIAU4	நற்றமிழ் இலக்கியம்	2	0	0	0			
	Course Objectives							
1	சங்க இலக்கியம் பற்றி மாணவர்களுக்கு எடுத்துரைத்	தல்.						
2	நீதி நூல்கள் வாயிலாக அறக்கருத்துகளை எடுத்து கூறு	<u>றத</u> ல்.						
3	சிலப்பதிகாரம், மணிமேகலை காப்பியங்களை எடுத்துரைத்தல்.							
4	இலக்கியங்களில் காணப்படும் அருள்நெறிக் கதைகளைப் பற்றி விளக்குதல்.							
5	தற்காலத் தமிழ் இலக்கியங்களை மாணவர்களுக்கு தெரியப்படுத்துதல்.							
UNIT 4 FFIF 6	NIT 4 Trius Conti Punio							

### UNIT 1 சங்க இலக்கியம்

6

- 1. தமிழின் துவக்க நூல் தொல்காப்பியம் எழுத்து, சொல், பொருள்.
- 2. அகநானூறு (82) இயற்கை இன்னிசை அரங்கம்.
- 3. குறிஞ்சிப் பாட்டின் மலர்க்காட்சி.
- 4. புறநானூறு (95, 195) போரை நிறுத்திய ஔவையார்.

### UNIT 2 அறநெறித்தமிழ்

6

- 1. அறநெறி வகுத்த திருவள்ளுவர் அறம் வலியுறுத்தல், அன்புடைமை, ஒப்புறவு அறிதல், ஈகை, புகழ்.
- 2. பிற அறநூல்கள் இலக்கிய மருந்து ஏலாதி, சிறுபஞ்சமூலம், திரிகடுகம், ஆசாரக்கோவை (தூய்மையை வலியுறுக்கும் நூல்).

## UNIT 3 இரட்டைக்காப்பியங்கள்

6

- 1. கண்ண கியின் புரட்சி- சிலப்பதிகார வழக்குரை காதை.
- 2. சமூக சேலை இலக்கியம் மணிமேகலை சிறைக்கோட்டம் அறக்கோட்டமாகிய காதை.

### UNIT 4 அருள்நெறித்தமிழ்

6

- 1. சிறுபாணாற்றுப்படை பாரி முல்லைக்கு தேர் கொடுத்தது, பேகன் மயிலுக்குப் போர்வை கொடுத்தது, அதியமான் ஔவைக்கு நெல்லிக்கனி கொடுத்தது, அரசர் பண்புகள்.
- 2. நற்றிணை அன்னைக்குரிய புன்னை சிறப்பு.
- 3. திருமந்திரம் (617,618) இயமம் நியமம் விதிகள்.
- 4. தர்மசாலையை நிறுவிய வள்ளலார்.
- 5. புறநானூறு சிறுவனே வள்ளலானான்.
- 6. அகநானூறு (4) வண்டு.
- 7. நற்றிணை (11) நண்டு.
- 8. கலித்தொகை (11) யானை, புறா.
- 9. ஐந்திணை ஐம்பது (27) மான்.
- ஆகியவை பற்றிய செய்திக





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### UNIT 5 நவீன தமிழ் இலக்கியம்

6

- 1. உரைநடைத்தமிழ்
- தமிழின் முதல் புதினம்.
- தமிழின் முதல் சிறுகதை.
- கட்டுரை இலக்கியம்.
- பயண இலக்கியம்.
- நாடகம்.
- 2. நாட்டு விடுதலை போராட்டமும் தமிழ் இலக்கியமும்.
- 3. சமுதாய விடுதலையும் தமிழ் இலக்கியமும்.
- 4. பெண் விடுதலையும் விளிம்பு நிலையினரின் மேம்பாட்டில் தமிழ் இலக்கியமும்.
- 5. அறிவியல் தமிழ்.
- 6. இணையத்தில் தமிழ்.
- 7. சுற்றுச்சூழல் மேம்பாட்டில் தமிழ் இலக்கியம்.

	TOTAL PERIODS	30
	Course Outcomes	
Upon complet	ion of this course the students will be able to:	
CO1	சங்க இலக்கியம் மாணவர்கள் முழுமையாக அறிந்து பயன்	பெறுதல்.
CO2	அறநெறி இலக்கியம் வாயிலாக வாழ்வியலுக்குத் தேவையா பணிகளை மேற்கொள்ளுதல்.	ான தூய்மைப்
CO3	சிலப்பதிகாரம், மணிமேகலை காப்பியங்களில் உள்ள நீதிக் மாணவர்கள் தெரிந்துகொள்ளுதல்.	கருத்துகளை
CO4	இலக்கியங்களில் காணப்படும் அருள்நெறிக் கதைகளைப் ட விளக்குதல்.	<b>ப</b> ற்றி
CO5	தற்காலத் தமிழ் இலக்கியங்களை மாணவர்கள் தெரிந்து அன்று வாயிலாக பயன் அடைதல்.	வற்றின்

### TEXT BOOKS: தமிழ் இலக்கிய வெளியீடுகள் புத்தகங்கள்

- 1. தமிழ் இணைய கல்விக்கழகம் (Tamil Virtual University) www.tamilvu.org.
- 2. தமிழ் விக்கிப்பீடியா (Tamil Wikipedia) -https://ta.wikipedia.org.
- 3. தர்மபுர ஆதீன வெளியீடு.
- 4. வாழ்வியல் களஞ்சியம் தமிழ்ப் பல்கலைக்கழகம், தஞ்சாவூர்.
- 5. தமிழ்க்கலைக்களஞ்சியம் தமிழ் வளர்ச்சித்துறை (thamilvalarchithurai.com).
- 6. அறிவியல் களஞ்சியம் தமிழ்ப் பல்கலைக்கழகம், தஞ்சாவூர்.





20107-			L		Т	Р	С
P24OT5	501	SUSTAINABLE MANAGEMENT	3		0	0	3
	"	Course Objectives					
1. To provide	e student	s with fundamental knowledge of the notion of corporate susta	inabilit	y.			
		organizations impacts on the environment and socio-technical social and environmental performance and competitiveness, t	-			s and	
UNIT I MANA	AGEMEI	IT OF SUSTAINABILITY					9
	and Eur	inability -rationale and political trends: An introduction to susta opean policies on sustainable development, theoretical pillars					ent,
UNIT II COR	PORATI	SUSTAINABILITY AND RESPONSIBILITY					9
	/ into stra	ity parameter, corporate sustainability institutional framework, tegic planning and regular business practices, fundamentals o					
Corporate su markets and	ustainabil competi	ity management and competitiveness: Sustainability-oriented iveness, Green Management between theory and practice, Sustainability-oriented iveness, Green Management between theory and practice, Sustainability-oriented in the control of the contro	ıstaina	ble	e Cor	tegie:	otion
Corporate su markets and and Green M approaches a SupplyChain	ustainabil competi larketing and tools Manage	ity management and competitiveness: Sustainability-oriented iveness, Green Management between theory and practice, Sustrategies, Environmental regulation and strategic postures; C; Green engineering: clean technologies and innovation procement and Procurement.	ıstaina Green I	ble Ma	e Cor nage	tegie: nsum ement able	s, otion
Corporate su markets and and Green M approaches a SupplyChain	ustainabil competii Marketing and tools Manage	ity management and competitiveness: Sustainability-oriented iveness, Green Management between theory and practice, Sustrategies, Environmental regulation and strategic postures; C; Green engineering: clean technologies and innovation procement and Procurement.  ILITY AND INNOVATION	ustaina Green I sses; S	ble Ma Su	e Cor nage stain	tegie: nsum ement able	s, otion
Corporate su markets and and Green M approaches a SupplyChain UNIT IV SUS Socio-technic	ustainabil competii Marketing and tools Manage STAINAE cal trans	ity management and competitiveness: Sustainability-oriented iveness, Green Management between theory and practice, Sustrategies, Environmental regulation and strategic postures; C; Green engineering: clean technologies and innovation procement and Procurement.	ustaina Green I sses; S	ble Ma Su	e Cor nage stain	tegie: nsum ement able	s, otion
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- 1. Daddi, T., Iraldo, F., Testa, Environmental Certification for Organizations and Products: Management, 2015
- 2. Christian N. Madu, Handbook of Sustainability Management 2012
- 3. Petra Molthan-Hill, The Business Student's Guide to Sustainable Management: Principles and Practice, 2014
- 4. Margaret Robertson, Sustainability Principles and Practice, 2014
- 5. Peter Rogers, An Introduction to Sustainable Development, 2006

CO, PO Mapping								
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3		
CO1	3	3	2	1	2	2		
CO2	3	2	2	2	1	2		
CO3	3	3	1	2	1	3		
CO4	3	3	2	1	1	2		
CO5	3	3	2	1	2	2		
AVG	3	3	2	1	2	3		





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P24OT502	MICRO AND SMALL BUSINESS MANAGEMENT	L	Т	Р	С		
P2401502	MICRO AND SMALL BUSINESS MANAGEMENT	3	0	0	3		
	Course Objectives						
1 To familiarize stud	To familiarize students with the theory and practice of small business management						

- To familiarize students with the theory and practice of small business management.
- 2. To learn the legal issues faced by small business and how they impact operations.

### UNIT I INTRODUCTION TO SMALL BUSINESS

9

Creation, Innovation, entrepreneurship and small business - Defining Small Business -Role of Owner -Manager – government policy towards small business sector –elements of entrepreneurship –evolution of entrepreneurship - Types of Entrepreneurship - social, civic, corporate - Business life cycle - barriers and triggers to new venture creation – process to assist start ups – small business and family business.

### UNIT II SCREENING THE BUSINESS OPPORTUNITY AND FORMULATING THE BUSINESS **PLAN**

9

Concepts of opportunity recognition; Key factors leading to new venture failure; New venture screening process; Applying new venture screening process to the early stage small firm Role planning in small business- importance of strategy formulation - management skills for small business creation and development.

### UNIT III BUILDING THE RIGHT TEAM AND MARKETING STRATEGY

9

Management and Leadership - employee assessments - Tuckman's stages of group development - The entrepreneurial process model - Delegation and team building - Comparison of HR management in small and large firms - Importance of coaching and how to apply a coaching model.

Marketing within the small business - success strategies for small business marketing - customer delight and business generating systems, - market research, - assessing market performance- sales management and strategy - the marketing mix and marketing strategy.

### **UNIT IV FINANCING SMALL BUSINESS**

Main sources of entrepreneurial capital; Nature of 'bootstrap' financing - Difference between cash and profit -Nature of bank financing and equity financing - Funding-equity gap for small firms. Importance of working capital cycle - Calculation of break-even point - Power of gross profit margin- Pricing for profit - Credit policy issues and relating these to cash flow management and profitability.

### UNIT V VALUING SMALL BUSINESS AND CRISIS MANAGEMENT

9

Causes of small business failure - Danger signals of impending trouble - Characteristics of poorly performing firms - Turnaround strategies - Concept of business valuation - Different valuation measurements - Nature ofgood will and how to measure it - Advantages and disadvantages of buying an established small firm -Process of preparing a business for sale.

		TOTAL	45					
	Course Outcomes							
At the en	d of the course, the student will be able to							
CO1	Familiarise the students with the concept of small business							
CO2	In depth knowledge on small business opportunities and challenges							
CO3	Ability to devise plans for small business by building the right skills and marketing	ng strategie	S					
CO4	Identify the funding source for small start ups							
CO5	Business evaluation for buying and selling of small firms	RTMEN						
	// .9	-11	200					

### REFERENCES

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2. Parker,R.(2000). "Small is not necessarily beautiful: An evaluation of policy support for small and medium-sized enterprise in Australia." Australian Journal of Political Science 35(2):239-253.

### 3. Journal articles on SME's.

			CO, PO Mapping			
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	2	2	1	1	-	-
CO2	3	3	3	3	2	3
CO3	3	3	2	2	3	3
CO4	3	2	2	2	1	1
CO5	3	2	2	3	2	1
AVG	3	3	2	2	2	2





				L	Т	Р	С	
P240	Γ503	INTELLE	CTUAL PROPERT	Y RIGHTS	3	0	0	3
			Course Objectives	 S	-			
To underst	and intelle	ctual property rights and	d its valuation.					
UNIT I INT	RODUCT	ON					9	9
Geographic	c Indicator		Property, Technology	nts, Copyrights, Tradem ogical Research, Invent				
UNIT II PR	OCESS						Ç	9
		IPR, Procedure for grant of Patent system in In		, GIs, Patenting under P oreign countries.	atent	Coop	peration	on
UNIT III ST	ATUTES						,	9
India, Pate	nt Amend		Act, Trademark A	reement, PCT Agreeme act, Geographical Indica				
UNIT IV ST	RATEGI	S IN INTELLECTUAL	PROPERTY				9	9
Strategies Knowledge			nation and databas	ses, IPR strength in Indi	a, Tr	aditio	nal	
UNIT V MC	DELS						,	9
				ce of IP in Value Creatio gic Decision Making, Tr				and
						TO	Γ <b>AL</b>	45
			Course Outcomes	S				
At the end		urse, the student will						
CO1				tion of the need to prote	ect it			
CO2		s about the process of						
CO3	Understa	nding of the statutes rel	ated to IPR					
CO4	Ability to	apply strategies to prote	ect intellectual prop	perty				
CO5	Ability to	apply models for makin	g strategic decisior	ns related to IPR				
REFEREN	CES							
1. V. Sople	Vinod, M	naging Intellectual Pro	perty by (Prentice I	hall of India Pvt.Ltd), 20	06.			
2. Intellectu	ıal Proper	y rights and copyrights,	EssEss Publicatio	ons.				
3. Primer, I	R. Anita R	o and Bhanoji Rao, Int	ellectual Property F	Rights, Lastain Book co	mpar	ıy.		
4. Edited b ElgarPublis	•		Vebster, The Mana	agement of Intellectual F	Prope	rty, E	dward	. k
5. WIPO In	tellectual	Property Hand book.						





			CO, PO Mapping			
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	3
CO2	3	3	2	3	1	3
CO3	3	3	3	3	2	3
CO4	3	3	3	2	1	3
CO5	3	3	3	2	2	3
AVG	3	3	3	3	2	3





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		W.E. Embedded System recimologies				
P24OT50	)4	ETHICAL MANAGEMENT	L	T	Р	С
		Course Objectives	3	0	0	3
To halp studer	nts deve	Course Objectives  lop knowledge and competence in ethical management and deci	eion	makir	na in	
organizational			51011	IIIanii	ıg III	
UNIT I ETHICS	S AND S	SOCIETY			9	9
Managerial eth	hics, pro	Definition, Motivation, Advantages-Practical implications of ethical fessional ethics, and social Responsibility-Role of culture and social responsibility to society and the community.				
UNIT II ETHIC	CAL DEC	CISION MAKING AND MANAGEMENT IN A CRISIS			9	9
	orld sce	I crisis, the nature of a crisis, ethics in crisis management, discus narios, develop ethical management skills, knowledge, and comp				tive
UNIT III STAK	KEHOLD	ERS IN ETHICAL MANAGEMENT			,	9
(leadership, fa environment(th	aimess, j he susta	f various kinds of stakeholders: customers (product and service i ustice, diversity) suppliers, collaborators, business, community, t inability imperative, green management, Contemporary issues).			пріоує	es
UNIT IV INDIV	/IDUAL	VARIABLES IN ETHICAL MANJAGEMENT			,	9
ethicalawarene emotions/intuit	ess, ethi itions/inte	ual variables in ethics, managerial ethics, concepts in ethical psy cal courage, ethical judgment, ethical foundations, ethical ensity. ncepts and competencies for ethical decision-making and manag				
UNIT V PRAC	TICAL I	FIELD-GUIDE, TECHNIQUES AND SKILLS				9
dilemmas,resc	olving is	n practice, development of techniques and skills, navigating chall sues and preventing unethical management proactively. Role mo nagement and human flourishing.				ting
				TO	Γ <b>AL</b>	45
		Course Outcomes				
		rse, the student will be able to				
		elling and influencing the ethical and cultural context.				
CO2 Re	espond t	o ethical crises and proactively address potential crises situation	S.			
CO3 Ur	nderstan	d and implement stakeholder management decisions.				
CO4 De	evelop th	ne ability, knowledge, and skills for ethical management				
CO5 De	evelop p	ractical skills to navigate, resolve and thrive in management situa	ations	3		
REFERENCE	S					
		iller, Bill O' Rourke, The Business Ethics Field Guide: the essented your company, 2016.	ial co	mpar	nion to	)
2. Steiner & St	teiner, B	usiness, Government & Society: A managerial Perspective, 201			Service .	

3. Lawrence & Weber, Business and Society: Stakeholders, Ethics, Public Policy, 2020, ARTIME,

8 / JAN 2025
\* SIGN R



			CO, PO Mapping			
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	2	3	2	3
CO2	-	3	2	3	1	3
CO3	3	3	3	3	2	3
CO4	3	3	3	2	1	3
CO5	3	3	3	2	2	3
AVG	3	3	3	3	2	3





DOLOTA	-0-5		L	T	Р	С
P24OT5	505	BIG DATA ANALYTICS	3	0	0	3
	'	Course Objectives				
1. To unders	tand the	basics of big data analytics				
2. To unders	tand the	search methods and visualization				
3. To learn m	nining da	ta streams				
4. To learn fr	ramewor	KS				
5. To gain kn	nowledge	on R language				
UNIT I INTR	ODUCTI	ON TO BIG DATA			,	9
of Data - Ana	alytic Pro	ata Platform – Challenges of Conventional Systems - Intelligent data cesses and Tools - Analysis Vs Reporting - Modern Data Analytic T Distributions - Re-Sampling - Statistical Inference - Prediction Error.	ools			
UNIT II SEA	RCH ME	THODS AND VISUALIZATION			,	9
Genetic Algo	orithm – (	Annealing – Stochastic, Adaptive search by Evaluation – Evaluatior Genetic Programming – Visualization – Classification of Visual Data				
		pes – Visualization Techniques – Interaction techniques – Specific				
analysis Tec UNIT III MIN	hniques	A STREAMS	Visu	ual da	ata	9 ing
analysis Tect UNIT III MINI Introduction Data in a Stru Counting On	thniques ING DAT To Strea Team – Frances in		Visu putir	ng -S Mom	ata samplents	ing –
analysis Tect UNIT III MINI Introduction Data in a Stru Counting On	chniques ING DAT To Strea ream – Freness in s -Real T	TA STREAMS  ms Concepts – Stream Data Model and Architecture - Stream Completering Streams – Counting Distinct Elements in a Stream – Estimat a Window – Decaying Window - Real time Analytics Platform(RTAFilme Sentiment Analysis, Stock Market Predictions	Visu putir	ng -S Mom	ata ampl ents ations	ing –
analysis Tecturist Tecturist Tecturist MINI MINI Introduction Data in a Structuring On Case Studies UNIT IV FRAMA Reduce Systems —Ca	ING DAT To Streateam – Frameness in s -Real T AMEWOI e – Hadoo ase Stud	TA STREAMS  ms Concepts – Stream Data Model and Architecture - Stream Completering Streams – Counting Distinct Elements in a Stream – Estimat a Window – Decaying Window - Real time Analytics Platform(RTAFilme Sentiment Analysis, Stock Market Predictions	putir ting P) A tribu	ng -S Mom pplic ted F - Gra	ata sampleents ations	ing – s -
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analysis Tect UNIT III MINI Introduction Data in a Structure Counting On Case Studies UNIT IV FRA Map Reduce Systems – Ca Challenge: A UNIT V R LA Overview, Pr issues-Recur frames - Clas  At the end of CO1	thniques ING DAT To Strea ream – From the ream – From the ream of the counderstan ING DATE of the counderstan	ms Concepts – Stream Data Model and Architecture - Stream Completering Streams – Counting Distinct Elements in a Stream – Estimate a Window – Decaying Window - Real time Analytics Platform(RTAFTime Sentiment Analysis, Stock Market Predictions  RKS  Op, Hive, MapR – Sharding – NoSQL Databases - S3 - Hadoop Distry- Preventing Private Information Inference Attacks on Social Network Regulatory Science and Big Data to Improve Medical Device Innovation in Structures: Control statements - Operators - Functions - Environmental Placement functions, R data structures: Vectors - Matrices and array att/output, String manipulations  Course Outcomes  urse, the student will be able to	putiriputing P) A	ng -S Mom pplic ted F - Gra	ata gampleents ations file and gampleents ations	9 9
analysis Tect UNIT III MINI Introduction Data in a Strict Counting On Case Studies UNIT IV FRA Map Reduce Systems – Ca Challenge: A UNIT V R LA Overview, Prissues-Recur frames - Clas  At the end of CO1 L CO2 A	thniques ING DAT To Strea ream – For the eness in the eness of the eness in the ene	ms Concepts – Stream Data Model and Architecture - Stream Completering Streams – Counting Distinct Elements in a Stream – Estimat a Window – Decaying Window - Real time Analytics Platform(RTAFilme Sentiment Analysis, Stock Market Predictions  RKS  Op, Hive, MapR – Sharding – NoSQL Databases - S3 - Hadoop Distry- Preventing Private Information Inference Attacks on Social Network Regulatory Science and Big Data to Improve Medical Device Innovation in Structures: Control statements - Operators - Functions - Environment Placement functions, R data structures: Vectors - Matrices and array att/output, String manipulations  Course Outcomes  urse, the student will be able to  and the basics of big data analytics	putiribu orks ation	ual dang -S Mom pplic tted F - Gra and Lists	ata  gampl ents ations  file and  scope -Data	9 9 45
analysis Tect UNIT III MINI Introduction Data in a Strict Counting On Case Studies UNIT IV FRA Map Reduce Systems – Ca Challenge: A UNIT V R LA Overview, Prissues-Recur frames - Clas  At the end of CO1 L CO2 A CO3 A	chniques ING DAT To Strea ream – F reness in s -Real T AMEWOI  ANGUAG AN	ms Concepts – Stream Data Model and Architecture - Stream Completering Streams – Counting Distinct Elements in a Stream – Estimat a Window – Decaying Window - Real time Analytics Platform(RTAR ime Sentiment Analysis, Stock Market Predictions  RKS  Op, Hive, MapR – Sharding – NoSQL Databases - S3 - Hadoop Distry- Preventing Private Information Inference Attacks on Social Network Regulatory Science and Big Data to Improve Medical Device Innovation in the structures: Control statements - Operators - Functions - Environmental Placement functions, R data structures: Vectors - Matrices and array att/output, String manipulations  Course Outcomes  urse, the student will be able to and the basics of big data analytics use Hadoop, Map Reduce Framework.	putiribu orks ation	ual dang -S Mom pplic tted F - Gra and Lists	ata  gampl ents ations  file and  scope -Data	9 9 45





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			CO, PO Mapping			
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	3	3	3	3	2	1
CO2	3	3	3	3	2	1
CO3	3	3	3	3	2	1
CO4	3	3	3	3	2	1
CO5	3	3	3	3	2	1
AVG	3	3	3	3	2	1





			L	Т	Р	С
P2401	Γ506	INTERNET OF THINGS AND CLOUD	3	0	0	3
		Course Objectives				
1. To under	rstand Sm	art Objects and IoT Architectures				
		ious IOT-related protocols				
3. To build	simple lo	Γ Systems using Arduino and Raspberry Pi.				
		a analytics and cloud in the context of IoT				
		rastructure for popular applications				
	•	TALS OF IOT				9
Technologi	es – loT (	loT definition – Characteristics – loT Complete Architectural Stack Challenges. Sensors and Hardware for loT – Hardware Platforms – se study with any one of the boards and data acquisition from sense	Ard			berry
UNIT II PR	OTOCOL	S FOR IoT				9
	Device Ma	ol (IPV4/V6/RPL), Identification (URIs), Transport (Wifi, Lifi, BLE), I anagement Protocols. – A Case Study with MQTT/CoAP usage-loT tions.				
UNIT III CA	SE STUD	DIES/INDUSTRIAL APPLICATIONS				9
		chitectural analysis: loT applications – Smart City – Smart Water – rt Healthcare – Smart Transportation – Smart Retail – Smart waste				
UNIT IV CL	OUD CO	MPUTING INTRODUCTION				9
		Computing - Service Model – Deployment Model- Virtualization Co AWS – Microsoft Azure – Google APIs.	once	pts -	Clou	d
UNIT V IoT	AND CL	OUD				9
Connecting	a web ap	Role of Cloud Computing in IoT - AWS Components - S3 – Lambda oplication to AWS IoT using MQTT- AWS IoT Examples. Security Copects of Cloud Computing- Cloud Data Security				re -
	<u> </u>			TO	ΓAL	45
		Course Outcomes	1			1
At the end	of the co	ourse, the student will be able to				
CO1	Understa	nd the various concept of the loT and their technologies				
CO2	Develop	loT application using different hardware platforms				
CO3	Impleme	nt the various loT Protocols				
CO4	Understa	nd the basic principles of cloud computing.				
CO5	Develop	and deploy the IoT application into cloud environment				
REFEREN	CES					
		nings: Enabling Technologies, Platforms, and Use Cases", by Petho ,CRC Press, 2017	ıru F	Raj ar	nd	
2. Adrian M	lcEwen, D	esigning the Internet of Things, Wiley,2013.	-		To other	
		ervices, "Data Science and Big Data Analytics: Discovering, Analyz ley publishers, 2015.	ing,	Visu	alizing	and
4. Simon W	/alkowiak,	"Big Data Analytics with R" PackT Publishers, 2016	rn.	JVEL	BY	100
5. Bart Bae Wiley Publi		alytics in a Big Data World: The Essential Guide to Data Science a 15.	nd ji	s Ap	olicati	ons",



P24OT507	MEDICAL ROBOTICS	L 3	T	Р	С
	Course Objectives	3	0	0	3
1 To evaloin the hea	Course Objectives				
•	sic concepts of robots and types of robots signing procedure of manipulators, actuators and grippers				
	dge on various types of sensors and power sources				
•	s applications of Robots in Medicine				
•	ge on wearable robots				
UNIT I INTRODUCT	<u> </u>				•
	tics, Overview of robot subsystems, Degrees of freedom, configurat	:	اء ء، ء	<u> </u>	
Proximity sensors, for					ıd
<u>.</u>	TORS & BASIC KINEMATICS			9	)
manipulator, Forward problems <b>Navigation and Tre</b>	ngements, Path determination – Machinery vision, Ranging – Laser	erse/	e Kin	emati	С
UNIT III SURGICAL	ROBOTS			9	)
System concept for i	stem, Image guided robotic systems for focal ultrasound based surgeobotic Tele-surgical system for off-pump, CABG surgery,Urologic a ery, Pediatric and General Surgery,Gynecologic Surgery, General S Study	pplid	cation	ıs, Ca	
<b>UNIT IV REHABILIT</b>	ATION AND ASSISTIVE ROBOTS			9	9
Rehabilitation Robot	on, Robotic Therapy for the Upper Extremity and Walking, Clinical-Is, Motion Correlation and Tracking, Motion Prediction, Motion Replicilitation, Robotic Exoskeletons – Design considerations,Hybrid assistant	catio	on. Po	ortable	
UNIT V WEARABLE	ROBOTS			9	)
Sensors, Actuators,	Kinematics and Dynamics for Wearable Robots, Wearable Robot te Portable Energy Storage, Human–robot cognitive interaction (cHRI) ction (pHRI), Wearable Robotic Communication - case study				



**TOTAL** 

45



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	Course Outcomes
At the end	d of the course, the student will be able to
CO1	Describe the configuration, applications of robots and the concept of grippers and actuators
CO2	Explain the functions of manipulators and basic kinematics
CO3	Describe the application of robots in various surgeries
CO4	Design and analyze the robotic systems for rehabilitation
CO5	Design the wearable robots

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- 2. Spong and Vidhyasagar, "Robot Dynamics and Control", John Wiley and Sons, First edition, 2008
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- 4. Bruno Siciliano, OussamaKhatib, Springer Handbook of Robotics, 1st Edition, Springer, 2008
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- 6. Sashi S Kommu, Rehabilitation Robotics, I-Tech Education and Publishing, 2007
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			CO, PO Mapp	ing		
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	-	-	-	1	-	-
CO2	-	-	-	2	-	-
CO3	2	-	2	2	2	2
CO4	2	-	2	2	3	2
CO5	2	-	2	2	3	3
AVG	2	-	2	2	3	2





P2401	T508	EMBEDDED AUTOMATION	L	T	Р	С
1 240	1000	EMBEBBE ACTOMATION	3	0	0	3
		Course Objectives				
1. To learn	about the	process involved in the design and development of real-time ember	edde	d sys	tem	
2. To devel	lop the em	bedded C programming skills on 8-bit microcontroller				
3. To study	/ about the	e interfacing mechanism of peripheral devices with 8-bit microcontro	oller	s		
4. To learn	about the	tools, firmware related to microcontroller programming				
5. To build	a home a	utomation system				
UNIT - I IN	TRODUC	TION TO EMBEDDED C PROGRAMMING			!	9
		gram Structure - C Types, Operators and Expressions - C Control F res - C Pointers And Arrays - FIFO and LIFO - C Structures - Deve				ons
UNIT - II A	VR MICRO	OCONTROLLER			,	9
Base,Timin	ng Subsyst	cture - Nonvolatile and Data Memories - Port System - Peripheral F tem, Pulse Width Modulation, USART, SPI, Two Wire Serial Interfa ting Parameters				
_		RE AND SOFTWARE INTERFACING WITH 8-BIT SERIES			,	9
Lights and Analog To	Switches Digital Co	- Stack Operation - Implementing Combinational Logic - Expanding nvertors - Interfacing Digital To Analog Convertors - LED Displays :	: Se	ven S	egme	nt
Analog To l Displays, D	Switches Digital Co Oot Matrix Clock - Ac	nvertors - Interfacing Digital To Analog Convertors - LED Displays : Displays - LCD Displays - Driving Relays - Stepper Motor Interface ccessing Constants Table - Arbitrary Waveform Generation - Comm	: Se - Se	ven S erial E	egme EPR	ent OM -
Lights and S Analog To Displays, D Real Time	Switches Digital Co Oot Matrix Clock - Acevelopmen	nvertors - Interfacing Digital To Analog Convertors - LED Displays : Displays - LCD Displays - Driving Relays - Stepper Motor Interface ccessing Constants Table - Arbitrary Waveform Generation - Comm t Tools	: Se - Se	ven S erial E	egme EPR Link	ent OM -
Lights and Analog To Displays, De Real Time System De UNIT – IV NEURING AND	Switches Digital Co Oot Matrix Clock - Ac evelopmen VISION SY tals of Ima	nvertors - Interfacing Digital To Analog Convertors - LED Displays : Displays - LCD Displays - Driving Relays - Stepper Motor Interface ccessing Constants Table - Arbitrary Waveform Generation - Comm t Tools	: Se - Se nunio	ven Serial Ecation	egme EPR Links	ent OM - s -
Lights and a Analog To Displays, D Real Time of System De UNIT – IV N Fundament -Blurring ar Gradient -C	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Ima and Sharpe Canny Edg	nvertors - Interfacing Digital To Analog Convertors - LED Displays: Displays - LCD Displays - Driving Relays - Stepper Motor Interface coessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contour	: Se - Se nunio	ven Serial Ecation	egme EPR Links Links d Mat es -	ent OM - s -
Lights and a Analog To Displays, Description Real Time of System Description Description Controlled Lights and Lights Analogo Description Controlled Lights Analogo Times Control Lights Analogo Times Control Lights Analogo Times Control Lights Analogo T	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Delivery De Home Aut	nvertors - Interfacing Digital To Analog Convertors - LED Displays: Displays - LCD Displays - Driving Relays - Stepper Motor Interface accessing Constants Table - Arbitrary Waveform Generation - Comment Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contours - Object Detection - Background Subtraction	ections Properties	ven Serial Ecation on anoperti	d Mates -	ent OM - S - Ching
Lights and a Analog To Displays, Description Real Time of System Description Description Controlled Lights and Lights Analogo Description Controlled Lights Analogo Times Control Lights Analogo Times Control Lights Analogo Times Control Lights Analogo T	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Delivery De Home Aut	nvertors - Interfacing Digital To Analog Convertors - LED Displays : Displays - LCD Displays - Driving Relays - Stepper Motor Interface coessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contourse Detector - Object Detection - Background Subtraction  TOMATION  Requirements - Water Level Notifier - Electric Guard Dog - Tweeting tector - Web Enabled Light Switch - Curtain Automation - Android Itomation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor	ections Properties	ven Serial Ecation on anoperti	d Mates -	ent OM - S - Ching
Lights and a Analog To Displays, Description Real Time of System Description Description Controlled Lights and Lights Analogo Description Controlled Lights Analogo Times Control Lights Analogo Times Control Lights Analogo Times Control Lights Analogo T	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Delivery De Home Aut	nvertors - Interfacing Digital To Analog Convertors - LED Displays : Displays - LCD Displays - Driving Relays - Stepper Motor Interface coessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contourse Detector - Object Detection - Background Subtraction  TOMATION  Requirements - Water Level Notifier - Electric Guard Dog - Tweeting tector - Web Enabled Light Switch - Curtain Automation - Android Itomation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor	ections Properties	ven Serial Ecation on anopertion	d Mates -	ent OM - S - 9 ching
Lights and a Analog To Displays, Description Real Time of System Description Description Real Time of System Description Real Time of State of Stat	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Domation - F Delivery De Home Aut Dor Opener	nvertors - Interfacing Digital To Analog Convertors - LED Displays: Displays - LCD Displays - Driving Relays - Stepper Motor Interface coessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contourse Detector - Object Detection - Background Subtraction  TOMATION  Requirements - Water Level Notifier - Electric Guard Dog - Tweeting tector - Web Enabled Light Switch - Curtain Automation - Android I comation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor - Vision Based Authentic Entry System	ections Properties	ven Serial Ecation on anopertion	d Mates -	ent OM - S - 9 ching
Lights and a Analog To Displays, Description Real Time of System Description Description Real Time of System Description Real Time of State of Stat	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Domation - Felivery De Home Aut For Opener	nvertors - Interfacing Digital To Analog Convertors - LED Displays: Displays - LCD Displays - Driving Relays - Stepper Motor Interface coessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contourse Detector - Object Detection - Background Subtraction  TOMATION  Requirements - Water Level Notifier - Electric Guard Dog - Tweeting tector - Web Enabled Light Switch - Curtain Automation - Android I comation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor - Vision Based Authentic Entry System  Course Outcomes	ections Bin Door	ven Serial Ecation on anopertion	d Mates -	ent OM - S - 9 ching
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Lights and a Analog To Displays, D Real Time System De UNIT - IV V Fundament -Blurring ar Gradient -C UNIT - V H Home Auto Package Do Controlled Garage Do At the end CO1	Switches Digital Co Dot Matrix Clock - Acevelopmen VISION SY tals of Imand Sharpe Canny Edg HOME AU Domation - Felivery De Home Aut For Opener I of the co analyze t write eml	nvertors - Interfacing Digital To Analog Convertors - LED Displays: Displays - LCD Displays - Driving Relays - Stepper Motor Interface occessing Constants Table - Arbitrary Waveform Generation - Commit Tools  YSTEM  age Processing - Filtering - Morphological Operations - Feature Detening - Segmentation - Thresholding - Contours - Advanced Contourse Detector - Object Detection - Background Subtraction  TOMATION  Requirements - Water Level Notifier - Electric Guard Dog - Tweeting elector - Web Enabled Light Switch - Curtain Automation - Android Itemation - Smart Lighting - Smart Mailbox - Electricity Usage Monitor - Vision Based Authentic Entry System  Course Outcomes  Course, the student will be able to the 8-bit series microcontroller architecture, features and pin details	ections Bin Door	ven Serial Ecation on anopertion	d Mates -	ent OM - S - 9 ching
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			CO, PO Mapping			
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3
CO1	1	-	1	1	1	-
CO2	1	3	1	1	1	3
CO3	1	3	1	1	1	3
CO4	1	3	1	1	1	3
CO5	1	3	1	1	1	3
AVG	1	3	1	1	1	3





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P24OT509	ENVIRONMENTAL SUSTAINABILITY	L	Т	P	С
		3	0	0	3
UNIT I INTRODUCTI	ON			,	9
Valuing the Environn Environmental Proble	nent: Concepts, Valuing the Environment: Methods, Property Righterns	s, E	xterna	alities,	and
UNIT II CONCEPT O	F SUSTAINABILITY			,	9
Sustainable Develop Overview, Energy, W	ment: Defining the Concept, the Population Problem, Natural Resc ater, Agriculture	ource	e Eco	nomic	s: An
UNIT III SIGNIFICAN	CE OF BIODIVERSITY			,	9
	labitat, Commercially Valuable Species, Stationary - Source Local c Modification, Transportation	Air	Pollut	ion, A	cid
UNIT IV POLLUTION	IMPACTS			,	9
Water Pollution, Solid	Waste and Recycling, Toxic Substances and Hazardous Wastes	, Glo	bal V	/armir	ng.
UNIT V ENVIRONME	NTAL ECONOMICS			,	9
Poverty, and the Env Tietenberg, Environn	ironment, Visions of the Future, Environmental economics and pol nental Economics	icy k	y Tor	n	
-			TO	TAL	45
REFERENCES					
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2. Stephen Doven, E Federation Press, 20	nvironment and Sustainability Policy: Creation, Implementation, Ev	/alua	ation,	the	
3. Robert Brinkmann	, Introduction to Sustainability, Wiley-Blackwell., 2016				
4. Niko Roorda., Fun	damentals of Sustainable Development, 3rd Edn, Routledge, 2020	)	•		•
5. Bhavik R Bakshi.,	Sustainable Engineering: Principles and Practice, Cambridge Univ	ersi	ty Pre	ss, 20	)19





	,				
P24OT510	TEXTILE REINFORCED COMPOSITES	L	T	Р	С
		3	0	0	3
UNIT I REINFORCE	MENTS				9
	sites –classification and application; reinforcements- fibres and its ced materials and quality evaluation; preforms for various composi		perties	s;	
UNIT II MATRICES					9
	ry, properties and applications of thermoplastic and thermoset resir s and reinforcements; optimization of matrices	ns; r	necha	anism	of
UNIT III COMPOSIT	E MANUFACTURING				9
Filament Winding, Re	ds of composites manufacturing for both thermoplastics and thermo esin transfer moulding, prepregs and autoclave moulding, pultrusion ls, compression moulding; post processing of composites and comp	n, va	acuun	า	yup,
UNIT IV TESTING					9
	ight fraction, specific gravity of composites, tensile, f lexural, impac tress and fatigue properties of thermoset and thermoplastic compos			ssion	١,
UNIT V MECHANICS	3				9
-	acro mechanics of single layer, macro mechanics of laminate, class s and prediction of inter laminar stresses using at ware	ical	lamir	ation	
-			TO	ΓAL	45
REFERENCES		'			
1. BorZ.Jang,"Advan	ced Polymer composites",ASM International,USA,1994.				
	Pipes R.B., "Experimental Characterization of advanced composite lition, CRCPress, New Jersey, 1996.	)			
3. George Lubinand	Stanley T.Peters, "Handbook of Composites", Springer Publications	,199	98.		
4. Mel. M. Schwartz,	"Composite Materials", Vol. 1 &2, Prentice Hall PTR, New Jersey,1	997	<b>'</b> .		
5. RichardM.Christer	sen, "Mechanics of compositematerials", Dover Publications, 2005.				
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2006

## Meenakshi Sundararajan Engineering College

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P24OT511	NANOCOMPOSITE MATERIALS	L 3	T 0	P 0	C 3
LINIT I BASICS OF I		3	U	0	3
Nomenclature, Proper Characterization of S	erties, features and processing of nanocomposites. Sample Prepara Structure and Physical properties. Designing, stability and mechanic hard nanocomposites.			ties a	nd
UNIT II METAL BAS	ED NANOCOMPOSITES			,	9
Metal-Ceramic comp	mposites, some simple preparation techniques and their properties. posites, Different aspects of their preparation techniques and their file based glass-metal nanocomposites, its designing and fractal dimend nanocomposites	nal <sub>l</sub>	prope	rties a	
UNIT III POLYMER	BASED NANOCOMPOSITES			,	9
	racterization of diblock Copolymer based nanocomposites; Polymer neir mechanical properties, and industrial possibilities.	· Ca	rbon	nanot	ubes
UNIT IV NANOCOM	POSITE FROM BIOMATERIALS			,	9
through self-assemb	site systems - spider silk, bones, shells; organic-inorganic nanocomply. Biomimetic synthesis of nanocomposites material; Use of synthe bone, teeth replacement.		te for	matio	n
UNIT V NANOCOM	POSITE TECHNOLOGY			,	9
Cosmetics-Nano-fille textiles (UV resistant dispersions for UV p	nbrane structures- Preparation and applications. Nanotechnology in ers embedded polypropylene fibers — Soil repellence, Lotus effect - I t, anti-bacterial, hydrophilic, self-cleaning, flame retardant finishes), rotection using titanium oxide — Colour cosmetics. Nanotechnology ackaging for enhanced shelf life - Smart/Intelligent packaging.	Nan Sun	o finis	shing	in
			TO	ΓAL	45
REFERENCES					
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2. Nanocomposites	Science and Technology - P. M. Ajayan, L.S. Schadler, P. V.Braun 2	2006	6.		
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4. Carbon Nanotube	s (Carbon , Vol 33) - M. Endo, S. lijima, M.S. Dresselhaus 1997.				
5. The search for no	vel, superhard materials- Stan Vepr¡ek (Review Article) JVST A, 19	99			
	s micrometer-sized particles-Christian Brosseau, Jamal BeN Yousse Review Article) J. Appl. Phys, Vol 93, 2003	ef, P	hilipp	e Tal	bot,
7. Diblock Copolyme	r, - Aviram (Review Article), Nature, 2002				

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P24OT512	IPR, BIOSAFETY AND ENTREPRENEURSHIP	L	Т	Р	С
		3	0	0	3
UNIT I IPR					

Intellectual property rights – Origin of the patent regime – Early patents act & Indian pharmaceutical industry– Types of patents – Patent Requirements – Application preparation filing and prosecution – Patentable subject matter – Industrial design, Protection of GMO's IP as a factor in R&D,IP's of relevance to biotechnology and few case studies.

### UNIT II AGREEMENTS, TREATIES AND PATENT FILING PROCEDURES

9

History of GATT Agreement – Madrid Agreement – Hague Agreement – WIPO Treaties – Budapest Treaty – PCT – Ordinary – PCT – Conventional – Divisional and Patent of Addition – Specifications – Provisional and complete – Forms and fees Invention in context of "prior art" – Patent databases – Searching International Databases – Country-wise patent searches (USPTO,espacenet(EPO) – PATENT Scope (WIPO) – IPO, etc National & PCT filing procedure – Time frame and cost – Status of the patent applications filed – Precautions while patenting – disclosure/non-disclosure – Financial assistance for patenting – Introduction to existing schemes Patent licensing and agreement Patent infringement – Meaning, scope, litigation, case studies

UNIT III BIOSAFETY 9

Introduction – Historical Backround – Introduction to Biological Safety Cabinets – Primary Containment for Biohazards – Biosafety Levels – Biosafety Levels of Specific Microorganisms – Recommended Biosafety Levels for Infectious Agents and Infected Animals – Biosafety guidelines – Government of India.

### UNIT IV GENETICALLY MODIFIED ORGANISMS

9

Definition of GMOs & LMOs – Roles of Institutional Biosafety Committee – RCGM – GEAC etc. for GMO applications in food and agriculture – Environmental release of GMOs – Risk Analysis – Risk Assessment – Risk management and communication – Overview of National Regulations and relevant International Agreements including Cartegana Protocol.

### UNIT V ENTREPRENEURSHIP DEVELOPMENT

9

Introduction – Entrepreneurship Concept – Entrepreneurship as a career – Entrepreneurial personality – Characteristics of successful Entrepreneur – Factors affecting entrepreneurial growth – Entrepreneurial Motivation – Competencies – Mobility – Entrepreneurship Development Programmes (EDP) - Launching Of Small Enterprise - Definition, Characteristics – Relationship between small and large units – Opportunities for an Entrepreneurial career – Role of small enterprise in economic development – Problems of small scale industries – Institutional finance to entrepreneurs - Institutional support to entrepreneurs.

TOTAL 4

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P2400	517	SECURITY PRACTICES	3	0	0	3
		Course Objectives				
1. To learn	the core f	undamentals of system and web security concepts				
2. To have	through u	nderstanding in the security concepts related to networks				
3. To deploy	y the secu	urity essentials in IT Sector				
4. To be ex	posed to	the concepts of Cyber Security and cloud security				
5. To perfor	m a detai	led study of Privacy and Storage security and related Issues				
UNIT I SYS	TEM SEC	CURITY			,	9
Cryptograpl	hy primer	curity – Security attacks, services and mechanisms – OSI security a - Intrusion detection system- Intrusion Prevention system - Security - Top 10 Web Application Security Risks.				
UNIT II NET	rwork s	SECURITY			,	9
		ranet security- Local Area Network Security - Wireless Network Security- Cellular Network Security - Mobile security - IOT security - Ca				
UNIT III SE	CURITY	MANAGEMENT			,	9
		essentials for IT Managers- Security Management System - Policy Durity - Online Identity and User Management System. Case study: I				
UNIT IV CY	BER SE	CURITY AND CLOUD SECURITY			,	9
MalwareFo	rensics –	k Forensics – Network Forensics – Wireless Forensics – Database Mobile Forensics – Email Forensics- Best security practices for auto ement – Establishing trust in IaaS, PaaS, and SaaS Cloud types. Ca	oma	ate Cl	oud	VA
UNIT V PR	IVACY A	ND STORAGE SECURITY			9	9
Conflicts ins	security p	et - Privacy Enhancing Technologies - Personal privacy Policies - Decension of the Policies - Decension of the Policies - Decension of the Policies - Risk management - Physical Security Devices - Risk management - Physical Security -	oraç	je Are	ea Net	work
				TO	ΓAL	45
		Course Outcomes				
At the end		urse, the student will be able to				
CO1	Understa	nd the core fundamentals of system security				
CO2		security concepts to wired and wireless networks				
CO3	Impleme	nt and Manage the security essentials in IT Sector				
CO4	Explain t	ne concepts of Cyber Security and Cyber forensics				
CO5	Be aware	e of Privacy and Storage security Issues				





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- 5. John Sammons, "The Basics of Digital Forensics- The Primer for Getting Started in Digital Forensics", Syngress, 2012
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	CO, PO Mapping									
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	1	2	1	1	2	1				
CO2	2	1	3	1	1	2				
CO3	-	-	2	3	3	3				
CO4	2	2	1	2	1	3				
CO5	1	-	1	1	2	3				
AVG	2	2	2	2	2	2				





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P24OC518	CLOUD COMPUTING TECHNOLOGIES	3	0	0	3
	Course Objectives				
1. To gain expertise	in Virtualization, Virtual Machines and deploy practical virtualization	solu	ıtion		
2. To understand the	architecture, infrastructure and delivery models of cloud computing				
3. To explore the ros	ter of AWS services and illustrate the way to make applications in A	WS			
4. To gain knowledge	e in the working of Windows Azure and Storage services offered by	Win	dows	Azur	e
5. To develop the clo	ud application using various programming model of Hadoop and Ar	neka	ì		
UNIT I VIRTUALIZA	TION AND VIRTUALIZATION INFRASTRUCTURE			(	6
Virtualization — Hard Virtualization – Netw	y Translation - Taxonomy of Virtual Machines. Virtualization –Managewent – dware Maximization – Architectures – Virtualization Management – dork Virtualization -Implementation levels of virtualization – virtualization, Memory and I/Odevices – virtual clusters and Resource Managemenation	Stor ion s	age struct		
UNIT II CLOUD PLA	TFORM ARCHITECTURE			1	2
-Categories of cloud	efinition, Characteristics - Cloud deployment models: public, private, computing: Everything as a service: Infrastructure, platform, softwa esign – Layered cloud Architectural Development – Architectural De	re-	A Ge	neric	,
UNIT III AWS CLOU	D PLATFORM - IAAS			,	9
Storage - Stretching Developer Tools: AW codeStar - AWS Mar	ces: AWS Infrastructure- AWS API- AWS Management Console - Sout with Elastic Compute Cloud - Elastic Container Service for Kuber/S Code Commit, AWS Code Build, AWS Code Deploy, AWS Code nagement Tools: Cloud Watch, AWS Auto Scaling, AWS control Towil, AWS License Manager	erne Pip	tes- /	AWS AWS	
UNIT IV PAAS CLO	UD PLATFORM			9	9
Azure- Service Mode	gin of Windows Azure, Features, The Fabric Controller – First Cloud el and Managing Services: Definition and Configuration, Service runt tal- Service Management API- Windows Azure Storage Characteris Blops	ime	API-	Wind	
UNIT V PROGRAMI	/ING MODEL			,	9
and output paramete Hadoop file system -	op Framework - Mapreduce, Input splitting, map and reduce function ers, configuring and running a job –Developing Map Reduce Applicat -Setting up Hadoop Cluster- Aneka: Cloud Application Platform, Thro and Map-Reduce Programming in Aneka	tions	s - De	esign	of
			TO	TAL.	45





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	Course Outcomes				
At the end	At the end of the course, the student will be able to				
CO1	Employ the concepts of virtualization in the cloud computing				
CO2	Identify the architecture, infrastructure and delivery models of cloud computing				
CO3	Develop the Cloud Application in AWS platform				
CO4	Apply the concepts of Windows Azure to design Cloud Application				
CO5	Develop services using various Cloud computing programming models.				

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- 2. Raoul Alongi, AWS: The Most Complete Guide to Amazon Web Service from Beginner to Advanced Level, Amazon Asia- Pacific Holdings Private Limited, 2019.
- 3. Sriram Krishnan, Programming: Windows Azure, O'Reilly,2010.
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- 6. Jim Smith, Ravi Nair, "Virtual Machines: Versatile Platforms for Systems and Processes", Elsevier/Morgan Kaufmann, 2005.
- 7. John W.Rittinghouse and James F.Ransome, "Cloud Computing: Implementation, Management, and Security", CRC Press, 2010.
- 8. Toby Velte, Anthony Velte, Robert Elsenpeter, "Cloud Computing, A Practical Approach", McGraw-Hill Osborne Media, 2009.
- 9. Tom White, "Hadoop: The Definitive Guide", Yahoo Press, 2012.





	M.E. Embedded System Technologies							
P24OC519	DESIGN THINKING	L	T	Р	C			
	Course Objectives	3	0	0	3			
1 To provide a soup	d knowledge in UI & UX							
2. To understand the								
-								
3. Research Methods 4. Tools used in UI &	· · · · · · · · · · · · · · · · · · ·							
-								
5. Creating a wirefram				1 .				
UNIT I UX LIFECYC					3			
complexity space. Me lifecycles. Business	ocess lifecycle template. Choosing a process instance for your procest the user interface team. Scope of UX presence within the team Strategy. Value Innovation. Validated User Research. Killer UX De oposition. What Is a Value Proposition?	. Mo	re ab					
UNIT II CONTEXTU	AL INQUIRY			1	0			
practice. Abridged co	statement. User work activity data gathering. Look for emotional a ontextual inquiry process. Data-driven vs. model-driven inquiry. Orgnodel. Creating and managing work activity notes. Constructing yow.D). Abridged contextual analysis process. History of affinity diagra	ganiz ur w	zing c	oncep	ts:			
<b>UNIT III DESIGN TH</b>	INKING, IDEATION, AND SKETCHING			Ç	9			
domain: slideshow posummaries. Model co	dels: second span of the bridge. Some general "how to" suggestic resentations. User models. Usage models. Work environment mod nsolidation. Protecting your sources. Abridged methods for design radigms. Design thinking. Design perspectives. User personas. Ide	lels. -info	Barrie rming	er I mode	els			
UNIT IV UX GOALS	METRICS, AND TARGETS				9			
instruments. UX met	ls. UX target tables. Work roles, user classes, and UX goals. UX mrics. Baseline level. Target level. Setting levels. Observed results. UX targets. How UX targets help manage the user experience eng	Prac	tical t	ips ar	ıd 🧧			
UNIT V ANALYSING	USER EXPERIENCE			9	)			
Usability Problems. ( Projects with User Ex UXResearch. How to Research Into the De Experience Debrief N	nking Tools. UX Research and Strength of Evidence. Agile Person Creating Insights, Hypotheses and Testable Design Ideas. How to Experience Metrics. Two Measures that Will Justify Any Design Chato Create a User Journey Map. Generating Solutions to Usability Presign Studio Methodology. Dealing with Common objections to UX Meeting. Creating a User Experience Dashboard.	Mana nge. oble	age D Evan ms. B	esign gelizi uilding	ng g UX			
2: Defining the Look 3: Create a Sample F 4: Identify a custome 5: Conduct end-to-er	Thinking process for a product and Feel of any new Project Pattern Library for that product (Mood board, Fonts, Colors based o		(User					
		1 1 11	TO	EÁL:	45			
Course Outcomes APPROVED BY								
	purse, the student will be able to	, ,	6 NJ -2	07E	150			
CO1 Build UI	for user Applications	1 3	AN Z	075	1			



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CO2	Use the UI Interaction behaviors and principles
CO3	Evaluate UX design of any product or application
CO4	Demonstrate UX Skills in product development
CO5	Implement Sketching principles

- 1. UX for Developers: How to Integrate User-Centered Design Principles Into Your Day-to-Day Development Work, Westley Knight. Apress, 2018
- 2. The UX Book: Process and Guidelines for Ensuring a Quality User Experience, Rex Hartson, PardhaPyla. Morgan Kaufmann, 2012
- 3. UX Fundamentals for Non-UX Professionals: User Experience Principles for Managers, Writers, Designers, and Developers, Edward Stull. Apress, 2018
- 4. Lean UX: Designing Great Products with Agile Teams, Gothelf, Jeff, Seiden, and Josh. O'Reilly Media, 2016
- 5. Designing UX: Prototyping: Because Modern Design is Never Static, Ben Coleman, and Dan Goodwin. SitePoint, 2017





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P24OC520	DDINGIDLES OF MULTIMEDIA	L	Т	Р	С	
	PRINCIPLES OF MULTIMEDIA	3	0	0	3	
Course Objectives						
1. To get familiarity v	vith gamut of multimedia and its significance					
2. To acquire knowle	dge in multimedia components.					
3. To acquire knowledge about multimedia tools and authoring.						
4. To acquire knowledge in the development of multimedia applications.						
5. To explore the late	est trends and technologies in multimedia					
UNIT I INTRODUCT	ION			9	9	

Introduction to Multimedia – Characteristics of Multimedia Presentation – Multimedia Components – Promotionof Multimedia Based Components – Digital Representation – Media and Data Streams – MultimediaArchitecture – Multimedia Documents, Multimedia Tasks and Concerns, Production, sharing and distribution, Hypermedia, WWW and Internet, Authoring, Multimedia over wireless and mobile networks.

### **Suggested Activities:**

- 1. Flipped classroom on media Components.
- 2. External learning Interactive presentation.

### **Suggested Evaluation Methods:**

- 1. Tutorial Handling media components
- 2. Quizzes on different types of data presentation.

### **UNIT II ELEMENTS OF MULTIMEDIA**

9

Text-Types, Font, Unicode Standard, File Formats, Graphics and Image data representations – data types, fileformats, color models; video – color models in video, analog video, digital video, file formats, video displayinterfaces, 3D video and TV: Audio – Digitization, SNR, SQNR, quantization, audio quality, file formats, MIDI; Animation- Key Frames and Tweening, other Techniques, 2D and 3D Animation. Suggested Activities:

- 1. Flipped classroom on different file formats of various media elements.
- 2. External learning Adobe after effects, Adobe Media Encoder, Adobe Audition.

### **Suggested Evaluation Methods:**

- 1. Demonstration on after effects animations.
- 2. Quizzes on file formats and color models.

### **UNIT III MULTIMEDIA TOOLS**

9

Authoring Tools – Features and Types – Card and Page Based Tools – Icon and Object Based Tools – TimeBased Tools – Cross Platform Authoring Tools – Editing Tools – Painting and Drawing Tools – 3D Modelingand Animation Tools – Image Editing Tools – Sound Editing Tools – Digital Movie Tools.

### **Suggested Activities:**

- 1. Flipped classroom on multimedia tools.
- 2. External learning Comparison of various authoring tools.

### **Suggested Evaluation Methods:**

- 1. Tutorial Audio editing tool.
- 2. Quizzes on animation tools.





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### **UNIT IV MULTIMEDIA SYSTEMS**

9

Compression Types and Techniques: CODEC, Text Compression: GIF Coding Standards, JPEG standard –JPEG 2000, basic audio compression – ADPCM, MPEG Psychoacoustics, basic Video compression techniques – MPEG, H.26X – Multimedia Database System – User Interfaces – OS Multimedia Support – Hardware Support – Real Time Protocols – Play Back Architectures – Synchronization – Document Architecture – Hypermedia Concepts: Hypermedia Design – Digital Copyrights, Content analysis.

Suggested Activities:

- 1. Flipped classroom on concepts of multimedia hardware architectures.
- 2. External learning Digital repositories and hypermedia design.

### **Suggested Evaluation Methods:**

- 1. Quizzes on multimedia hardware and compression techniques.
- 2. Tutorial Hypermedia design.

### UNIT V MULTIMEDIA APPLICATIONS FOR THE WEB AND MOBILE PLATFORMS

9

ADDIE Model – Conceptualization – Content Collection – Storyboard–Script Authoring Metaphors – Testing –Report Writing – Documentation. Multimedia for the web and mobile platforms. Virtual Reality, Internet multimedia content distribution, Multimedia Information sharing – social media sharing, cloud computing for multimedia services, interactive cloud gaming. Multimedia information retrieval.

### **Suggested Activities:**

book)

- 1. External learning Game consoles.
- 2. External learning VRML scripting languages.

### **Suggested Evaluation Methods:**

- 1. Demonstration of simple interactive games.
- 2. Tutorial Simple VRML program.

		TOTAL	45			
	Course Outcomes					
At the en	d of the course, the student will be able to					
CO1	Handle the multimedia elements effectively.					
CO2	Articulate the concepts and techniques used in multimedia applications.					
CO3	CO3 Develop effective strategies to deliver Quality of Experience in multimedia applications.					
CO4	Design and implement algorithms and techniques applied to multimedia objects	6.				
CO5	Design and develop multimedia applications following software engineering mo	dels.				
REFERE	NCES					
1. Li, Ze-l	lian, Drew, Mark, Liu, Jiangchuan, "Fundamentals of Multimedia", Springer, Third	Edition, 20	21.			
2. Prabha	2. PrabhatK.Andleigh, Kiran Thakrar, "MULTIMEDIA SYSTEMS DESIGN", Pearson Education, 2015.					
3. Gerald	Friedland, Ramesh Jain, "Multimedia Computing", Cambridge University Press, 2	018. (digita				

4. Ranjan Parekh, "Principles of Multimedia", Second Edition, McGraw-Hill Education, 2017





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P24OC52	1  │ BLOCKCHAIN TECHNOLOGIES  ├	L 3	T 0	P 0	C 3
	Course Objectives	<u>ა  </u>	U	U	<u> </u>
This course is i	intended to study the basics of Blockchain technology				
	rse the learner will explore various aspects of Blockchain technology like	ann	licatio	าท	
in various doma		арр	noati	J11	
By implementing	ng, learners will have idea about private and public Blockchain, and smart	cor	tract		
UNIT I INTROI	DUCTION OF CRYPTOGRAPHY AND BLOCKCHAIN			9	9
ofBlockchain, E	Blockchain, Blockchain Technology Mechanisms & Networks, Blockchain Blockchain Challenges, Transactions and Blocks, P2P Systems, Keys as I shing, and public key cryptosystems, private vs. public Blockchain.				
UNIT II BITCO	IN AND CRYPTOCURRENCY			,	9
Wallets, Decen	Bitcoin, The Bitcoin Network, The Bitcoin Mining Process, Mining Develop stralization and Hard Forks, Ethereum Virtual Machine (EVM), Merkle Tree schain and Digital Currency, Transactional Blocks, Impact of Blockchain Te	e, D	ouble	-Spe	
UNIT III INTRO	DDUCTION TO ETHEREUM			9	
	Ethereum, Consensus Mechanisms, Metamask Setup, Ethereum Accounters, Smart Contracts	ts, ,	Tran	sactio	ns,
UNIT-IV INTRO	DDUCTION TO HYPERLEDGER AND SOLIDITY PROGRAMMING			9	9
Ledger Techno Installing Solidi SmartContract	Hyperledger, Distributed Ledger Technology & its Challenges, Hyperledge blogy, Hyperledger Fabric, Hyperledger Composer. Solidity - Language of ity &Ethereum Wallet, Basics of Solidity, Layout of a Solidity Source File & s, General Value Types.  KCHAIN APPLICATIONS	Sm	art C	ontrac e of	
Internet of Thir AltCoins.	ngs, Medical Record Management System, Domain Name Service and Fut	ture	of B	ockcł	nain,
			TO	ΓAL	45
	Course Outcomes				
At the end of t	the course, the student will be able to				
CO1 Un	derstand and explore the working of Blockchain technology				
CO2 An	alyze the working of Smart Contracts				
CO3 Un	derstand and analyze the working of Hyperledger				
<b>CO4</b> Ap	ply the learning of solidity to build de-centralized apps on Ethereum				
CO5 De	velop applications on Blockchain				





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- 1. Imran Bashir, "Mastering Blockchain: Distributed Ledger Technology, Decentralization, and Smart Contracts Explained", Second Edition, Packt Publishing, 2018.
- 2. Narayanan, J. Bonneau, E. Felten, A. Miller, S. Goldfeder, "Bitcoin and Cryptocurrency Technologies: A Comprehensive Introduction" Princeton University Press, 2016
- 3. Antonopoulos, Mastering Bitcoin, O'Reilly Publishing, 2014.
- 4. Antonopoulos and G. Wood, "Mastering Ethereum: Building Smart Contracts and Dapps", O'Reilly Publishing, 2018
- 5. D. Drescher, Blockchain Basics. Apress, 2017

CO, PO Mapping								
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3		
CO1	2	2	2	2	-	-		
CO2	1	1	1	2	-	-		
CO3	3	2	3	3	-	-		
CO4	2	3	1	2	-	-		
CO5	2	2	2	1	-	-		
AVG	2	2	1	2	-	-		





D0400500	DEED LEADANNO		T	Р	С		
P24OC522	DEEP LEARNING	3	0	0	3		
	Course Objectives						
1. Develop and Train	Deep Neural Networks.						
2. Develop a CNN, F	R-CNN, Fast R-CNN, Faster-R-CNN, Mask-RCNN for detection and	rec	ogniti	on			
3. Build and train RN	INs, work with NLP and Word Embeddings						
4. The internal struct	ure of LSTM and GRU and the differences between them						
5. The Auto Encoder	s for Image Processing						
UNIT I DEEP LEARI	NING CONCEPTS			(	6		
Neural Networks. Ho	Deep Learning. Perception Learning Algorithms. Probabilistic mode by Deep Learning different from Machine Learning. Scalars. Vectors Tensors. Manipulating Tensors. Vector Data. Time Series Data. Ima	s. M	atrixe	s,			
UNIT II NEURAL NE	TWORKS			!	9		
	rk. Building Blocks of Neural Network. Optimizers. Activation Functi- processing for neural networks, Feature Engineering. Overfitting ar arameters.		Loss				
UNIT III CONVOLUT	TIONAL NEURAL NETWORK			1	0		
Input Layers, Convol Convolutional Layer. Layers and Regulari AlexNet, VGG16, Re	Time Invariant. Image Processing Filtering. Building a convolutional lution Layers. Pooling Layers. Dense Layers. Back propagation Thr Filters and Feature Maps. Back propagation Through the Pooling Logical Eation. Batch Normalization. Various Activation Functions. Various CosNet. Transfer Learning with Image Data. Transfer Learning using Inception Model, MicrosoftResNet Model. R-CNN, Fast R-CNN, Factorial Processing Processin	ougl ₋aye )ptin Ince	n the ers. D nizers ption	ropou s. LeN Oxfo	it let, rd		
UNIT VI NATURAL I	LANGUAGE PROCESSING USING RNN			1	0		
About NLP & its Toolkits. Language Modeling. Vector Space Model (VSM). Continuous Bag of Words (CBOW). Skip-Gram Model for Word Embedding. Part of Speech (PoS) Global Co-occurrence Statistics—based Word Vectors. Transfer Learning. Word2Vec. Global Vectors for WordRepresentation GloVe. Backpropagation Through Time. Bidirectional RNNs (BRNN). Long ShortTerm Memory (LSTM). Bidirectional LSTM. Sequence-to-Sequence Models (Seq2Seq). Gatedrecurrent unit GRU.							
UNIT V DEEP REINI	FORCEMENT & UNSUPERVISED LEARNING			1	0		
Critic Algorithm. Abo Adversarial Network	cement Learning. Q-Learning. Deep Q-Network (DQN). Policy Grad out Autoencoding. Convolutional Auto Encoding. Variational AutoEncos. Autoencoders for Feature Extraction. Auto Encoders for Classification. Sparse Autoencoders	codi	ng. G				
0	· · · · · · · · · · · · · · · · · · ·						





	Course Outcomes						
At the end	At the end of the course, the student will be able to						
CO1	CO1 Feature Extraction from Image and Video Data						
CO2	Implement Image Segmentation and Instance Segmentation in Images						
соз	Implement image recognition and image classification using a pretrained network (Transfer68 Learning)						
CO4	Traffic Information analysis using Twitter Data						
CO5	Autoencoder for Classification & Feature Extraction						
REFEREN	ICES						
1. Deep Le Inc.2017	earning A Practitioner's Approach Josh Patterson and Adam Gibson O'Reilly Media,						
2. Learn K	Ceras for Deep Neural Networks, JojoMoolayil, Apress,2018						
3. Deep Lo	earning Projects Using TensorFlow 2, Vinita Silaparasetty, Apress, 2020						
4. Deep Learning with Python, FRANÇOIS CHOLLET, MANNING SHELTER ISLAND,2017							
5. Pro Deep Learning with TensorFlow, SantanuPattanayak, Apress,2017							





CO1

## Meenakshi Sundararajan Engineering College

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Department: Electrical and Electronics Engineering, R2024, CBCS
M.E. Embedded System Technologies

P240M523   VIBRATION AND NOISE CONTROL STRATEGIES   L   T   P   C   C   3   0   0   3   COURSE OBJECTIVES		W.L. Embedded System Technologies								
COURSE OBJECTIVES  1. To appreciate the basic concepts of vibration in damped and undamped systems 2. To appreciate the basic concepts of noise, its effect on hearing and related terminology 3. To use the instruments for measuring and analyzing the vibration levels in a body 4. To use the instruments for measuring and analyzing the noise levels in a system 5. To learn the standards of vibration and noise levels and their control techniques  UNIT I BASICS OF VIBRATION  9 Introduction - Sources and causes of Vibration-Mathematical Models - Displacement, velocity and Acceleration - Classification of vibration: free and forced vibration, undamped and damped vibration, linear and non-linear vibration - Single Degree Freedom Systems - Vibration isolation - Determination of natural frequencies  UNIT II BASICS OF NOISE  9 Introduction - Anatomy of human ear - Mechanism of hearing - Amplitude, frequency, wavelength and sound pressure level - Reliationship between sound power, sound intensity and sound pressure level - Addition, subtraction and averaging decibel levels - sound spectra -Types of sound fields - Octave band analysis - Loudness.  UNIT II INSTRUMENTATION FOR VIBRATION MEASUREMENT  9 Experimental Methods in Vibration Analysis Vibration Measuring Instruments - Selection of Sensors - Accelerometer Mountings - Vibration Exciters - Mechanical, Hydraulic, Electromagnetic and Electrodynamics - Frequency Measuring Instruments - System Identification from Frequency Response - Testing for resonance and mode shapes  UNIT IV INSTRUMENTATION FOR NOISE MEASUREMENT AND ANALYSIS  9 Microphones - Weighting networks - Sound Level meters, its classes and calibration - Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.  UNIT V METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS  OCONTROL  Specification of Vibration Limits - Vibration severity standards - Vibration as condition Mo	P24OM523	VIBRATION AND NOISE CONTROL STRATEGIES			-					
2. To appreciate the basic concepts of noise, its effect on hearing and related terminology 3. To use the instruments for measuring and analyzing the vibration levels in a body 4. To use the instruments for measuring and analyzing the noise levels in a system 5. To learn the standards of vibration and noise levels and their control techniques  UNIT I BASICS OF VIBRATION  Introduction - Sources and causes of Vibration-Mathematical Models - Displacement, velocity and Acceleration - Classification of vibration: free and forced vibration, undamped and damped vibration, linear and non-linear vibration - Single Degree Freedom Systems - Vibration isolation - Determination of natural frequencies  UNIT II BASICS OF NOISE  9 Introduction - Anatomy of human ear - Mechanism of hearing - Amplitude, frequency, wavelength and sound pressure level - Relationship between sound power, sound intensity and sound pressure level - Addition, subtraction and averaging decibel levels - sound spectra -Types of sound fields - Octave band analysis - Loudness.  UNIT III INSTRUMENTATION FOR VIBRATION MEASUREMENT  9 Experimental Methods in Vibration Analysis Vibration Measuring Instruments - Selection of Sensors - Accelerometer Mountings - Vibration Exciters - Mechanical, Hydraulic, Electromagnetic and Electrodynamics - Frequency Measuring Instruments - System Identification from Frequency Response -Testing for resonance and mode shapes  UNIT IV INSTRUMENTATION FOR NOISE MEASUREMENT AND ANALYSIS  9 Microphones - Weighting networks - Sound Level meters, its classes and calibration - Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.  UNIT V METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS  CONTROL  Specification of Vibration Limits - Vibration severity standards - Vibration as condition Monitoring Tool - Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber - Need for Balan		COURSE OBJECTIVES	ر ح	-	U					
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UNIT I BASICS OF VIBRATION 9 Introduction - Sources and causes of Vibration-Mathematical Models - Displacement, velocity and Acceleration - Classification of vibration: free and forced vibration, undamped and damped vibration, linear and non-linear vibration - Single Degree Freedom Systems - Vibration isolation - Determination of natural frequencies  UNIT II BASICS OF NOISE 9 Introduction - Anatomy of human ear - Mechanism of hearing - Amplitude, frequency, wavelength and sound pressure level - Relationship between sound power, sound intensity and sound pressure level - Addition, subtraction and averaging decibel levels - sound spectra - Types of sound fields - Octave band analysis - Loudness.  UNIT III INSTRUMENTATION FOR VIBRATION MEASUREMENT 9 Experimental Methods in Vibration Analysis - Vibration Measuring Instruments - Selection of Sensors - Accelerometer Mountings - Vibration Exciters - Mechanical, Hydraulic, Electromagnetic and Electrodynamics - Frequency Measuring Instruments - System Identification from Frequency Response - Testing for resonance and mode shapes  UNIT IV INSTRUMENTATION FOR NOISE MEASUREMENT AND ANALYSIS 9 Microphones - Weighting networks - Sound Level meters, its classes and calibration - Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.  UNIT V METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS CONTROL  Specification of Vibration Limits - Vibration severity standards - Vibration as condition Monitoring Tool - Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber - Need for Balancing - Static and Dynamic Balancing machines - Field balancing - Major sources of noise - Noise survey techniques - Measurement technique for vehicular noise - Road vehicles Noise standard - Noise work techniques - Measurement technique for vehicular noise - Road vehicles Noise standard - Noise control at the receiver Sound transmission throu			•							
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Accelerometer Mountings - Vibration Exciters - Mechanical, Hydraulic, Electromagnetic and Electrodynamics - Frequency Measuring Instruments System Identification from Frequency Response - Testing for resonance and mode shapes  UNIT IV INSTRUMENTATION FOR NOISE MEASUREMENT AND ANALYSIS  Microphones - Weighting networks - Sound Level meters, its classes and calibration - Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.  UNIT V METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS CONTROL  Specification of Vibration Limits - Vibration severity standards - Vibration as condition Monitoring Tool - Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber - Need for Balancing - Static and Dynamic Balancing machines - Field balancing - Major sources of noise - Noise survey techniques - Measurement technique for vehicular noise - Road vehicles Noise standard - Noise due to construction equipment and domestic appliances - Industrial noise sources and its strategies - Noise control at the source - Noise control along the path - Acoustic Barriers - Noise control at the receiver Sound transmission through barriers - Noise reduction Vs Transmission loss - Enclosures  Course Outcomes	UNIT III INSTRUME	NTATION FOR VIBRATION MEASUREMENT			Ş	•				
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Noise measurements using sound level meters - Data Loggers - Sound exposure meters - Recording of noise - Spectrum analyser - Intensity meters - Energy density sensors - Sound source localization.  UNIT V METHODS OF VIBRATION CONTROL, SOURCES OF NOISE AND ITS CONTROL  Specification of Vibration Limits – Vibration severity standards - Vibration as condition Monitoring Tool – Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber – Need for Balancing - Static and Dynamic Balancing machines – Field balancing - Major sources of noise - Noise survey techniques – Measurement technique for vehicular noise - Road vehicles Noise standard – Noise due to construction equipment and domestic appliances – Industrial noise sources and its strategies – Noise control at the source – Noise control along the path – Acoustic Barriers – Noise control at the receiver Sound transmission through barriers – Noise reduction Vs Transmission loss - Enclosures  Course Outcomes	UNIT IV INSTRUME	NTATION FOR NOISE MEASUREMENT AND ANALYSIS			Ş	•				
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Course Outcomes APPROVED BY	Case Studies - Vibration Isolation methods - Dynamic Vibration Absorber - Need for Balancing - Static and Dynamic Balancing machines - Field balancing - Major sources of noise - Noise survey techniques - Measurement technique for vehicular noise - Road vehicles Noise standard - Noise due to construction equipment and domestic appliances - Industrial noise sources and its strategies - Noise control at the source - Noise control along the path - Acoustic Barriers - Noise control at the receiver Sound transmission through barriers - Noise reduction Vs Transmission loss - Enclosures									
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Apply the basic concepts of vibration in damped and undamped systems

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CO2	Apply the basic concepts of noise and to understand its effects on systems
CO3	Select the instruments required for vibration measurement and its analysis
CO4	Select the instruments required for noise measurement and its analysis.
CO5	Recognize the noise sources and to control the vibration levels in a body and to control noise under different strategies.

- 1. Singiresu S. Rao, "Mechanical Vibrations", Pearson Education Incorporated, 2017.
- 2. Graham Kelly. Sand Shashidhar K. Kudari, "Mechanical Vibrations", Tata McGraw –Hill Publishing Com. Ltd., 2007.
- 3. Ramamurti. V, "Mechanical Vibration Practice with Basic Theory", Narosa Publishing House, 2000.
- 4. William T. Thomson, "Theory of Vibration with Applications", Taylor & Francis, 2003.
- 5. G.K. Grover, "Mechanical Vibrations", Nem Chand and Bros., Roorkee, 2014.
- 6. A.G. Ambekar, "Mechanical Vibrations and Noise Engineering", PHI Learning Pvt. Ltd., 2014.
- 7. David A. Bies and Colin H. Hansen, "Engineering Noise Control Theory and Practice", Spon Press, London and New York, 2009.





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		•							
P240N	1524	ENERGY CONSERVATION AND MANAGEMENT IN DOMESTIC SECTORS	L	T	Р	С			
			3	0	0	3			
		Course Objectives							
1		present energy scenario and the need for energy conservation.							
To understand the different measures for energy conservation in utilities.									
<ol><li>Acquaint students with principle theories, materials, and construction techniques to create energy efficient buildings.</li></ol>									
I	4. To identify the energy demand and bridge the gap with suitable technology for sustainable habitat								
		iar with the energy technology, current status of research and stem as per the user requirement	fin	d the	way	s to			
UNIT I ENI	ERGY SC	ENARIO				9			
	icing, En	ources - Sectorial energy consumption (domestic, industrial an ergy conservation and its importance, Energy Conservation star rating.							
UNIT II HE	ATING, V	ENTILLATION & AIR CONDITIONING			!	9			
		ion and Air Conditioning $-$ COP $/$ EER $/$ SEC Evaluation $-$ lar Refrigeration.	SPV	syst	em d	esign			
UNIT III LI	GHTING,	COMPUTER, TV			,	9			
		naries – Types – Efficacy – Selection & Application – Time Sensor inservation measures in computer – Television – Electronic devices		Occup	pancy				
UNIT IV E	NERGY I	EFFICIENT BUILDINGS				9			
I		s Energy efficient buildings – Landscape design – Envelope h ng and heating – Renewable sources integration.	eat	loss	and	heat			
UNIT V EI	NERGY S	TORAGE TECHNOLOGIES			,	9			
	⊢ Hydro	energy storage – Thermal energy storage – Battery energy storage gen energy storage & Super capacitors – energy density and							
				TO	ΓAL	45			
		Course Outcomes							
At the end		purse, the student will be able to							
CO1	Understand technical aspects of energy conservation scenario.								
CO2	Energy a	audit in any type for domestic buildings and suggest the conservation	on m	neasu	res.				
CO3	Perform	Perform building load estimates and design the energy efficient landscape system.							
CO4	Gain kno	Sain knowledge to utilize an appliance/device sustainably.							
CO5 Understand the status and current technological advancement in energy storage field.									
REFEREN	CES:	(2)			No. of	150			

1. Yogi Goswami, Frank Kreith, Energy Efficiency and Renewable energy Handbook, CRC Press,



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### 2016

- 2. ASHRAE Handbook 2020 HVAC Systems & Equipment
- 3. Paolo Bertoldi, Andrea Ricci, Anibal de Almeida, Energy Efficiency in Household Appliances and Lighting, Conference proceedings, Springer, 2001
- 4. David A. Bainbridge, Ken Haggard, Kenneth L. Haggard, Passive Solar Architecture: Heating, Cooling, Ventilation, Daylighting, and More Using Natural Flows, Chelsea Green Publishing, 2011.
- 5. Guide book for National Certification Examination for Energy Managers and Energy Auditors (Could be downloaded from www.energymanagertraining.com)
- 6. Ibrahim Dincer and Mark A. Rosen, Thermal Energy Storage Systems and Applications, John Wiley & Sons 2002.
- 7. Robert Huggins, Energy Storage: Fundamentals, Materials and Applications, 2nd edition, Springer, 2015
- 8. Ru-shiliu, Leizhang, Xueliang sun, Electrochemical technologies for energy storage and conversion, Wiley publications, 2012.





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DOLOMESE		L	Т	Р	С			
P24OM525	ADDITIVE MANUFACTURING	3	0	0	3			
UNIT I INTRODUCTION								
	Need - Development - Rapid Prototyping Rapid Tooling – Rapid Manufacturing – Addit Manufacturing. AM Process Chain- Classification – Benefits.							
UNIT II DESIGN FOI	R ADDITIVE MANUFACTURING			,	9			
CAD Model Preparation - Part Orientation and Support Structure Generation -Model Slicing - Tool Path Generation Customized Design and Fabrication - Case Studies.								
UNIT III VAT POLYMERIZATION								
Stereolithography Apparatus (SLA)- Materials -Process -Advantages Limitations- Applications. Digital Light Processing (DLP) - Materials – Process - Advantages - Applications. Multi Jet Modelling (MJM) - Principles - Process - Materials - Advantages and Limitations.								
UNIT IV MATERIAL EXTRUSION AND SHEET LAMINATION								

Fused Deposition Modeling (FDM)- Process-Materials - Applications and Limitations. Sheet Lamination Process: Laminated Object Manufacturing (LOM)- Basic Principle- Mechanism: Gluing or Adhesive Bonding - Thermal Bonding- Materials- Application and Limitation - Bio-Additive Manufacturing Computer Aided Tissue Engineering (CATE) - Case studies

### POWDER BASED PROCESS

Selective Laser Sintering (SLS): Process –Mechanism– Typical Materials and Application- Multi Jet Fusion - Basic Principle— Materials- Application and Limitation - Three Dimensional Printing - Materials -Process - Benefits and Limitations. Selective Laser Melting (SLM) and Electron Beam Melting (EBM): Materials – Process - Advantages and Applications. Beam Deposition Process: Laser Engineered Net Shaping (LENS)- Process -Material Delivery - Process Parameters - Materials - Benefits -Applications.

### UNIT V CASE STUDIES AND OPPORTUNITIES ADDITIVE MANUFACTURING PROCESSES

Education and training - Automobile- pattern and mould - tooling - Building Printing-Bio Printing - medical implants -development of surgical tools Food Printing -Printing Electronics. Business Opportunities and Future Directions - Intellectual Property.

TOTAL 45

9

### **REFERENCES**

- 1. Andreas Gebhardt and Jan-Steffen Hötter "Additive Manufacturing: 3D Printing for Prototyping and Manufacturing", Hanser publications, United States, 2015, ISBN: 978-1-56990-582-1.
- 2. Ian Gibson, David W. Rosen and Brent Stucker "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing", 2nd edition, Springer., United States, 2015, ISBN13: 978-1493921126.
- 3. Amit Bandyopadhyay and Susmita Bose, "Additive Manufacturing", 1st Edition, CRC Press., United States, 2015, ISBN-13: 978-1482223590
- 4. Andreas Gebhardt, "Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing", Hanser Gardner Publication, Cincinnati., Ohio, 2011, ISBN :9783446425521.
- 5. Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", Third edition, World Scientific Publishers, 2010.

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P24OM526	ELECTRIC VEHICLE TECHNOLOGY	L	Т	Р	С
		3	0	0	3
UNIT I NEED FOR ELECTRIC VEHICLES					

History and need for electric and hybrid vehicles, social and environmental importance of hybrid and electric vehicles, impact of modern drive-trains on energy supplies, comparison of diesel, petrol, electric and hybrid vehicles, limitations, technical challenges

### UNIT II ELECTRIC VEHICLE ARCHITECHTURE

9

Electric vehicle types, layout and power delivery, performance – traction motor characteristics, tractive effort, transmission requirements, vehicle performance, energy consumption, Concepts of hybrid electric drive train, architecture of series and parallel hybrid electric drive train, merits and demerits, mild and full hybrids, plug-in hybrid electric vehicles and range extended hybrid electric vehicles, Fuel cell vehicles.

### **UNIT III ENERGY STORAGE**

9

Batteries – types – lead acid batteries, nickel based batteries, and lithium based batteries, electrochemical reactions, thermodynamic voltage, specific energy, specific power, energy efficiency, Battery modeling and equivalent circuit, battery charging and types, battery cooling, Ultra-capacitors, Flywheel technology, Hydrogen fuel cell, Thermal Management of the PEM fuel cell

### UNIT IV ELECTRIC DRIVES AND CONTROL

9

Types of electric motors – working principle of AC and DC motors, advantages and limitations, DC motor drives and control, Induction motor drives and control, PMSM and brushless DC motor - drives and control, AC and Switch reluctance motor drives and control – Drive system efficiency – Inverters – DC and AC motor speed controllers

### **UNIT V DESIGN OF ELECTRIC VEHICLES**

9

Materials and types of production, Chassis skate board design, motor sizing, power pack sizing, component matching, Ideal gear box – Gear ratio, torque–speed characteristics, Dynamic equation of vehicle motion, Maximum tractive effort – Power train tractive effort Acceleration performance, rated vehicle velocity – maximum gradability, Brake performance, Electronic control system, safety and challenges in electric vehicles. Case study of Nissan leaf, Toyota Prius, tesla model 3, and Renault Zoe cars.

TOTAL 45

### **REFERENCES**

- 1. Iqbal Hussein, Electric and Hybrid Vehicles: Design Fundamentals, 2nd edition CRC Press, 2011.
- 2. Mehrdad Ehsani, Yimi Gao, Sebastian E. Gay, Ali Emadi, Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design, CRC Press, 2004.
- 3. James Larminie, John Lowry, Electric Vehicle Technology Explained Wiley, 2003, PPROVED
- 4. Ehsani, M, "Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design", CRC Press, 2005

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P24OC527		NEW PRODUCT DEVELOPMENT	L	Т	Р	С
1 240		NEW I NOBOST BEVEEST IMENT	3	0	0	3
		Course Objectives				
		inciples of generic development process; and understanding th duct design and development.	e c	rgani	zatior	ı
2. Identify	ing oppo	rtunity and planning for new product design and development.				
<ol><li>Conduand develo</li></ol>	•	tomer need analysis; and setting product specification for new	pro	oduct	desig	jn
4. Genera	ating, sele	cting, and testing the concepts for new product design and develop	mei	nt.		
5. Applyii developme		principles of Industrial design and prototype for new produ	ıct	desig	n ar	ıd
UNIT I INT	RODUCT	ION TO PRODUCTDESIGN & DEVELOPMENT			9	9
Design an Product Do End Proce	d Develop evelopme ss – Ada	acteristics of Successful Product Development – People involvencement – Duration and Cost of Product Development – The Chant – The Product Development Process – Concept Development process – Product Development Process – Product Deduct Development Organizations.	nalle ent:	enges The	of Front	
UNIT II OP	PORTUN	ITY DENTIFICATION & PRODUCT PLANNING			ç	9
Opportunity	/ Identifica	ation: Definition – Types of Opportunities – Tournament Struc ation – Effective Opportunity Tournaments – Opportunity Id t Planning: Four types of Product Development Projects – The Proc	lenti	ificatio		
UNIT III ID	ENTIFYI	NG CUSTOMER NEEDS & PRODUCT SPECIFICATIONS			Ç	9
Needs. Pro	duct Spe	Needs: The Importance of Latent Needs – The Process of Identify cifications: Definition – Time of Specifications Establishment – Establing the Final Specifications				
UNIT IV CO	ONCEPT (	GENERATION, SELECTION & TESTING			ç	•
Concept G	eneration	: Activity of Concept Generation – Structured Approach – Five . Concept Selection: Methodology – Concept Screening and Concept Selection: Methodology – Concept Screening and Concept Step activities of concept testing.				
UNIT V INDUSTRIAL DESIGN & PROTOTYPING						9
		ed and Impact–Industrial Design Process. Prototyping – Principles ogies – Planning for Prototypes.	of F	Prototy	/ping	_
				TO	ΓAL	45
		Course Outcomes				
At the end		27 12	10000	RTM		-
CO1		e principles of generic development process; and understand to for new product design and development.	the PRO	orgai DVED	nizatio BY	12 J
CO2	Identify o	pportunity and plan for new product design and development.	J	AN Z	025	m



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соз	Conduct customer need analysis; and set product specification for new product design and development.
CO4	Generate, select, and test the concepts for new product design and development.
CO5	Apply the principles of Industrial design and prototype for design and develop new products.

### **TEXT BOOK:**

1. Ulrich K.T., Eppinger S. D. and Anita Goyal, "Product Design and Development "McGraw-Hill Education; 7 edition, 2020.

- 1. Belz A., 36-Hour Course: "Product Development" McGraw-Hill, 2010.
- 2. Rosenthal S., "Effective Product Design and Development", Business One Orwin, Homewood, 1992, ISBN 1-55623-603-4.
- 3. Pugh.S, "Total Design Integrated Methods for Successful Product Engineering", Addison Wesley Publishing, 1991, ISBN 0-202-41639-5.
- 4. Chitale, A. K. and Gupta, R. C., Product Design and Manufacturing, PHI Learning, 2013.
- 5. Jamnia, A., Introduction to Product Design and Development for Engineers, CRC Press, 2018.





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P2400	C528	INTEGRATED WATER RESOURCES MANAGEMENT	L 3	T 0	P 0	C 3	
		Course Objectives					
01 1 1		=	<b>.</b>				
		duced to the concepts and principles of IWRM, which is inclusive o ivate partnership, water & health, water & food security and legal &			у		
UNIT I COI	NTEXT FO	DR IWRM			!	9	
Keyelemen	ts of IWR	sue: key challenges – Definition of IWRM within the broader contex M - Principles – Paradigm shift in water management - Complexity Water Assessment - SDGs.				nt –	
UNIT II WA	TER ECC	DNOMICS			,	9	
monetary v	aluation n	nter issues: economic characteristics of water good and services – nethods – Water economic instruments – Private sector involvement ent: PPP objectives, PPP models, PPP processes, PPP experience	nt in	water	•	e	
UNIT III LE	GAL AND	REGULATORY SETTINGS			,	9	
manageme lawfor grou	nt - Unde ndwater n	nd governance: principles of international and national law in the al rstanding UN law on non-navigable uses of international water cou nanagement – World Water Forums – Global Water Partnerships - al and regulatory framework	rses	– Inte	ernati		
UNIT IV W	ATER AN	D HEALTH WITHIN THE IWRM CONTEXT			!	9	
protection a	and promo	and health: options to include water management interventions for otion in the context of IWRM – Global burden of Diseases - Health is evelopment projects – Case studies					
UNIT V AG	RICULTU	IRE IN THE CONCEPT OF IWRM			,	9	
	lobal wate	ction: 'blue' versus 'green' water debate – Water foot print - Virtual er and food security –- Irrigation efficiencies, irrigation methods - cook pricing.					
				TO	Γ <b>AL</b>	45	
		Course Outcomes					
At the end	of the co	ourse, the student will be able to					
CO1	Describe the context and principles of IWRM; Compare the conventional and integrated ways of watermanagement						
CO2	Select the best economic option among the alternatives; illustrate the pros and cons of PPP throughcase studies.						
CO3	Apply law and governance in the context of IWRM.						
CO4	Discuss	the linkages between water-health; develop a HIA framework.	PAF	RTME	EN/E		
CO5	Analyse how the virtual water concept pave way to alternate policy options						

### **REFERENCES**

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CO, PO Mapping									
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3			
CO1	2	2	2	3	2	2			
CO2	2	2	2	2	2	2			
CO3	2	2	2	2	2	2			
CO4	2	2	2	2	2	2			
CO5	2	2	2	2	2	2			
AVG	2	2	2	2	2	2			





P24ON529		WATER SANITATION AND HEALTH		L	Т	Р	С
P24UN3	029	WATER, SANITATION AND HEALTH		3	0	0	3
		Course Objectives					
		erating health impacts due to the present managerial aspec and health sectors in the developing scenario	ts and	initia	atives	in	
UNIT I FUND	AMENT	ALS WASH				,	9
issues-Water	r security	on: Safe Water- Health, Nexus: Water- Sanitation - Health a - Food Security. Sanitation And Hygiene (WASH) and Integ - Need and Importance of WASH					
<b>UNIT II MAN</b>	AGERIA	L IMPLICATIONS AND IMPACT				!	9
Factors conto LiteracyDem Washed and	ribute to ography Water B	<ul> <li>Poor and Multidimensional DeprivationHealth Burden in water, sanitation and hygiene related diseases-Social: Social Population and Migration- Fertility - Mortality- Environment: ased Diseases - Economic: Wage - Water and Health Budge Relapse - Political: Political Will</li> </ul>	al Strat : Wateı	ifica Bor	tion a ne-W	nd /ater	
UNIT III CHA	LLENG	ES IN MANAGEMENT AND DEVELOPMENT				,	9
Infrastructure	e-Service	in WASH - Bureaucracy and Users- Water Utilities -Sectora Delivery: Health services: Macro and Micro- level: Commu gm Shift: Democratization of Reforms and Initiatives				Issue	es-
UNIT IV GOV	/ERNAN	CE				!	9
Investments	on Wate	unity Health Assessment and Improvement Planning (CHA/0 r, (WASH) - Cost Benefit Analysis – Institutional Interventior rectives - Social Insurance -Political Will vs Participatory Go	า <b>-</b> Pub <sup>l</sup> lio	c Pri	vate	ture a	nd
UNIT V INITI	ATIVES					,	9
Developmen	t-Global	elopment -Accelerating Development- Development Indicate				lans -	
	on -Cap	and Local- Millennium Development Goal (MDG) and Targe acity Building - Case studies on WASH	els - FIV				45
	on -Cap	and Local- Millennium Development Goal (MDG) and Targe acity Building - Case studies on WASH	elS - FIV		TO		45
A441		and Local- Millennium Development Goal (MDG) and Targe acity Building - Case studies on WASH  Course Outcomes	eis - riv				45
CO1	<b>of the co</b>	Course Outcomes urse, the student will be able to fundamental concepts and terms which are to be applied a			ТО		45
CO1 (2	of the co Capture tall throug	and Local- Millennium Development Goal (MDG) and Targe acity Building - Case studies on WASH  Course Outcomes  urse, the student will be able to	and un	ders	TO1	ΓAL	45
CO1 (2)	of the co Capture t all throug Compreh	Course Outcomes  Course Outcomes  Urse, the student will be able to  of fundamental concepts and terms which are to be applied and the study.  end the various factors affecting water sanitation and health orld scenario.  analyse and articulate the underlying common challenges in	and un	ders Jh th	TO:	Γ <b>AL</b>	45
CO1 (a) (c) (c) (c) (c) (c) (d) (d) (d) (d) (d) (d) (d) (d) (d) (d	of the co Capture tall throug Comprehof third w Critically and healt	Course Outcomes  Course Outcomes  Urse, the student will be able to  of fundamental concepts and terms which are to be applied and the study.  end the various factors affecting water sanitation and health orld scenario.  analyse and articulate the underlying common challenges in	and und through	ders gh th	tood e lens	Γ <b>AL</b> S	45



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- 6. Third World Network.org (www.twn.org)

	CO, PO Mapping									
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	1	2	1	-	-	-				
CO2	1	2	1	3	3	3				
CO3	1	2	1	3	2	3				
CO4	1	2	1	3	3	3				
CO5	1	2	1	3	3	2				
AVG	1	2	1	3	3	3				





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P24ON530	PRINCIPLES OF SUSTAINABLE DEVELOPMENT	L	T	Р	C
P240N530	PRINCIPLES OF SUSTAINABLE DEVELOPMENT	3	0	0	3

### **Course Objectives**

To impart knowledge on environmental, social and economic dimensions of sustainability and the principles evolved through landmark events so as to develop an action mindset for sustainable development.

### UNIT I SUSTAINABILITY AND DEVELOPMENT CHALLEGES

9

Definition of sustainability – environmental, economical and social dimensions of sustainability - sustainable development models – strong and weak sustainability – defining development- millennium development goals – mindsets for sustainability: earthly, analytical, precautionary, action and collaborative – syndromes of global change: utilisation syndromes, development syndromes, and sink syndromes – core problems and crosscutting Issues of the 21 century - global, regional and local environmental issues – social insecurity – resource degradation –climate change – desertification.

### **UNIT II PRINCIPLES AND FRAME WORK**

9

History and emergence of the concept of sustainable development - our common future - Stockholm to Rio plus 20– Rio Principles of sustainable development – Agenda 21 natural step- peoples earth charter – business charter for sustainable development –UN Global Compact - Role of civil society, business and government – United Nations' 2030 Agenda for sustainable development – 17 sustainable development goals and targets, indicators and intervention areas

### UNIT III SUSTAINABLE DEVELOPMENT AND WELLBEING

9

The Unjust World and inequities - Quality of Life - Poverty, Population and Pollution - Combating Poverty - - Demographic dynamics of sustainability - Strategies to end Rural and Urban Poverty and Hunger – Sustainable Livelihood Framework- Health, Education and Empowerment of Women, Children, Youth, Indigenous People, Non-Governmental Organizations, Local Authorities and Industry for Prevention, Precaution, Preservation and Public participation.

### UNIT IV SUSTAINABLE SOCIO-ECONOMIC SYSTEMS

10

Sustainable Development Goals and Linkage to Sustainable Consumption and Production – Investing in Natural Capital- Agriculture, Forests, Fisheries - Food security and nutrition and sustainable agriculture-Waterand sanitation - Biodiversity conservation and Ecosystem integrity –Ecotourism - Sustainable Cities – Sustainable Habitats- Green Buildings - Sustainable Transportation — Sustainable Mining - Sustainable Energy – Climate Change – Mitigation and Adaptation - Safeguarding Marine Resources - Financial Resources and Mechanisms

### **UNIT V ASSESSING PROGRESS AND WAY FORWARD**

8

Nature of sustainable development strategies and current practice- Sustainability in global, regional and national context –Approaches to measuring and analysing sustainability– limitations of GDP- Ecological Footprint- Human Development Index- Human Development Report – National initiatives for Sustainable Development - Hurdles to Sustainability - Science and Technology for sustainable development – Performanceindicators of sustainability and Assessment mechanism – Inclusive Green Growth and Green Economy –National Sustainable Development Strategy Planning and National Status of Sustainable Development Goals

TOTAL

45





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	Course Outcomes							
At the en	At the end of the course, the student will be able to							
CO1	Explain and evaluate current challenges to sustainability, including modern world social, environmental, and economic structures and crises.							
CO2	Identify and critically analyze the social environmental, and economic dimensions of sustainability in terms of UN Sustainable development goals							
CO3	Develop a fair understanding of the social, economic and ecological linkage of Human well being, production and consumption							
CO4	Evaluate sustainability issues and solutions using a holistic approach that focuses on connections between complex human and natural systems.							
CO5	Integrate knowledge from multiple sources and perspectives to understand environmental limits governing human societies and economies and social justice dimensions of sustainability							

- 1. Tom Theis and Jonathan Tomkin, Sustainability: A Comprehensive Foundation, Rice University, Houston, Texas, 2012
- 2. A guide to SDG interactions:from science to implementation, International Council for Science, Paris, 2017
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- 4. The New Global Frontier Urbanization, Poverty and Environmentin the 21st Century George Martine, Gordon McGranahan, Mark Montgomery and Rogelio Fernández-Castilla, IIED and UNFPA, Earthscan, UK, 2008
- 5. NolbertoMunier, Introduction to Sustainability: Road to a Better Future, Springer, 2006
- 6. Barry Dalal Clayton and Stephen Bass, Sustainable Development Strategies- a resource book", Earthscan Publications Ltd, London, 2002

	CO, PO Mapping									
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	-	2	1	3	-	-				
CO2	-	2	1	3	-	-				
CO3	-	2	1	3	-	_				
CO4	-	2	1	3	-	-				
CO5	-	2	1	3	-	-				
AVG	-	2	1	3	-	-				



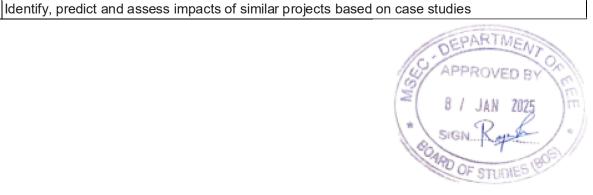


CO<sub>5</sub>

## Meenakshi Sundararajan Engineering College

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		W.E. Embedded System rechnologies						
P240N5	ENVIRONMENTAL IMPACT ASSESSMENT	L 3	T 0	P 0	C 3			
		Course Objectives	<u> </u>	U		<u> </u>		
	n overall	s to understand environmental clearance, its legal requirements and methodology of EIA, prediction tools and models, environmental n						
UNIT I INTR	ODUCTI	ON				9		
projectcycle.	legal anns of refe	nt of Environmental Impact Assessment (EIA). Environmental Clea d regulatory aspects in India – types and limitations of EIA –EIA pr erence in EIA- setting – analysis – mitigation. Cross sectoral issues ccreditation.	oces	ss-so	creeni			
UNIT II IMPA	ACT IND	ENTIFICATION AND PREDICTION			1	10		
prediction to	ols for El	<ul> <li>checklists – cost benefit analysis – analysis of alternatives – expending A – mathematical modeling for impact prediction – assessment of biological – cumulative impact assessment</li> </ul>						
UNIT III SOC	CIO-ECO	NOMIC IMPACT ASSESSMENT				8		
	arrangen	act assessment - relationship between social impacts and change in nents. factors and methodologies- individual and family level impac on						
UNIT IV EIA	DOCUM	IENTATION AND ENVIRONMENTAL MANAGEMENT PLAN				9		
plans - polic	y and gu	gement plan - preparation, implementation and review – mitigation idelines for planning and monitoring programmes – post project aucal and quality aspects of environmental impact assessment						
UNIT V CAS	E STUD	IES				9		
		, cement plants, highways, petroleum refining industry, storage & h , common hazardous waste facilities, CETPs, CMSWMF, building				on		
				TO	TAL	45		
		Course Outcomes						
		urse, the student will be able to						
		nd need for environmental clearance, its legal procedure, need of lestakeholders and their roles	ΞIA,					
		nd various impact identification methodologies, prediction techniquel of impacts on various environments	es					
	CO3 Understand relationship between social impacts and change in community due to development activities and rehabilitation methods							
( ( )/	Documer nonitorin	nt the EIA findings and prepare environmental management and g plan						





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	CO, PO Mapping									
CO / PO	PO1	PO2	PO3	PSO1	PSO2	PSO3				
CO1	-	-	2	2	-	-				
CO2	-	-	2	-	2	2				
CO3	-	-	2	-	2	-				
CO4	-	-	2	-	2	2				
CO5	-	-	2	-	-	-				
AVG	-	-	2	2	2	2				





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